

## Math 4A03: Practice problems on Multivariable Calculus

**Problem 1.** Consider the mapping  $\mathbf{f} = (u, v) : \mathbb{R}^2 \rightarrow \mathbb{R}^2$  defined by

$$\mathbf{f}(x, y) = (e^y + x, e^x - y) \quad (x, y) \in \mathbb{R}^2.$$

(a) Is it possible to express  $(x, y)$  as a differentiable function of  $(u, v)$  near the origin  $(x_0, y_0) = (0, 0)$ ?

(b) Compute  $\frac{\partial x}{\partial u}, \frac{\partial x}{\partial v}, \frac{\partial y}{\partial u}, \frac{\partial y}{\partial v}$  at  $(x, y) = (0, 0)$ , i.e. when  $(u, v) = (1, 1)$ .

**Problem 2.** Consider the mapping  $\mathbf{f} = (u, v) : \mathbb{R}^2 \rightarrow \mathbb{R}^2$  defined by

$$\mathbf{f}(x, y) = (x^2 - y^2, 2xy), \quad (x, y) \in \mathbb{R}^2.$$

(a) Show that the range of  $\mathbf{f}$  is  $\mathbb{R}^2$  and that if  $(u_0, v_0) \neq (0, 0)$ , there are exactly two points in  $\mathbb{R}^2$  that are mapped to  $(u_0, v_0)$  by  $\mathbf{f}$ .

(b) Show that the mapping  $\mathbf{f}$  is locally invertible at the point  $(x_0, y_0) = (1, 1)$ . Find an explicit formula for its local inverse  $\mathbf{g}(u, v)$  defined in a neighborhood of  $\mathbf{f}(1, 1) = (0, 2)$ .

**Problem 3.** Consider the system of equations

$$\begin{cases} wxyz = 0 \\ w^4 + x^4 + y^4 + z^4 = 18 \end{cases}$$

(a) Is it possible to express  $(x, y)$  as a differentiable function of  $(w, z)$  near the solution  $(w, x, y, z) = (-1, 0, 1, 2)$ ? (Use the implicit function theorem to answer this question.)

(b) If so, what are  $\frac{\partial x}{\partial w}(-1, 2)$  and  $\frac{\partial x}{\partial z}(-1, 2)$ ? (Use the implicit function theorem to answer this question.)

(c) Compute explicitly the differentiable function of  $(w, z)$  in part (a) and verify your answers in part (b) by a direct computation (i.e. without using the implicit function theorem).

**Problem 4.** Determine if the function  $f : \mathbb{R}^2 \rightarrow \mathbb{R}$  defined by

$$f(x, y) = \begin{cases} x + y, & x \neq y, \\ x^2 + x, & x = y \end{cases}$$

is differentiable at  $(0, 0)$  using the definition of differentiability.

**Solution.** We first compute the first-order partial derivatives at  $(0, 0)$ .

$$\frac{\partial f}{\partial x}(0, 0) = \lim_{h \rightarrow 0} \frac{f(h, 0) - f(0, 0)}{h} = \lim_{h \rightarrow 0} \frac{h}{h} = 1.$$

and

$$\frac{\partial f}{\partial y}(0, 0) = \lim_{h \rightarrow 0} \frac{f(0, h) - f(0, 0)}{h} = \lim_{h \rightarrow 0} \frac{h}{h} = 1.$$

We know that if  $f'(0, 0)$  exists then

$$f'(0, 0) = \begin{bmatrix} \frac{\partial f}{\partial x}(0, 0) & \frac{\partial f}{\partial y}(0, 0) \end{bmatrix} = [1 \ 1].$$

To see if  $f$  is differentiable at  $(0, 0)$ , we need to check if

$$\begin{aligned} & \frac{|f(h_1, h_2) - f(0, 0) - \frac{\partial f}{\partial x}(0, 0) h_1 - \frac{\partial f}{\partial y}(0, 0) h_2|}{\sqrt{h_1^2 + h_2^2}} \\ &= \frac{|f(h_1, h_2) - f(0, 0) - h_1 - h_2|}{\sqrt{h_1^2 + h_2^2}} \rightarrow 0, \end{aligned}$$

as  $(h_1, h_2) \rightarrow (0, 0)$ . If  $h_1 \neq h_2$ , we have  $f(h_1, h_2) = h_1 + h_2$  and since  $f(0, 0) = 0$ ,  $f(h_1, h_2) - f(0, 0) - h_1 - h_2 = 0$  so, clearly, the previous quotient goes to 0 if  $(h_1, h_2) \rightarrow (0, 0)$  with  $h_1 \neq h_2$ . On the other if  $h_1 = h_2$ , we have

$$\frac{|f(h_1, h_2) - f(0, 0) - h_1 - h_2|}{\sqrt{h_1^2 + h_2^2}} = \frac{|h_1^2 + h_1 - 2h_1|}{\sqrt{2h_1^2}} = \frac{|h_1 - 1|}{\sqrt{2}}$$

and this large expression does not converge to 0 as  $h_1 \rightarrow 0$ . Hence,  $f$  is not differentiable at  $(0, 0)$ .

**Problem 5.** Let  $E \subset \mathbb{R}^n$  be open and let  $f : E \rightarrow \mathbb{R}$  be a function having partial derivatives  $\frac{\partial f}{\partial x_j}$ ,  $j = 1, \dots, n$ , bounded on  $E$ . Prove that  $f$  is continuous on  $E$ .

**Hint:** Proceed as in the proof done in class that, if these partial derivatives are continuous on  $E$ , then  $f \in C^1(E)$ .

**Solution.** Let  $\mathbf{x} \in E$  and choose  $r > 0$  small enough so that

$$\{\mathbf{y} \in \mathbb{R}^n, \|\mathbf{x} - \mathbf{y}\| < r\} \subset E.$$

where  $\|\cdot\|$  denotes the usual euclidean norm on  $\mathbb{R}^n$ . let  $\mathbf{h} = \sum_{j=1}^n h_j \mathbf{e}_j$  with  $\|\mathbf{h}\| < r$  (where  $\mathbf{e}_1, \dots, \mathbf{e}_n$  is the standard orthonormal basis in  $\mathbb{R}^n$ ). Define  $\mathbf{v}_0 = \mathbf{0}$  and  $\mathbf{v}_k = \sum_{j=1}^k h_j \mathbf{e}_j$  for  $k = 1, \dots, n$ . We can thus write

$$f(\mathbf{x} + \mathbf{h}) - f(\mathbf{x}) = \sum_{j=1}^n [f(\mathbf{x} + \mathbf{v}_j) - f(\mathbf{x} + \mathbf{v}_{j-1})].$$

Define

$$g_j(t) = f(\mathbf{x} + \mathbf{v}_{j-1} + t(\mathbf{v}_j - \mathbf{v}_{j-1})) = f(\mathbf{x} + \mathbf{v}_{j-1} + t h_j \mathbf{e}_j), \quad 0 \leq t \leq 1,$$

for  $j = 1, \dots, n$ . Then,

$$g'_j(t) = \frac{\partial f}{\partial x_j}(\mathbf{x} + \mathbf{v}_{j-1} + t h_j \mathbf{e}_j) h_j.$$

By the mean value theorem, there exists  $\theta_j$  with  $0 < \theta_j < 1$  such that

$$g_j(1) - g_j(0) = g'_j(\theta_j),$$

or, equivalently,

$$f(\mathbf{x} + \mathbf{v}_j) - f(\mathbf{x} + \mathbf{v}_{j-1}) = \frac{\partial f}{\partial x_j}(\mathbf{x} + \mathbf{v}_{j-1} + \theta_j h_j \mathbf{e}_j) h_j.$$

Since all first-order partial derivatives are bounded by  $M$  on  $E$ , it follows that

$$|f(\mathbf{x} + \mathbf{v}_j) - f(\mathbf{x} + \mathbf{v}_{j-1})| = \left| \frac{\partial f}{\partial x_j}(\mathbf{x} + \mathbf{v}_{j-1} + \theta_j h_j \mathbf{e}_j) \right| |h_j| \leq M |h_j|.$$

This leads to

$$|f(\mathbf{x} + \mathbf{h}) - f(\mathbf{x})| \leq \sum_{j=1}^n |f(\mathbf{x} + \mathbf{v}_j) - f(\mathbf{x} + \mathbf{v}_{j-1})| \leq M \sum_{j=1}^n |h_j| \rightarrow 0,$$

as  $\|\mathbf{h}\| \rightarrow 0$ . This shows that

$$\lim_{\|\mathbf{h}\| \rightarrow 0} f(\mathbf{x} + \mathbf{h}) = f(\mathbf{x}),$$

which means that  $f$  is continuous at  $\mathbf{x}$ .

**Problem 6.** Let  $\mathbf{f} : \mathbf{R}^2 \rightarrow \mathbf{R}^2$  be the mapping defined by

$$\mathbf{f}(x, y) = (e^x \cos y, e^x \sin y), \quad (x, y) \in \mathbf{R}^2.$$

(a) What is the range of  $\mathbf{f}$ .

(b) Show that  $\mathbf{f}$  is locally one-to-one on  $\mathbf{R}^2$  (i.e. one-to-one on a neighborhood of every point  $(x_0, y_0) \in \mathbf{R}^2$ ), but not globally one-to-one (i.e. not one-to-one on  $\mathbf{R}^2$ ).

(c) Let  $\mathbf{g}$  be the continuous inverse of  $\mathbf{f}$  defined in a neighborhood of  $(\frac{1}{2}, \frac{\sqrt{3}}{2}) = \mathbf{f}(0, \frac{\pi}{3})$ . Find an explicit formula for  $\mathbf{g}$ . Compute  $\mathbf{f}'(0, \frac{\pi}{3})$  and  $\mathbf{g}'(\frac{1}{2}, \frac{\sqrt{3}}{2})$  and verify that

$$\mathbf{g}'\left(\frac{1}{2}, \frac{\sqrt{3}}{2}\right) = \left(\mathbf{f}'\left(0, \frac{\pi}{3}\right)\right)^{-1}.$$

(d) What are the images under  $\mathbf{f}$  of lines parallel to the coordinate axes?

**Solution.**

(a) Since any point  $(u, v) \in \mathbb{R}^2$  can be written in polar coordinate as  $(u, v) = (r \cos(y), r \sin(y))$  where  $r \geq 0$  and  $r = 0$  if and only  $(u, v) = (0, 0)$  while  $r = e^x$ , for some real  $x$  if and only if  $r > 0$  or  $(u, v) \neq (0, 0)$ , it follows that the range of  $f$  is the set  $\mathbb{R}^2 \setminus \{(0, 0)\}$ .

(b) If  $(x_0, y_0) \in \mathbb{R}^2$ , we have

$$\mathbf{f}'(x_0, y_0) = \begin{bmatrix} \frac{\partial f_1}{\partial x}(x_0, y_0) & \frac{\partial f_1}{\partial y}(x_0, y_0) \\ \frac{\partial f_2}{\partial x}(x_0, y_0) & \frac{\partial f_2}{\partial y}(x_0, y_0) \end{bmatrix} = \begin{bmatrix} e^{x_0} \cos(y_0) & -e^{x_0} \sin(y_0) \\ e^{x_0} \sin(y_0) & e^{x_0} \cos(y_0) \end{bmatrix}$$

Since  $\det(\mathbf{f}'(x_0, y_0)) = e^{2x_0}(\cos^2(x_0) + \sin^2(x_0)) = e^{2x_0} \neq 0$ , it follows that  $\mathbf{f}'(x_0, y_0)$  is invertible and the inverse function theorem shows that  $\mathbf{f}$  is one-to-one on a neighborhood of  $(x_0, y_0)$ . Nevertheless,  $\mathbf{f}$  is not one-to-one on  $\mathbb{R}^2$ , since

$$\begin{aligned} \mathbf{f}(x, y + 2\pi) &= (e^x \cos(y + 2\pi), e^x \sin(y + 2\pi)) \\ &= (e^x \cos(y), e^x \sin(y)) \\ &= \mathbf{f}(x, y). \end{aligned}$$

(c) Since  $\mathbf{f}(0, \frac{\pi}{3}) = (\frac{1}{2}, \frac{\sqrt{3}}{2})$ , we need to solve the system

$$\begin{cases} e^x \cos(y) = u \\ e^x \sin(y) = v \end{cases}$$

for  $(x, y)$  in term of  $(u, v)$ , for  $(u, v)$  close to  $(\frac{1}{2}, \frac{\sqrt{3}}{2})$ . Since  $u^2 + v^2 = e^{2x}$ , it follows that  $x = \ln(\sqrt{u^2 + v^2})$ . Since  $\tan(y) = \frac{v}{u}$ , we have  $y = \tan^{-1}(\frac{v}{u})$  (Note that  $\tan^{-1}(\frac{\sqrt{3}}{\frac{1}{2}}) = \tan^{-1}(\sqrt{3}) = \frac{\pi}{3}$ ). The inverse mapping  $\mathbf{g}$  is thus given by

$$\mathbf{g}(u, v) = \left( \ln(\sqrt{u^2 + v^2}), \tan^{-1}\left(\frac{v}{u}\right) \right).$$

Letting  $\mathbf{g} = (g_1, g_2)$ , we have

$$\mathbf{g}'(u_0, v_0) = \begin{bmatrix} \frac{\partial g_1}{\partial u}(u_0, v_0) & \frac{\partial g_1}{\partial v}(u_0, v_0) \\ \frac{\partial g_2}{\partial u}(u_0, v_0) & \frac{\partial g_2}{\partial v}(u_0, v_0) \end{bmatrix} = \begin{bmatrix} \frac{u}{u^2 + v^2} & \frac{v}{u^2 + v^2} \\ -\frac{v}{u^2 + v^2} & \frac{u}{u^2 + v^2} \end{bmatrix}$$

We have

$$\mathbf{f}'\left(0, \frac{\pi}{3}\right) = \begin{bmatrix} \frac{1}{2} & -\frac{\sqrt{3}}{2} \\ \frac{\sqrt{3}}{2} & \frac{1}{2} \end{bmatrix}, \quad \mathbf{g}'\left(\frac{1}{2}, \frac{\sqrt{3}}{2}\right) = \begin{bmatrix} \frac{1}{2} & \frac{\sqrt{3}}{2} \\ -\frac{\sqrt{3}}{2} & \frac{1}{2} \end{bmatrix}$$

and

$$\mathbf{f}'\left(0, \frac{\pi}{3}\right) \mathbf{g}'\left(\frac{1}{2}, \frac{\sqrt{3}}{2}\right) = \begin{bmatrix} \frac{1}{2} & -\frac{\sqrt{3}}{2} \\ \frac{\sqrt{3}}{2} & \frac{1}{2} \end{bmatrix} \begin{bmatrix} \frac{1}{2} & \frac{\sqrt{3}}{2} \\ -\frac{\sqrt{3}}{2} & \frac{1}{2} \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

which shows that

$$\mathbf{g}'\left(\frac{1}{2}, \frac{\sqrt{3}}{2}\right) = \left(\mathbf{f}'\left(0, \frac{\pi}{3}\right)\right)^{-1}.$$

(d) The line  $x = x_0$  has for image the circle of radius  $e^{x_0}$  centered at  $(0, 0)$  while the line  $y = y_0$  has for image a ray starting at the origin (but not including it) that makes an angle  $y_0$  with the positive  $x$ -axis.

**Problem 7.**

**Solution.**

**Problem 8.** Consider the mapping  $\mathbf{f} = (u, v) : \mathbb{R}^2 \rightarrow \mathbb{R}^2$  defined by

$$\mathbf{f}(x, y) = (x + y, 2xy), \quad (x, y) \in \mathbb{R}^2.$$

(a) Show that the range of  $\mathbf{f}$  is the set

$$L = \{(u, v) \in \mathbb{R}^2, u^2 - 2v \geq 0\}$$

**Hint:** Show first that  $\mathbf{f}$  maps  $\mathbb{R}^2$  into  $L$  and then that every point in  $L$  is the image under  $\mathbf{f}$  of some point in  $\mathbb{R}^2$ .

(b) (9 pts.) Show that the mapping  $\mathbf{f}$  is locally invertible at the point  $(x_0, y_0) = (2, -1)$ . Find an explicit formula for its local inverse  $\mathbf{g}(u, v)$  defined in a neighborhood of  $\mathbf{f}(2, -1) = (1, -4)$ .

(c) (5 pts.) Compute  $\mathbf{g}'(1, -4)$ .

**Solution.** (a) Let  $u = x + y$  and  $v = 2xy$ , then

$$u^2 - 2v = (x + y)^2 - 4xy = x^2 + 2xy + y^2 - 4xy = x^2 - 2xy + y^2 = (x - y)^2 \geq 0.$$

This shows that the range of  $\mathbf{f}$  is contained in  $L$ .

Now let  $(u, v)$  belong to  $L$ , so  $u^2 - 2v \geq 0$ .

If  $v = 0$ , we have  $\mathbf{f}(0, u) = (u, 0)$  (or  $\mathbf{f}(u, 0) = (u, 0)$ ) showing that  $(u, 0)$  belongs to the range of  $\mathbf{f}$  for any value of  $u$ .

If  $v \neq 0$  we have  $y = \frac{v}{2x}$  and  $u = x + \frac{v}{2x}$  or  $x^2 - ux + \frac{v}{2} = 0$ , so  $x = \frac{u \pm \sqrt{u^2 - 2v}}{2}$ . There are thus two points mapped to  $(u, v)$  by  $\mathbf{f}$ , namely

$$(x, y) = \left( \frac{u + \sqrt{u^2 - 2v}}{2}, \frac{v}{u + \sqrt{u^2 - 2v}} \right)$$

and

$$(x, y) = \left( \frac{u - \sqrt{u^2 - 2v}}{2}, \frac{v}{u - \sqrt{u^2 - 2v}} \right).$$

Thus  $(u, v)$  also belongs to the range of  $\mathbf{f}$  when  $(u, v) \in L$  and  $v \neq 0$ .

(b) We have

$$\mathbf{f}'(x, y) = \begin{bmatrix} \frac{\partial u}{\partial x} & \frac{\partial u}{\partial y} \\ \frac{\partial v}{\partial x} & \frac{\partial v}{\partial y} \end{bmatrix} = \begin{bmatrix} 1 & 1 \\ 2y & 2x \end{bmatrix}.$$

Since the first-order partial derivatives of  $u$  and  $v$  are continuous,  $\mathbf{f}$  belongs to  $\mathcal{C}^1(\mathbb{R}^2)$ . Since

$$\mathbf{f}'(2, -1) = \begin{bmatrix} 1 & 1 \\ -2 & 4 \end{bmatrix}$$

and

$$\begin{vmatrix} 1 & 1 \\ -2 & 4 \end{vmatrix} = 6 \neq 0,$$

the inverse mapping theorem shows that  $\mathbf{f}$  is locally invertible at the point  $(2, -1)$ . Using part (a), the local inverse is given by

$$\begin{aligned} \mathbf{g}(u, v) &= \left( \frac{u + \sqrt{u^2 - 2v}}{2}, \frac{v}{u + \sqrt{u^2 - 2v}} \right) \\ &= \left( \frac{u + \sqrt{u^2 - 2v}}{2}, \frac{u - \sqrt{u^2 - 2v}}{2} \right). \end{aligned}$$

(c)

$$\mathbf{g}'(1, -4) = (\mathbf{f}'(2, -1))^{-1} = \begin{bmatrix} \frac{2}{3} & -\frac{1}{6} \\ \frac{1}{3} & \frac{1}{6} \end{bmatrix}$$

Equivalently, we can use the explicit expression of  $\mathbf{g}$  to compute  $\mathbf{g}'$ . We have

$$\mathbf{g}'(u, v) = \begin{bmatrix} \frac{\partial x}{\partial u} & \frac{\partial x}{\partial v} \\ \frac{\partial y}{\partial u} & \frac{\partial y}{\partial v} \end{bmatrix} = \begin{bmatrix} \frac{1}{2} + \frac{u}{2\sqrt{u^2 - 2v}} & -\frac{1}{2\sqrt{u^2 - 2v}} \\ \frac{1}{2} - \frac{u}{2\sqrt{u^2 - 2v}} & \frac{1}{2\sqrt{u^2 - 2v}} \end{bmatrix}$$

and

$$\mathbf{g}'(1, -4) = \begin{bmatrix} \frac{2}{3} & -\frac{1}{6} \\ \frac{1}{3} & \frac{1}{6} \end{bmatrix}.$$

**Problem 9. (a)** Show that the system

$$\begin{cases} x^2 + y^2 - uv - 3 = 0 \\ xu + yv - 2 = 0 \end{cases}$$

can be solved for  $x, y$  in terms of  $u, v$  near the point  $(x, y, u, v) = (1, 0, 2, -1)$ .

**(b)** Compute the partial derivative

$$\frac{\partial x}{\partial u}(2, -1).$$

**Solution.** Let  $\mathbf{f}(x, y, u, v) = (f_1, f_2) = (x^2 + y^2 - uv - 3, xu + yv - 2)$ . Note that  $\mathbf{f}$  belongs to  $\mathcal{C}^1(\mathbb{R}^2)$  and

$$\mathbf{f}'(x, y, u, v) = \begin{bmatrix} \frac{\partial f_1}{\partial x} & \frac{\partial f_1}{\partial y} & \frac{\partial f_1}{\partial u} & \frac{\partial f_1}{\partial v} \\ \frac{\partial f_2}{\partial x} & \frac{\partial f_2}{\partial y} & \frac{\partial f_2}{\partial u} & \frac{\partial f_2}{\partial v} \end{bmatrix} = \begin{bmatrix} 2x & 2y & -v & -u \\ u & v & x & y \end{bmatrix}$$

For the system to be solvable for  $x, y$  in terms of  $u, v$ , we need to verify, according to the implicit function theorem, that the matrix

$$\begin{bmatrix} \frac{\partial f_1}{\partial x} & \frac{\partial f_1}{\partial y} \\ \frac{\partial f_2}{\partial x} & \frac{\partial f_2}{\partial y} \end{bmatrix}$$

evaluated at the point  $(x, y, u, v) = (1, 0, 2, -1)$  is invertible. This matrix is

$$\begin{bmatrix} 2x & 2y \\ u & v \end{bmatrix}_{(1,0,2,-1)} = \begin{bmatrix} 2 & 0 \\ 2 & -1 \end{bmatrix}$$

which has determinant  $-2 \neq 0$  and is thus invertible.

(b) Since

$$f_1(x(u, v), y(u, v), u, v) = 0,$$

we have

$$\frac{\partial f_1}{\partial x} \frac{\partial x}{\partial u} + \frac{\partial f_1}{\partial y} \frac{\partial y}{\partial u} + \frac{\partial f_1}{\partial u} = 0.$$

Similarly,

$$\frac{\partial f_2}{\partial x} \frac{\partial x}{\partial u} + \frac{\partial f_2}{\partial y} \frac{\partial y}{\partial u} + \frac{\partial f_2}{\partial u} = 0.$$

This can be written in matrix form as

$$\begin{bmatrix} \frac{\partial f_1}{\partial x} & \frac{\partial f_1}{\partial y} \\ \frac{\partial f_2}{\partial x} & \frac{\partial f_2}{\partial y} \end{bmatrix} \begin{bmatrix} \frac{\partial x}{\partial u} \\ \frac{\partial y}{\partial u} \end{bmatrix} = - \begin{bmatrix} \frac{\partial f_1}{\partial u} \\ \frac{\partial f_2}{\partial u} \end{bmatrix}$$

from which we deduce that

$$\begin{bmatrix} \frac{\partial x}{\partial u} \\ \frac{\partial y}{\partial u} \end{bmatrix} = - \begin{bmatrix} \frac{\partial f_1}{\partial x} & \frac{\partial f_1}{\partial y} \\ \frac{\partial f_2}{\partial x} & \frac{\partial f_2}{\partial y} \end{bmatrix}^{-1} \begin{bmatrix} \frac{\partial f_1}{\partial u} \\ \frac{\partial f_2}{\partial u} \end{bmatrix}$$

Evaluating the previous expression at the point  $(x, y, u, v) = (1, 0, 2, -1)$ , we obtain

$$\begin{bmatrix} \frac{\partial x}{\partial u} \\ \frac{\partial y}{\partial u} \end{bmatrix}_{(2,-1)} = - \begin{bmatrix} 2 & 0 \\ 2 & -1 \end{bmatrix}^{-1} \begin{bmatrix} 1 \\ 1 \end{bmatrix} = - \begin{bmatrix} \frac{1}{2} & 0 \\ 1 & -1 \end{bmatrix} \begin{bmatrix} 1 \\ 1 \end{bmatrix} = \begin{bmatrix} -\frac{1}{2} \\ 0 \end{bmatrix}$$

In particular,

$$\frac{\partial x}{\partial u}(2, -1) = -\frac{1}{2}.$$