

**Math 3C03**  
**Short Answers to Assignment #1**

# 1. The positive symmetric matrix  $R = A^T A = \begin{pmatrix} 882 & 504 & -558 \\ 504 & 936 & -504 \\ -558 & -504 & 882 \end{pmatrix}$

has eigenvalues  $\lambda_1 = 1944, \lambda_2 = 432, \lambda_3 = 324$  (in descending order) with corresponding unit eigenvectors:

$$u_1 = \frac{1}{\sqrt{3}}(1, 1, -1)^T \quad u_2 = \frac{1}{\sqrt{6}}(1, -2, -1)^T \quad u_3 = \frac{1}{\sqrt{2}}(1, 0, 1)^T$$

*You can do this “by hand” but it is less labour-intensive if you use Matlab to compute*

So  $R = U\Lambda U^T$  with  $U = (u_1, u_2, u_3)$  and  $\Lambda$  is the diagonal matrix with diagonal elements  $\lambda_1, \lambda_2, \lambda_3$ .

Similarly the positive symmetric matrix  $S = AA^T$  has the spectral decomposition:  $S = V\tilde{\Lambda}V^T$  with the same non-zero eigenvalues as  $R$ :  $\lambda_1 = 1944, \lambda_2 = 432, \lambda_3 = 324$  plus an additional zero eigenvalue  $\lambda_4 = 0$  with corresponding eigenvectors: (which are the columns of  $V$ ):

$$v_1 = \frac{1}{\sqrt{18}}(4, 1, 1, 0)^T \quad v_2 = \frac{1}{\sqrt{18}}(-1, 2, 2, -3)^T \quad v_3 = \frac{1}{\sqrt{2}}(0, -1, 1, 0)^T \quad v_4 = \frac{1}{\sqrt{18}}(-1, 2, 2, 3)^T$$

The SVD of  $A$  is therefore:

$$\begin{pmatrix} 22 & 28 & -22 \\ 1 & -2 & -19 \\ 19 & -2 & -1 \\ -6 & 12 & 6 \end{pmatrix} = \frac{1}{3\sqrt{2}} \begin{pmatrix} 4 & -1 & 0 & -1 \\ 1 & 2 & -3 & 2 \\ 1 & 2 & 3 & 2 \\ 0 & -3 & 0 & 3 \end{pmatrix} \begin{pmatrix} \sqrt{1944} & 0 & 0 \\ 0 & \sqrt{432} & 0 \\ 0 & 0 & \sqrt{324} \\ 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} \frac{1}{\sqrt{3}} & \frac{1}{\sqrt{6}} & \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{3}} & -\frac{2}{\sqrt{6}} & 0 \\ \frac{\sqrt{3}}{1} & -\frac{\sqrt{6}}{1} & \frac{1}{\sqrt{2}} \\ -\frac{1}{\sqrt{3}} & -\frac{1}{\sqrt{6}} & \frac{1}{\sqrt{2}} \end{pmatrix}$$

Let  $B = U\hat{\Lambda}V^T$ , where  $\hat{\Lambda} = \begin{pmatrix} \frac{1}{\sqrt{\lambda_1}} & 0 & 0 & 0 \\ 0 & \frac{1}{\sqrt{\lambda_2}} & 0 & 0 \\ 0 & 0 & \frac{1}{\sqrt{\lambda_3}} & 0 \end{pmatrix}$ .

The “best” solution (in the sense of minimising the squared length of the error) of  $Ax = b$  is given by  $x = Bb$ .  $B$  is known as the “pseudo-inverse” ( $B = \text{pinv}(A)$  in Matlab)

For  $b = (6, -39, 15, 18)^T$ , we get  $x = (1, 1, 2)^T$ , which is an exact solution.

For  $b = (9, -42, 15, 15)^T$ , we get  $x = \frac{1}{36}(40, 37, 74)$  with error vector  $(-1, 2, 2, 3)^T$ , so the residual (length of the error vector) is  $= \sqrt{18}$

# 2. From the given equations:  $-A\ddot{x} = Bx$ , with

$$A = \begin{pmatrix} m & 0 & 0 \\ 0 & M & 0 \\ 0 & 0 & m \end{pmatrix} \quad \text{and} \quad B = \begin{pmatrix} cm + d & -d & 0 \\ -d & cM + 2d & -d \\ 0 & -d & cm + d \end{pmatrix}$$

we solve for  $\omega^2$  in the characteristic equation:

$$|B - \omega^2 A| = \begin{vmatrix} cm + d - m\omega^2 & -d & 0 \\ -d & cM + 2d - M\omega^2 & -d \\ 0 & -d & cm + d - m\omega^2 \end{vmatrix} = 0$$

and obtain the three eigenvalues:

$$\omega_1^2 = c, \quad \omega_2^2 = c + \frac{d}{m}, \quad \omega_3^2 = c + \frac{d}{m} + \frac{2d}{M}$$

with corresponding eigenvectors (normal modes):

$$e_1 = (1, 1, 1)^T \quad e_2 = (1, 0, -1)^T \quad e_3 = \left(1, -\frac{2m}{M}, 1\right)^T$$

When  $d \rightarrow 0$ , the system decouples into three independent harmonic oscillators with the same frequency  $\sqrt{c}$ .

When  $d \rightarrow \infty$ , the system is rigidly coupled and only the first mode  $e_1$  with frequency  $\sqrt{c}$  survives.

$$\begin{aligned} \#3. \quad & \begin{vmatrix} x & a & b \\ x^2 & a^2 & b^2 \\ a+b & x+b & x+a \end{vmatrix} = \begin{vmatrix} x-a & a & b-a \\ x^2-a^2 & a^2 & b^2-a^2 \\ a-x & x+b & a-b \end{vmatrix} = (b-a)(x-a) \begin{vmatrix} 1 & a & 1 \\ x+a & a^2 & b+a \\ -1 & x+b & -1 \end{vmatrix} \\ & = (b-a)(x-a) \begin{vmatrix} 1 & a & 1 \\ x+a & a^2 & b+a \\ 0 & x+b+a & 0 \end{vmatrix} = (b-a)(x-a)(x-b)(x+a+b) \end{aligned}$$

# 4.  $\langle 1, 1 \rangle = \int_{-1}^1 1^2 dt = 2$ , so  $\mathbf{e}_0 = \frac{1}{\sqrt{2}}$ .

$\langle t, 1 \rangle = \int_{-1}^1 t dt = 0$  and  $\langle t, t \rangle = \int_{-1}^1 t^2 dt = \frac{2}{3}$ , so  $\mathbf{e}_1 = \sqrt{\frac{3}{2}} t$

$\langle t^2, \mathbf{e}_0 \rangle = \frac{1}{3}$ ,  $\langle t^2, \mathbf{e}_1 \rangle = 0$  and  $|t^2 - \frac{1}{3}|^2 = \int_{-1}^1 (t^4 - \frac{2}{3}t^2 + \frac{1}{9}) dt = \frac{8}{45}$  so  $\mathbf{e}_2 = \frac{3\sqrt{5}}{2\sqrt{2}} (t^2 - \frac{1}{3})$

$\langle t^3, 1 \rangle = 0$ ,  $\langle t^3, \mathbf{e}_1 \rangle = \frac{3}{5}t$ ,  $\langle t^3, t^2 - \frac{1}{3} \rangle = 0$  and  $|t^3 - \frac{3}{5}t|^2 = \int_{-1}^1 (t^6 - \frac{6}{5}t^4 + \frac{9}{25}t^2) dt = \frac{8}{175}$   
so  $\mathbf{e}_3 = \frac{5\sqrt{7}}{2\sqrt{2}} (t^3 - \frac{3}{5}t)$

Answer:  $\left\{ \frac{1}{\sqrt{2}}, \sqrt{\frac{3}{2}} t, \frac{3\sqrt{5}}{2\sqrt{2}} (t^2 - \frac{1}{3}), \frac{5\sqrt{7}}{2\sqrt{2}} (t^3 - \frac{3}{5}t) \right\}$

(up to normalisation these are the first four Legendre polynomials)

# 5. (in Matlab code)

$$A = [0.11 \ 0.19 \ 0.10; 0.49 \ -0.31 \ 0.21; 1.55 \ -0.70 \ 0.70];$$

$$B = [0.11 \ 0.19 \ 0.10; 0.49 \ -0.31 \ 0.21; 1.55 \ -0.70 \ 0.71];$$

$$e = [1 \ 1 \ 1]';$$

$$x = \text{inv}(A) * e;$$

$$y = \text{inv}(B) * e;$$

$$x = [-74.1651 \ -25.5413 \ 140.1101]'$$

$$y = [-142.5327 \ -50.5162 \ 262.7667]'$$

so the two solutions are quite different!

$$\det(A) = 0.0027, \det(B) = 0.0015 \text{ (relatively small)}$$

A and B are ill-conditioned matrices with condition numbers:

$$\text{cond}(A) = 342.1096 \text{ and } \text{cond}(B) = 644.6448 \text{ (pretty large)}$$

#6  $f(x) = x^3 - 4x$  for  $0 \leq x \leq 2$ , extended periodically as an odd function with period 4.

$$b_n = \int_0^{+2} (x^3 - 4x) \sin\left(\frac{1}{2}n\pi x\right) dx = (-1)^n \frac{96}{n^3\pi^3}$$

so by Parseval's identity

$$\frac{1}{2} \sum_{n=1}^{\infty} \frac{96^2}{n^6\pi^6} = \frac{1}{4} \int_{-2}^{+2} (x^3 - 4x)^2 dx = \frac{512}{105}$$

from which it follows that

$$\zeta(6) = \sum_{n=1}^{\infty} \frac{1}{n^6} = \frac{\pi^6}{945}$$

The approximation is already very good after summing up three terms of the Fourier series as you can see here:

