

# Principles of Data Reduction

- \* In statistics we use a sample  $X_1, \dots, X_n$  to make inference about a parameter  $\theta$  through the use of a statistic  $T(\mathbf{X})$ .
- \* The aim of data reduction is to keep all of the relevant information in the sample through a smaller number of statistics.
- \* Any statistic  $T(\mathbf{X})$  defines a partition of the sample space into sets

$$A_t = \{\mathbf{x} : T(\mathbf{X}) = t\}$$

- \* Within such a partition we treat two samples,  $\mathbf{x}$  and  $\mathbf{y}$  as equal if  $T(\mathbf{x}) = T(\mathbf{y})$ .

## The Sufficiency Principle

- \* The sufficiency principle relies on the concept of a **sufficient statistic**.
- \* Such statistics are functions of the data which contain all of the information about the parameter of interest.

### Definition 9.1

A statistic  $T(x)$  is a **sufficient statistic for a parameter  $\theta$**  if the conditional distribution of the sample  $\mathbf{X}$  given the value of  $T(\mathbf{X})$  does not depend on  $\theta$ .

## The Sufficiency Principle

If  $T(\mathbf{X})$  is a sufficient statistic for  $\theta$  then any inference about  $\theta$  should depend on the sample  $\mathbf{X}$  only through the value of  $T(\mathbf{X})$ . If two sample points  $\mathbf{x}$  and  $\mathbf{y}$  have  $T(\mathbf{x}) = T(\mathbf{y})$  then inference about  $\theta$  should be the same whether  $\mathbf{X} = \mathbf{x}$  or  $\mathbf{X} = \mathbf{y}$ .

## Characterizing Sufficient Statistics

### Theorem 9.1

Let  $\mathbf{X}$  be a random vector with pdf or pmf  $f_{\mathbf{X}}(\mathbf{x} | \theta)$  and let  $T(\mathbf{X})$  be a statistic with pdf or pmf  $f_T(t | \theta)$ . Then  $T(\mathbf{X})$  is a sufficient statistic if, for every  $\mathbf{x}$  with  $f_{\mathbf{X}}(\mathbf{x} | \theta) > 0$ , the ratio

$$\frac{f_{\mathbf{X}}(\mathbf{x} | \theta)}{f_T(T(\mathbf{x}) | \theta)}$$

is constant as a function of  $\theta$ .

### Theorem 9.2 (Factorization Criterion)

Let  $f_{\mathbf{X}}(\mathbf{x} | \theta)$  be the joint pdf (pmf) of a sample  $\mathbf{X}$ . A statistic  $T(\mathbf{X})$  is a sufficient statistic for  $\theta$  if, and only if, there exist two non-negative functions  $g(t, \theta)$  and  $h(\mathbf{x})$  such that  $h(\mathbf{x})$  is free of  $\theta$  and for all sample points  $\mathbf{x}$

$$f_{\mathbf{X}}(\mathbf{x} | \theta) = g(T(\mathbf{x}), \theta)h(\mathbf{x}).$$

## Sufficient Statistics in the Exponential Family

### Theorem 9.3

If  $X_1, \dots, X_n$  is a random sample from a distribution having an exponential family form

$$f(x; \boldsymbol{\theta}) = h(x)c(\boldsymbol{\theta}) \exp \left\{ \sum_{j=1}^k w_j(\boldsymbol{\theta})t_j(x) \right\}$$

Then a sufficient statistic for  $\boldsymbol{\theta}$  is the vector

$$T(X_1, \dots, X_n) = \left\{ \sum_i t_1(x_i), \dots, \sum_i t_k(x_i) \right\}$$

## Multiple Sufficient Statistics

- \* In general, there are many sufficient statistics available for any model.
- \* Clearly any function of a sufficient statistic is also a sufficient statistic.
- \* The sample is a sufficient statistic (although it results in no data reduction).
- \* For *iid* data, the ordered sample is also a sufficient statistic.

## Minimal Sufficient Statistics

### Definition 9.2

A sufficient statistic  $T(\mathbf{X})$  is *minimal sufficient* if, and only if, for every other sufficient statistic  $T'(\mathbf{X})$ ,  $T(\mathbf{X})$  is a function of  $T'(\mathbf{X})$ .

- \* By saying that  $T(\mathbf{X})$  is a function of  $T'(\mathbf{X})$  we simply mean that if  $\mathbf{x}$  and  $\mathbf{y}$  are sample points such that  $T'(\mathbf{x}) = T'(\mathbf{y})$  then  $T(\mathbf{x}) = T(\mathbf{y})$ .

### Theorem 9.4

Let  $f(\mathbf{x} | \theta)$  be the pdf of a sample  $\mathbf{X}$  and suppose that there exists a function  $T(\mathbf{x})$  such that, for any two points  $\mathbf{x}$  and  $\mathbf{y}$ , the ratio  $f(\mathbf{x} | \theta)/f(\mathbf{y} | \theta)$  is constant in  $\theta$  if, and only if,  $T(\mathbf{x}) = T(\mathbf{y})$ . Then  $T(\mathbf{X})$  is a minimal sufficient statistic for  $\theta$ .

## Complete Families of Distributions

### Definition 9.3

Suppose  $f(t | \theta)$  is the family of distributions for a statistic  $T(\mathbf{X})$  indexed by the parameter  $\theta$ . This family of distributions is called *complete* if

$$E_{\theta}(g(T)) = 0 \implies P_{\theta}(g(T) = 0) = 1 \text{ for every } \theta.$$

- \* A statistic  $T(\mathbf{X})$  whose sampling distribution is from a complete family is often called a **complete statistic**.
- \* Unfortunately, it is often quite difficult to prove completeness.

### Theorem 9.5 (Bahadur's Theorem)

If a minimal sufficient statistic exists, then any complete statistic is also a minimal sufficient statistic.



## Complete Statistics in the Exponential Family

### Theorem 9.6

Suppose that  $X_1, \dots, X_n$  is a random sample from an exponential family with pdf or pmf given by

$$f(x | \boldsymbol{\theta}) = h(x)c(\boldsymbol{\theta}) \exp \left( \sum_{i=1}^k w_i(\boldsymbol{\theta})t_i(x) \right)$$

and further suppose that the set  $\{w_1(\boldsymbol{\theta}), \dots, w_k(\boldsymbol{\theta})\}$  contains an open subset in  $\mathbb{R}^k$ .

Then the statistic

$$T(X_1, \dots, X_n) = \left\{ \sum_i t_1(x_i), \dots, \sum_i t_k(x_i) \right\}$$

is complete and minimal sufficient.

## Ancillary Statistics

### Definition 9.4

Suppose that  $\mathbf{X}$  is a random sample from a distribution depending on a parameter  $\theta$ . A statistic  $S(\mathbf{X})$  is called an *ancillary statistic* if the sampling distribution of  $S(\mathbf{X})$  does not depend on  $\theta$ .

### Theorem 9.7 (Basu's Theorem)

If  $T(\mathbf{X})$  is a complete and minimal sufficient statistic then  $T(\mathbf{X})$  is independent of any ancillary statistic.

## Likelihood Principle

### Definition 9.5

Let  $\mathbf{X}$  be a random sample with joint pdf (or pmf)  $f(\mathbf{x} | \theta)$ . If  $\mathbf{x}$  is the observed value of  $\mathbf{X}$  then the *likelihood function* is the function of  $\theta$  given by

$$L(\theta | \mathbf{x}) = f(\mathbf{x} | \theta)$$

- \* We can use the likelihood to compare the probability of observing  $\mathbf{X} = \mathbf{x}$  under different parameter values.
- \* If  $L(\theta_1 | \mathbf{x}) > L(\theta_2 | \mathbf{x})$  then we may think of  $\theta_1$  as being more plausible than  $\theta_2$  given that we did actually observe  $\mathbf{X} = \mathbf{x}$ .

## The Likelihood Principle

*If  $x$  and  $y$  are two sample points such that*

$$L(\theta | x) = C(x, y)L(\theta | y)$$

*then the inference drawn from  $x$  should be identical to those drawn from  $y$ .*

- \* Note that if  $T(\mathbf{X})$  is a sufficient statistic and  $x$  and  $y$  are such that  $T(x) = T(y)$  then the sufficiency principle says that inference should be the same and so does the likelihood principle.