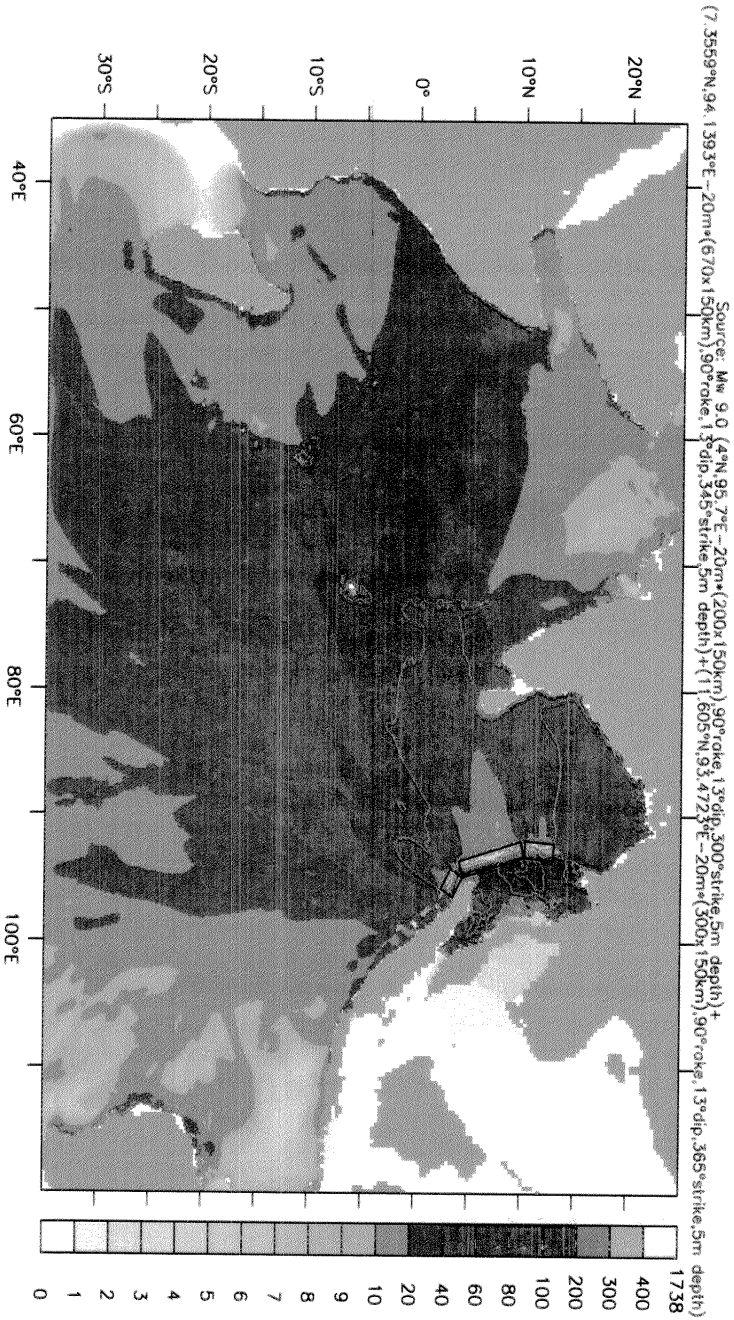


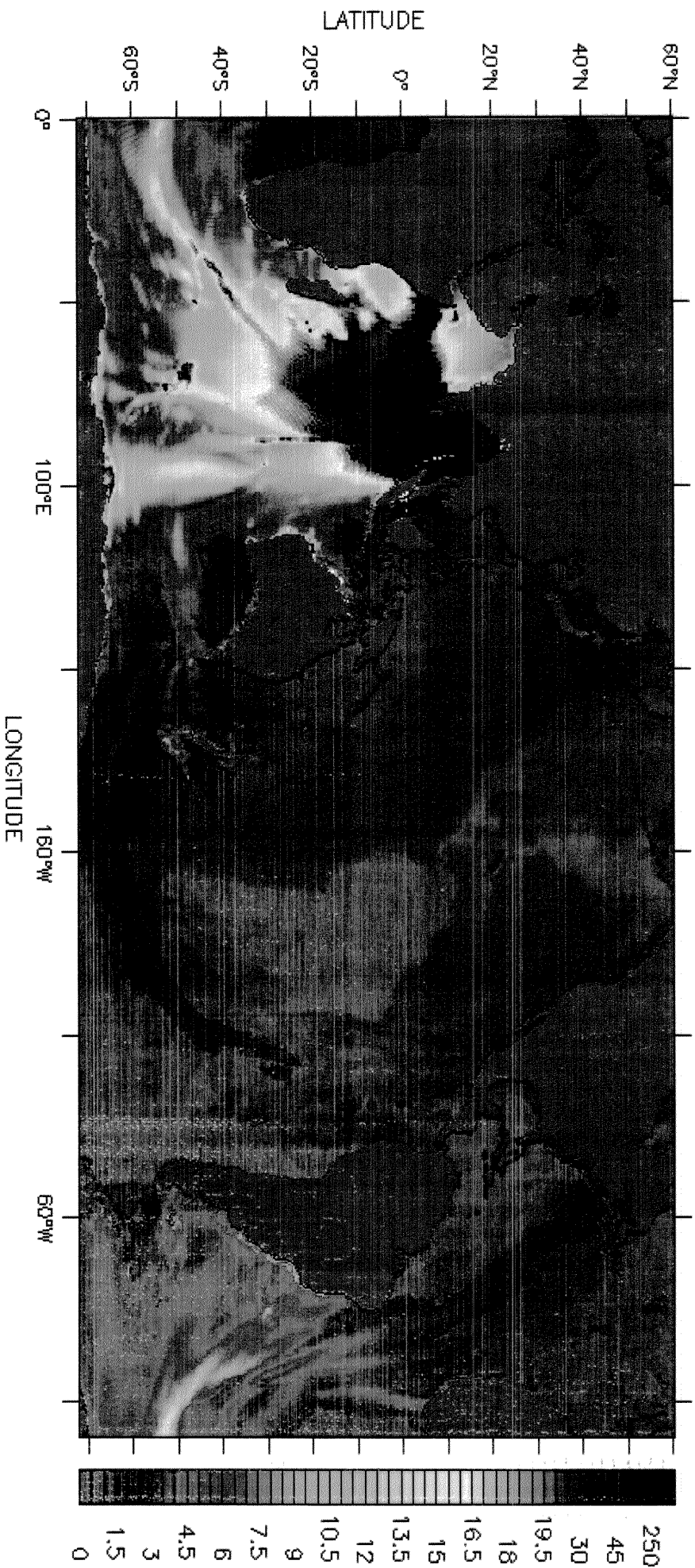
Facility for the Analysis and Comparison of Tsunami Simulations (FACTS)
 Maximum Wave Height(cm) – 2004.12.26 Indonesian Tsunami
 T (SECONDS) : –30 to 36030



T (SECONDS) : -120 to 240040 (maximum)

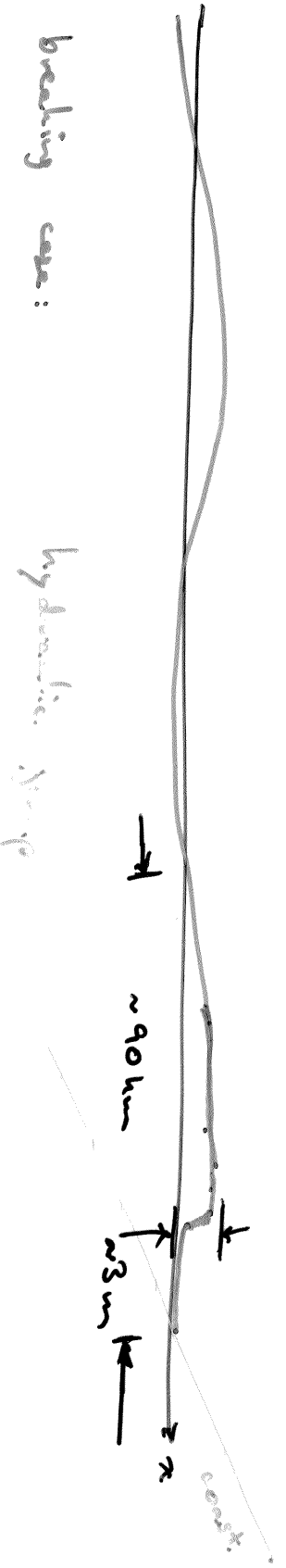
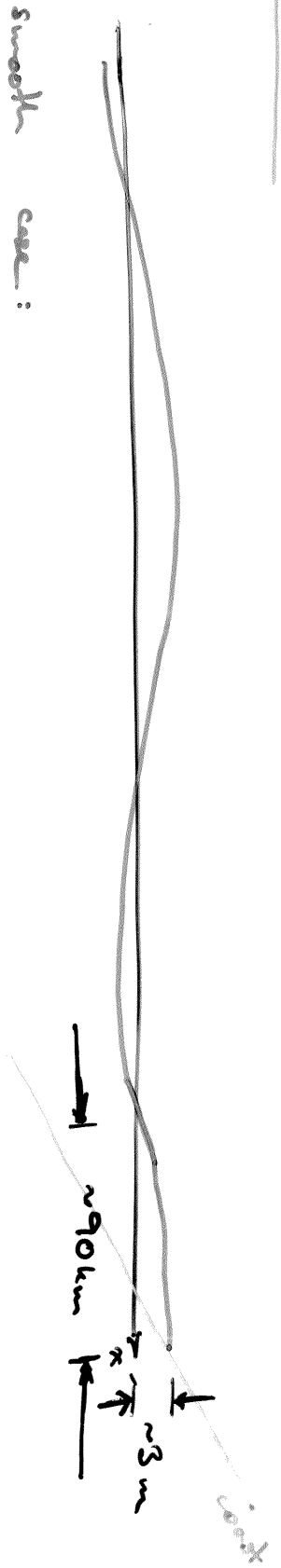
DATA SET: topo16_ha

PERPET Ver. 5.70
NOAA/PFEL/TMAP
Jan 4 2005 13:58:18



Wave Amplitude (CENTIMETERS)

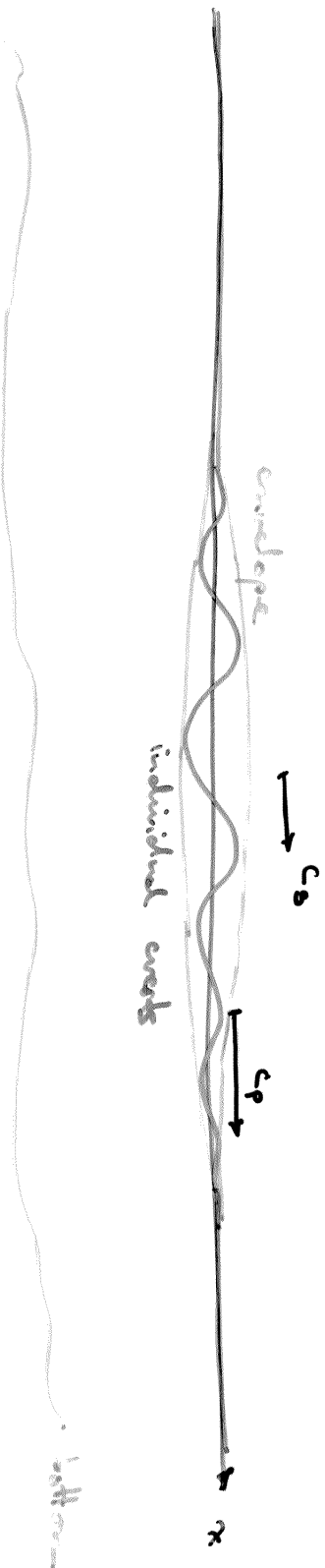
Speculation: interaction with shoreline



hydraulic jump

- smooth case: water level simply rises over 10 min to 2-3 meters higher than normal.
- breaking case: impact of a hydraulic jump (speed to 30 km/hr, side to breaking wave), returning water, or underflow very dangerous.
- backwash:

Furthermore, the tsunami travels as a wave packet:

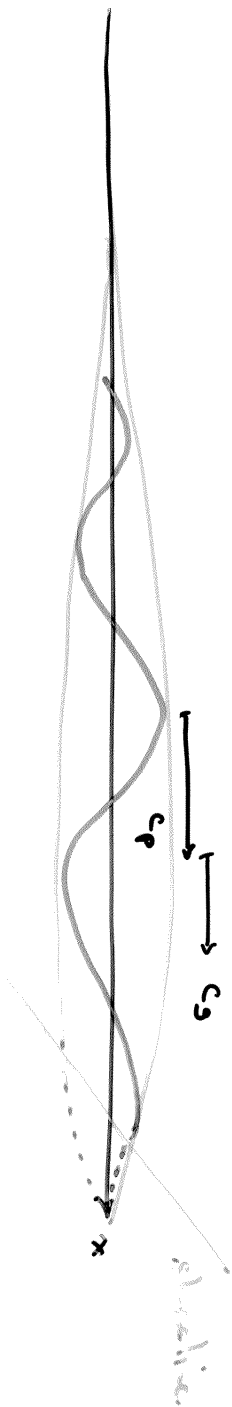


* Observers of the Dec 26, 2004 tsunami recall experiencing up to 7 crests, at roughly 15 minute intervals.

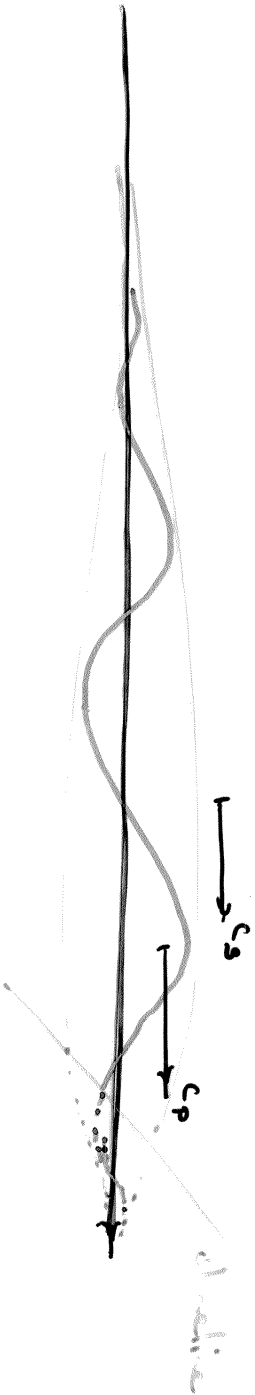
— In a wave packet, the first crest or first few crests will be smaller than later crests.

— When a wave packet impinges on the shoreline, the relative placement of the first significant oscillation determines whether the water level initially recedes, or rises.

18 km



case: water level initially rises



second case: water level initially recedes

14)

* Nonlinear equations of motion:

Euler's equations

$$(1) \quad \Delta \varphi = 0 \quad u = \nabla \varphi$$

$$\begin{cases} \partial_t \eta = \partial_y \varphi - \partial_x \eta \cdot \partial_x \varphi \\ \partial_t \varphi = -g\eta - \frac{1}{2} |\nabla \varphi|^2 \end{cases} \quad \text{or} \quad \{\eta = \eta(x, t)\}$$

In cases of a flat bottom at least:

Korteweg-deVries equations

$$(12) \quad \partial_t Q = \mp \left(\frac{1}{6} \partial_x^3 Q + \frac{3}{2} Q \partial_x Q \right)$$

nonlinear Schrödinger equation

$$(13) \quad \partial_t \Phi = - \frac{\partial_k^2 \omega(k_0)}{2} \partial_x^2 \Phi + \lambda |\Phi|^2 \Phi$$

All of these equations admit localized solutions.

$$(14) \quad \begin{aligned} \partial_t \eta &= -\partial_{x_1} \left((\bar{h}(x) + \varepsilon^2 (1 + \bar{c}_1) \eta) \partial_{x_1} \xi \right) \\ &\quad - \varepsilon^2 \partial_{x_1}^3 \left((\bar{c}_2 + \frac{1}{3} h^3 + \bar{c}_3) \partial_{x_1}^2 \xi \right) \\ &\quad - \varepsilon^2 \partial_{x_2} \left((h + \bar{c}_1) \partial_{x_2} \xi \right) \end{aligned}$$

$$\partial_t \xi = -g\eta - \frac{1}{2} \varepsilon^2 (1 + \bar{c}_1) (\partial_{x_1} \xi)^2$$

[Papoulis & Proakis 1983].
[WC, P. Guyenne, D. Nicholls & C. Sulem 2004]. Coeffs $\bar{c}_j(x)$ by homogenized

15)

* Hamiltonian systems of PDE

I want to base my derivation of these various equations of motion on Hamiltonian perturbation theory.

+ Euler equations [Zakharov, 1968]

$$H = \int \int_{-b(x)}^{\eta(x,t)} \frac{1}{2} |\nabla \varphi|^2 dy dx + \int_{\frac{a}{2}}^{\frac{b}{2}} \eta^2 dx$$

kinetic potential

variables, canonical coordinates

$$(\eta(x), \xi(x)) = \varphi(x, \eta(x))$$

$$(15) \quad H(\eta, \xi) = \int \frac{1}{2} \xi G(\eta, \xi) + \frac{g}{2} \eta^2 dx$$

Dirichlet-Neumann operator

$$\begin{aligned} \iint \frac{1}{2} |\nabla \varphi|^2 dy dx &= -\frac{1}{2} \iint \varphi \Delta \varphi dy dx \\ &+ \frac{1}{2} \int \varphi N \cdot \nabla \varphi dS_{\text{bottom}} \\ &+ \frac{1}{2} \int \varphi N \cdot \nabla \varphi dS_{\text{top}} \end{aligned}$$

Define the operator

$$\begin{aligned} \text{Dirichlet to Neumann} \xi(x) &\longmapsto \varphi(x, \eta) \text{ harmonic extension to } \{-b(x) < y < \eta\} \\ &\longmapsto N \cdot \nabla \varphi dS_{\text{top}} := \underline{G(\eta, \xi) dx} \end{aligned}$$

Theorem The Dirichlet-Neumann operator $G(\gamma)$

is:

(i) bounded $G(\gamma) : H^1 \rightarrow L^2$

(ii) positive (semi) definite $G(\gamma) \geq 0$

(iii) symmetric $G(\gamma)^T = G(\gamma)$

(iv) [Coifman & Roze, 1985] analytic in its dependence on $\gamma \in \text{Lip}$ (2-dim case)

[Christ & Tataru, 1997], [Coifman & Rochberg, 1991]
analytic in $\gamma \in C^1$ (n-dim case)

Taylor expansion:

$$G(\gamma) = G_0 + G_1(\gamma) + G_2(\gamma) + \dots \quad G_j(\alpha\gamma) = \alpha^j G_j(\gamma)$$

examples

$$G_0 = |D| \tanh(ch|D|) \quad D_j = \frac{i}{2} \partial_{x_j}$$

$$G_1(\gamma) = D \cdot \gamma D - G_0 \gamma G_0$$

$$G_2(\gamma) = \frac{i}{2} (|D|^2 \gamma^2 G_0 + G_0 \gamma^2 |D|^2 - 2 G_0 \gamma G_0 \gamma G_0)$$

(17)

* Transformation theory:

Zakharov's form for equations (1) are

$$(16) \quad \partial_t \eta = \delta_{\xi} H = \epsilon(\eta, \xi)$$

$$\partial_t \xi = -\delta_{\eta} H = -\epsilon(\eta, \xi) - \frac{1}{2} \delta_{\xi} \langle \xi, \epsilon(\eta, \xi) \rangle$$

This is in Hamiltonian form (Darboux coordinates).

$$(17) \quad \partial_t \begin{pmatrix} \eta \\ \xi \end{pmatrix} = J \begin{pmatrix} \partial_{\eta} H \\ \partial_{\xi} H \end{pmatrix} \quad J = \begin{pmatrix} 0 & I \\ -I & 0 \end{pmatrix}$$

Under transformation $w = f(\nu)$ with $\nu = \begin{pmatrix} \eta \\ \xi \end{pmatrix}$,
the canonical form (17) changes to

$$(18) \quad \partial_t w = (\partial_{\nu} f) J (\partial_{\nu} f)^T \delta_w K(w)$$

transformed Hamiltonian $H(w) = K(w)$.

Definition: The transformation $w = f(\nu)$ is canonical

$$\text{if} \quad (\partial_{\nu} f) J (\partial_{\nu} f)^T = J.$$

In general case, a new symplectic form $J_1 = (\partial_{\nu} f) J (\partial_{\nu} f)^T$

(18)

Hamiltonian perturbation theory: (KdV regime)

(1) amplitude scaling

$$\varepsilon^2 \eta' = \eta \quad \varepsilon \xi' = \xi \quad \mathcal{J}' = \varepsilon^3 \mathcal{J}$$

(2) spatial scaling

$$x \mapsto \varepsilon x = x' \quad \mathcal{J}'' = \varepsilon \mathcal{J}'$$

$$\mathcal{D} = \varepsilon \mathcal{D}'$$

Fourier multipliers transform

$$|\mathcal{D}| \tanh(k|\mathcal{D}|) \mapsto \varepsilon |\mathcal{D}'| \tanh(\varepsilon k |\mathcal{D}'|)$$

$$\sim \varepsilon^2 k |\mathcal{D}'|^2 - \frac{\varepsilon^4 k^3}{3} |\mathcal{D}'|^4 + \dots$$

(3) moving reference frame

$$v'(x, t) = v(x - \sqrt{g}h t, t)$$

add an integral of momentum to the Hamiltonian

$$H \mapsto H - \sqrt{g}h I$$

where the momentum is

$$I(\eta, \xi) = \int \xi \partial_x \eta \, dx$$

It is a conserved quantity

$$\{H, I\} = \int \delta_v H \mathcal{J} \delta_v I \, dx = 0$$

(4) characteristic coordinates

$$(1) (\eta, \xi) \mapsto (\eta, u = \partial_x \xi) \quad \mathcal{J}''' = \varepsilon^4 \begin{pmatrix} 0 & \partial_x \\ \partial_x & 0 \end{pmatrix}$$

$$(2) (\eta, u) \mapsto \begin{pmatrix} Q_+ \\ Q_- \end{pmatrix} = \begin{pmatrix} \sqrt{\frac{g}{4h}} \eta & \sqrt{\frac{g}{4h}} u \\ \sqrt{\frac{g}{4h}} \eta & -\sqrt{\frac{g}{4h}} u \end{pmatrix} \begin{pmatrix} \eta \\ u \end{pmatrix} \quad \mathcal{J}^{(4)} = \varepsilon^4 \begin{pmatrix} -\partial_x & 0 \\ 0 & \partial_x \end{pmatrix}$$

19) Applying the above transformation to the water wave Hamiltonian of Zakharov:

$$\begin{aligned}
 H \mapsto H_1 &= \frac{1}{2} \int \sqrt{gh} (Q_+^2 + Q_-^2) \varepsilon^2 dx \\
 &+ \frac{1}{2} \int -\frac{1}{6} \sqrt{gh}^{\frac{3}{2}} ((\partial_x Q_+)^2 - 2 \partial_x Q_+ \partial_x Q_- + (\partial_x Q_-)^2) \varepsilon^3 dx \\
 &+ \frac{1}{2} \int \frac{1}{2\sqrt{2}} (Q_+^3 - Q_+^2 Q_- - Q_+ Q_-^2 + Q_-^3) \varepsilon^3 dx \\
 &+ O(\varepsilon^4)
 \end{aligned}$$

In a neighborhood = H^m where $\|Q_\pm\|_{H^m} < O(\varepsilon^2)$

$$H_1 = \frac{\varepsilon^2}{2} \int \sqrt{gh} Q_+^2 - \frac{\varepsilon^3}{6} (\partial_x Q_+)^2 + c_2 Q_+^3 dx + O(\varepsilon^4)$$

$$I_1 = \varepsilon^2 \int Q_+^2 dx + O(\varepsilon^4)$$

This is the Hamiltonian for the KdV equation

$$\tau = \varepsilon^2 t$$

$$(19) \quad \partial_\tau Q_\pm = \mp \left(\frac{c_1}{6} \partial_x^3 Q_\pm + 6c_2 Q_\pm \partial_x Q_\pm \right)$$