

Continuity equation.

Let \underline{F} represents the velocity field of a fluid at time t which now varies and let $\rho(x, y, z, t)$ be the mass density of the fluid at (x, y, z) and time t . Let P be a point in the fluid and let S be a small sphere centered at P . The total mass of the solid region V enclosed by S at time t is

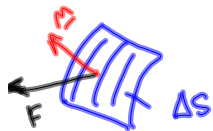
$$m = \iiint_V \rho(x, y, z, t) dx dy dz$$

∴ The rate of change of that mass with respect to time is thus

$$\frac{dm}{dt} = \iiint_V \frac{\partial \rho}{\partial t}(x, y, z, t) dt.$$

The volume of fluid flowing through an element of surface ΔS per unit of time is $\approx \underline{F} \cdot \underline{n} \text{ Area}(\Delta S)$

$$= \underline{F} \cdot \underline{n} dS \quad \text{area of } \Delta S$$



The mass of fluid flowing through ΔS per unit of time is $\approx \rho \underline{F} \cdot \underline{n} dS$

∴ The total mass of fluid flowing out of S per unit of time is then

$$\iint_S \rho \underline{F} \cdot \underline{n} dS = \iiint_V \nabla \cdot (\rho \underline{F}) dV$$

divergence theorem

$$= \frac{dm}{dt} = \iiint_V \frac{\partial \rho}{\partial t}(x, y, z, t) dV$$

Since the point P and the radius of the sphere are arbitrary, we conclude that

$$\boxed{\frac{\partial \rho}{\partial t} = \text{div}(\rho \underline{F})} \quad \text{Continuity Equation}$$

In particular, if $\rho = \text{constant}$ (fluid is incompressible)

$$\text{then } \frac{\partial \rho}{\partial t} = 0 = \text{div}(\rho \underline{F}) \Rightarrow$$

$$\boxed{\text{div}(\underline{F}) = 0}$$

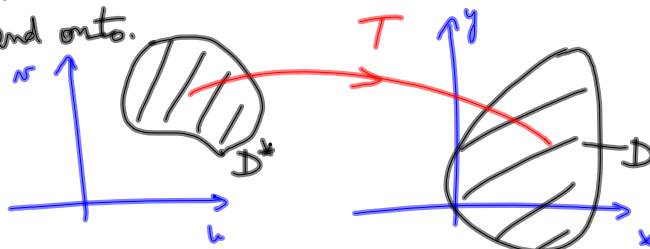
9.17 Change of Variables in Multiple Integrals

The dimensional Case

Suppose that the rectangular coordinates x, y are related to another coordinate system u, v by:

$$x = g_1(u, v), \quad y = g_2(u, v) \quad (1)$$

We denote by T the transformation from the u, v plane to the x, y plane defined by (1). We will assume that T is of class C^1 (which means that $g_1, g_2, \frac{\partial g_1}{\partial u}, \frac{\partial g_1}{\partial v}, \frac{\partial g_2}{\partial u}, \frac{\partial g_2}{\partial v}$ are continuous on the domain in which they are defined) and T maps the region D^* in the u, v plane to the region D in the x, y plane and that $T: D^* \rightarrow D$ is one-to-one and onto.



Def The Jacobian of the transformation T at the point (u, v) is defined by

$$\frac{\partial(x, y)}{\partial(u, v)} := \begin{vmatrix} \frac{\partial x}{\partial u} & \frac{\partial x}{\partial v} \\ \frac{\partial y}{\partial u} & \frac{\partial y}{\partial v} \end{vmatrix}$$

Theorem (Change of Variables formula)

If $f(x, y)$ is integrable on D ,

$$\iint_D f(x, y) dx dy = \iint_{D^*} f(x(u, v), y(u, v)) \left| \frac{\partial(x, y)}{\partial(u, v)} \right| du dv$$

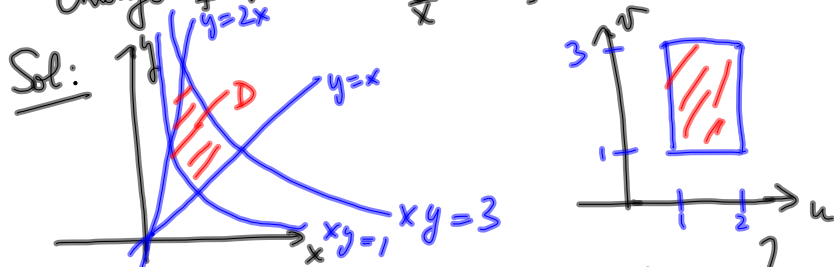
where $T: D^* \rightarrow D$ is 1-1, onto and of class C^1 .

Ex: Polar coordinates

$$\begin{cases} x = r \cos \theta \\ y = r \sin \theta \end{cases} \quad \frac{\partial(x, y)}{\partial(r, \theta)} = \begin{vmatrix} \frac{\partial x}{\partial r} & \frac{\partial x}{\partial \theta} \\ \frac{\partial y}{\partial r} & \frac{\partial y}{\partial \theta} \end{vmatrix} = \begin{vmatrix} \cos \theta & -r \sin \theta \\ \sin \theta & r \cos \theta \end{vmatrix} = r$$

$$\iint_D f(x, y) dx dy = \iint_{D^*} f(r \cos \theta, r \sin \theta) r dr d\theta$$

Ex: Evaluate $\iint_D x^3 y \, dx \, dy$, where D is the region in the 1st quadrant of the xy plane bounded by the lines $y=x$, $y=2x$ and by the hyperbolas $xy=1$ and $xy=3$, using the change of variables $\frac{y}{x} = u$, $xy = v$.



Note that $D = \left\{ (x, y), 1 \leq xy \leq 3, 1 \leq \frac{y}{x} \leq 2 \right\}$

$\therefore D^* = \left\{ (u, v), 1 \leq u \leq 2, 1 \leq v \leq 3 \right\}$

We need to express x, y in terms of u, v

$$uv = \frac{y}{x} \times y = y^2 \Rightarrow y = \sqrt{uv} = u^{1/2} v^{1/2}$$

$$x = \frac{v}{y} = u^{-1/2} v^{1/2}$$

$$\frac{\partial(x, y)}{\partial(u, v)} = \begin{vmatrix} \frac{\partial x}{\partial u} & \frac{\partial x}{\partial v} \\ \frac{\partial y}{\partial u} & \frac{\partial y}{\partial v} \end{vmatrix} = \begin{vmatrix} -\frac{1}{2} u^{-3/2} v^{1/2} & \frac{1}{2} u^{-1/2} v^{-1/2} \\ \frac{1}{2} u^{-1/2} v^{1/2} & \frac{1}{2} u^{1/2} v^{-1/2} \end{vmatrix}$$

$$= -\frac{1}{4} u^{-1} - \frac{1}{4} u^{-1} = -\frac{u^{-1}}{2}$$

Note: $\frac{\partial(x, y)}{\partial(u, v)} = \frac{1}{\frac{\partial(u, v)}{\partial(x, y)}}$ (check!)

$$\therefore \iint_D x^3 y \, dx \, dy = \iint_{D^*} u^{-3/2} v^{3/2} u^{1/2} v^{1/2} \left(\frac{u^{-1}}{2} \right) \, du \, dv$$

$$= \frac{1}{2} \iint_D u^{-2} v^2 \, du \, dv = \frac{1}{2} \int_1^2 u^{-2} \, du \int_1^3 v^2 \, dv$$

$$= \frac{1}{2} \left[-u^{-1} \right]_1^2 \left[\frac{v^3}{3} \right]_1^3$$

$$= \frac{1}{2} \left(1 - \frac{1}{2} \right) \left(9 - \frac{1}{3} \right) = \frac{1}{4} \frac{26}{3} = \frac{13}{6}$$

□