

1. pg 103, ex 3:

$$A = \begin{pmatrix} 0 & 0 & a \\ 0 & b & 0 \\ c & 0 & 0 \end{pmatrix} \rightarrow \text{real, complex, repeated eigenvalues?}$$

$$\det(A - \lambda I) = \begin{vmatrix} -\lambda & 0 & a \\ 0 & b-\lambda & 0 \\ c & 0 & -\lambda \end{vmatrix} = -\lambda \begin{vmatrix} b-\lambda & 0 \\ 0 & -\lambda \end{vmatrix} + a \begin{vmatrix} 0 & b-\lambda \\ c & 0 \end{vmatrix}$$

$$p(\lambda) = \lambda^2(b-\lambda) - ac(b-\lambda) = (\lambda^2 - ac)(b-\lambda) = 0$$

when $\lambda_1 = b$

$$\lambda^2 = ac \Rightarrow \lambda_{2,3} = \pm \sqrt{ac}$$

• Real eigenvalues

- ① $a > 0$ & $c > 0$
- ② $a < 0$ & $c < 0$
- ③ $a = 0$
- ④ $c = 0$

• Complex eigenvalues:

- ① $a > 0$ & $c < 0$
- ② $a < 0$ & $c > 0$

• Repeated eigenvalues:

- ① $a = 0$
- ② $c = 0$
- ③ $b = \sqrt{ac}$
- ④ $b = -\sqrt{ac}$

2. pg 103, ex 5: canonical form

$$a. A = \begin{pmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ 1 & 0 & 0 \end{pmatrix}$$

$$\det(A - \lambda I) = \begin{vmatrix} -\lambda & 0 & 1 \\ 0 & 1-\lambda & 0 \\ 1 & 0 & -\lambda \end{vmatrix} = -\lambda \begin{vmatrix} 1-\lambda & 0 \\ 0 & -\lambda \end{vmatrix} + \begin{vmatrix} 0 & 1-\lambda \\ 1 & 0 \end{vmatrix}$$

$$= \lambda^2(1-\lambda) - (1-\lambda) = (1-\lambda)(\lambda^2 - 1) = -(\lambda-1)^2(\lambda+1)$$

 $\Rightarrow \lambda_1 = 1, \lambda_2 = -1, \text{ where } \text{alg}(\lambda_1) = 2, \text{ alg}(\lambda_2) = 1$

for $\lambda_1 = 1$: $\begin{pmatrix} -1 & 0 & 1 & | & 0 \\ 0 & 0 & 0 & | & 0 \\ 1 & 0 & -1 & | & 0 \end{pmatrix} = \begin{pmatrix} 1 & 0 & -1 & | & 0 \\ 0 & 0 & 0 & | & 0 \\ 0 & 0 & 0 & | & 0 \end{pmatrix} \Rightarrow v_2, v_{31} \text{ are free variables}$

want $v_1 = \begin{pmatrix} v_{11} \\ v_{21} \\ v_{31} \end{pmatrix}$ $v_{11} = v_{31}$

Choose $v_{21} = v_{31} = 1$

Then $v_{11} = 1$

so we get two, linearly independent eigenvectors:

$$v_1 = \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix}$$

$$\& v_2 = \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}$$

Thus, the canonical form for this matrix is

$$J = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & -1 \end{pmatrix}$$

 $\Rightarrow \text{geom}(\lambda_1) = 2$
 $\& \text{ know } \text{geom}(\lambda_2) = 1$

$$d. \quad A = \begin{pmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 1 & 1 & 1 \end{pmatrix} \quad \det(A - \lambda I) = \begin{vmatrix} -\lambda & 1 & 0 \\ 1 & -\lambda & 0 \\ 1 & 1 & 1-\lambda \end{vmatrix} = (1-\lambda) \begin{vmatrix} -\lambda & 1 \\ 1 & -\lambda \end{vmatrix}$$

$$= (1-\lambda)(\lambda^2 - 1) = -(\lambda-1)^2(\lambda+1)$$

$\Rightarrow \lambda_1 = 1, \lambda_2 = -1$, where $\text{alg}(\lambda_1) = 2, \text{alg}(\lambda_2) = 1$

for $\lambda_1 = 1$:

$$\text{want } V_1 = \begin{pmatrix} v_{11} \\ v_{21} \\ v_{31} \end{pmatrix} \quad \left(\begin{array}{ccc|c} -1 & 1 & 0 & 0 \\ 1 & -1 & 0 & 0 \\ 1 & 1 & 0 & 0 \end{array} \right) = \left(\begin{array}{ccc|c} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right) \Rightarrow v_{11} = v_{21} = 0$$

v_{31} is a free variable
choose $v_{31} = 1$.

so we get one eigenvector $\Rightarrow \text{geom}(\lambda_1) = 1$.

& we know that $\text{geom}(\lambda_2) = 1$.

Thus, the canonical form for this matrix is $J = \begin{pmatrix} 1 & 1 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & -1 \end{pmatrix}$

$$g. \quad A = \begin{pmatrix} 1 & 0 & -1 \\ -1 & 1 & -1 \\ 0 & 0 & 1 \end{pmatrix} \quad \det(A - \lambda I) = \begin{vmatrix} 1-\lambda & 0 & -1 \\ -1 & 1-\lambda & -1 \\ 0 & 0 & 1-\lambda \end{vmatrix}$$

$$= (1-\lambda) \begin{vmatrix} 1-\lambda & 0 \\ -1 & 1-\lambda \end{vmatrix} = (1-\lambda)^3$$

$\Rightarrow \lambda_1 = 1$, where $\text{alg}(\lambda_1) = 3$.

for $\lambda_1 = 1$:

$$\text{want } V_1 = \begin{pmatrix} v_{11} \\ v_{21} \\ v_{31} \end{pmatrix} \quad \left(\begin{array}{ccc|c} 0 & 0 & -1 & 0 \\ -1 & 0 & -1 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right) = \left(\begin{array}{ccc|c} 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right) \Rightarrow v_{11} = 0$$

v_{21} & v_{31} are free variables.
choose $v_{21} = v_{31} = 1$.

so we get two, linearly independent eigenvectors: $\begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}$ & $\begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}$

$\Rightarrow \text{geom}(\lambda_1) = 2$.

Thus, the canonical form for this matrix is

$$J = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{pmatrix}$$

3. pg. 104, ex 6:

5x5 matrix with eigenvalues $\lambda_1=2$ & $\lambda_{2,3}=1\pm i \Rightarrow \text{alg}(\lambda_1) + \text{alg}(\lambda_2) + \text{alg}(\lambda_3) = 5$
 Possible canonical forms?

complex eigenvalues only come in conjugate pairs.

Case ① $\lambda_1=2$ is repeated with $\text{alg}(\lambda_1)=3$.

$$\left. \begin{array}{l} \lambda_2=1+i \\ \lambda_3=1-i \end{array} \right\} \begin{array}{l} \text{alg}(\lambda_2)=1 \\ \text{alg}(\lambda_3)=1 \end{array}$$

① $\text{geom}(\lambda_1)=3 \Rightarrow J = \begin{pmatrix} \boxed{2} & 0 & 0 & 0 & 0 \\ 0 & \boxed{2} & 0 & 0 & 0 \\ 0 & 0 & \boxed{2} & 0 & 0 \\ 0 & 0 & 0 & 1 & i \\ 0 & 0 & 0 & -1 & i \end{pmatrix}$

② $\text{geom}(\lambda_1)=1 \Rightarrow J = \begin{pmatrix} \boxed{2} & 1 & 0 & 0 & 0 \\ 0 & \boxed{2} & 1 & 0 & 0 \\ 0 & 0 & \boxed{2} & 0 & 0 \\ 0 & 0 & 0 & 1 & i \\ 0 & 0 & 0 & -1 & i \end{pmatrix}$

③ $\text{geom}(\lambda_1)=2 \Rightarrow J = \begin{pmatrix} \boxed{2} & 0 & 0 & 0 & 0 \\ 0 & \boxed{2} & 1 & 0 & 0 \\ 0 & 0 & \boxed{2} & 0 & 0 \\ 0 & 0 & 0 & 1 & i \\ 0 & 0 & 0 & -1 & i \end{pmatrix}$

* Jordan blocks indicated by green boxes.

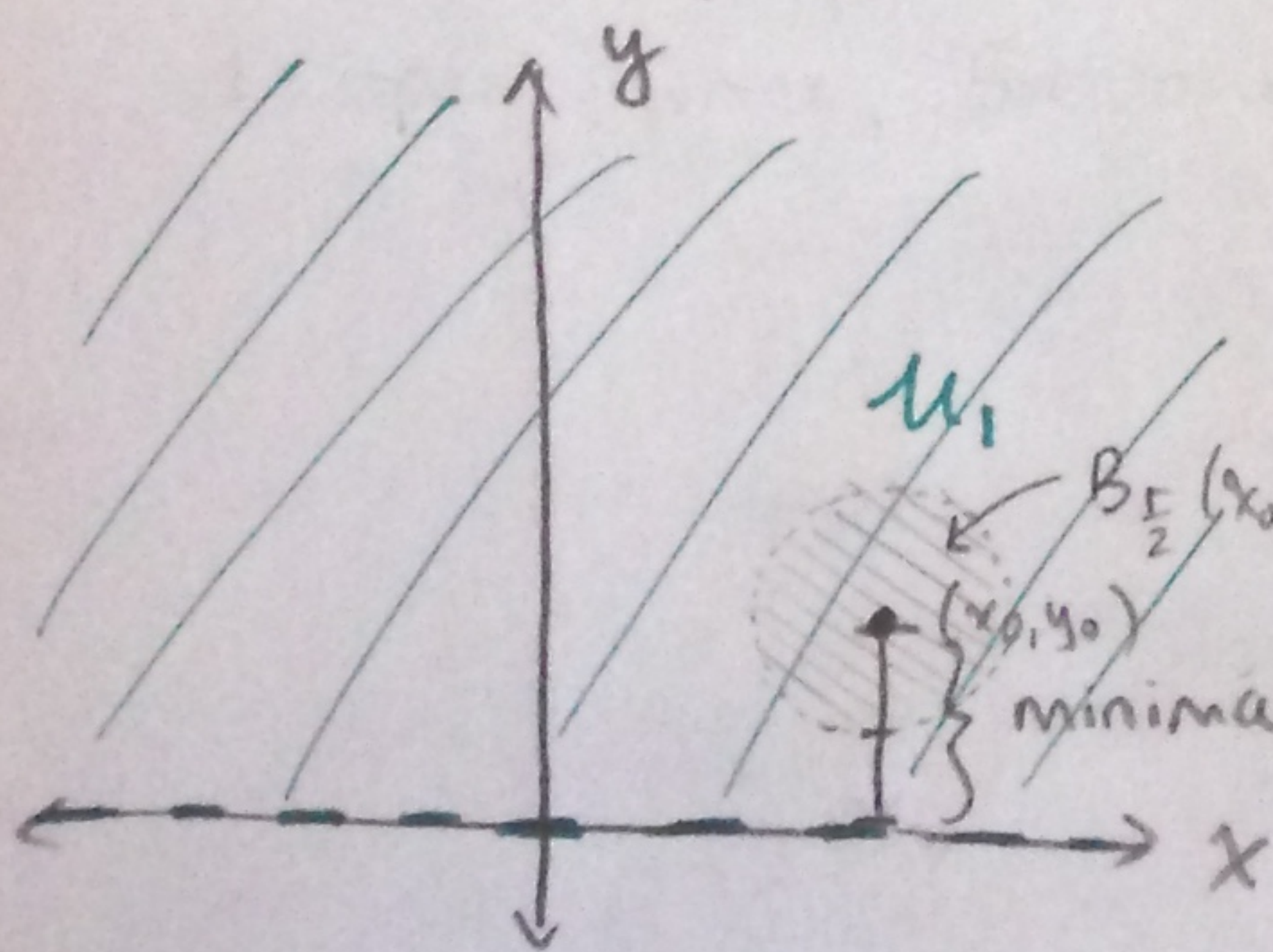
Case ② $\lambda_2=1+i$ & $\lambda_3=1-i$ are each repeated with $\text{alg}(\lambda_2)=\text{alg}(\lambda_3)=2$
 $\text{alg}(\lambda_1)=1$

① $\text{geom}(\lambda_2)=\text{geom}(\lambda_3)=2 \Rightarrow J = \begin{pmatrix} \boxed{2} & 0 & 0 & 0 & 0 \\ 0 & \boxed{1+i} & 1 & 0 & 0 \\ 0 & 0 & \boxed{1+i} & 0 & 0 \\ 0 & 0 & 0 & 1 & i \\ 0 & 0 & 0 & -1 & i \end{pmatrix}$

② $\text{geom}(\lambda_2)=\text{geom}(\lambda_3)=1 \Rightarrow J = \begin{pmatrix} \boxed{2} & 0 & 0 & 0 & 0 \\ 0 & \boxed{1+i} & 1 & 0 & 0 \\ 0 & 0 & \boxed{1+i} & 0 & 0 \\ 0 & 0 & 0 & 1 & i \\ 0 & 0 & 0 & -1 & i \end{pmatrix}$

4. pg. 104, ex. 13:

a. $U_1 = \{(x,y) | y > 0\}$



→ open, since for any point

$(x_0, y_0) \in U_1$, we can always find an open ball centred about (x_0, y_0) that is fully contained in U_1 (see diagram)

→ not dense, because a point in the set

minimal distance to boundary (call it r)

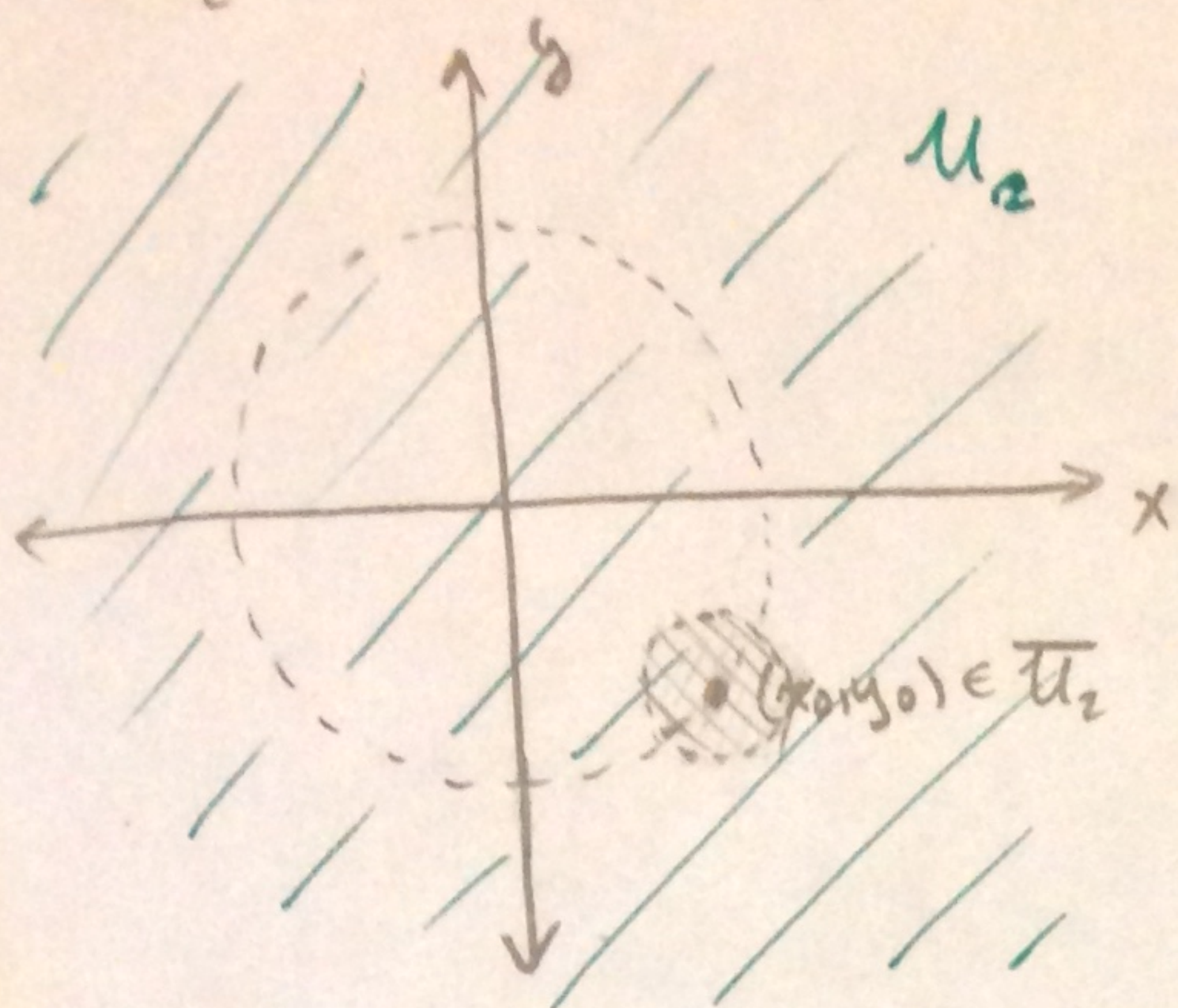
So take a ball of radius $\frac{r}{2}$ about (x_0, y_0)

$V_1 = \{(x,y) | y < 0\} \in \mathbb{R}^2$ is not arbitrarily close to U_1 (take $(x,y) = (0,-1)$... not true that every neighbourhood of $(0,-1)$ intersects U_1 → any ball of radius < 1 will not intersect)

"neighbourhood of (x_0, y_0) " = "open ball centred at (x_0, y_0) " in this context

b. $U_2 = \{(x,y) \mid x^2 + y^2 \neq 1\}$

→ open, again, because we can always find a neighbourhood around any point in U_2 , where the neighbourhood is fully contained in U_2 .



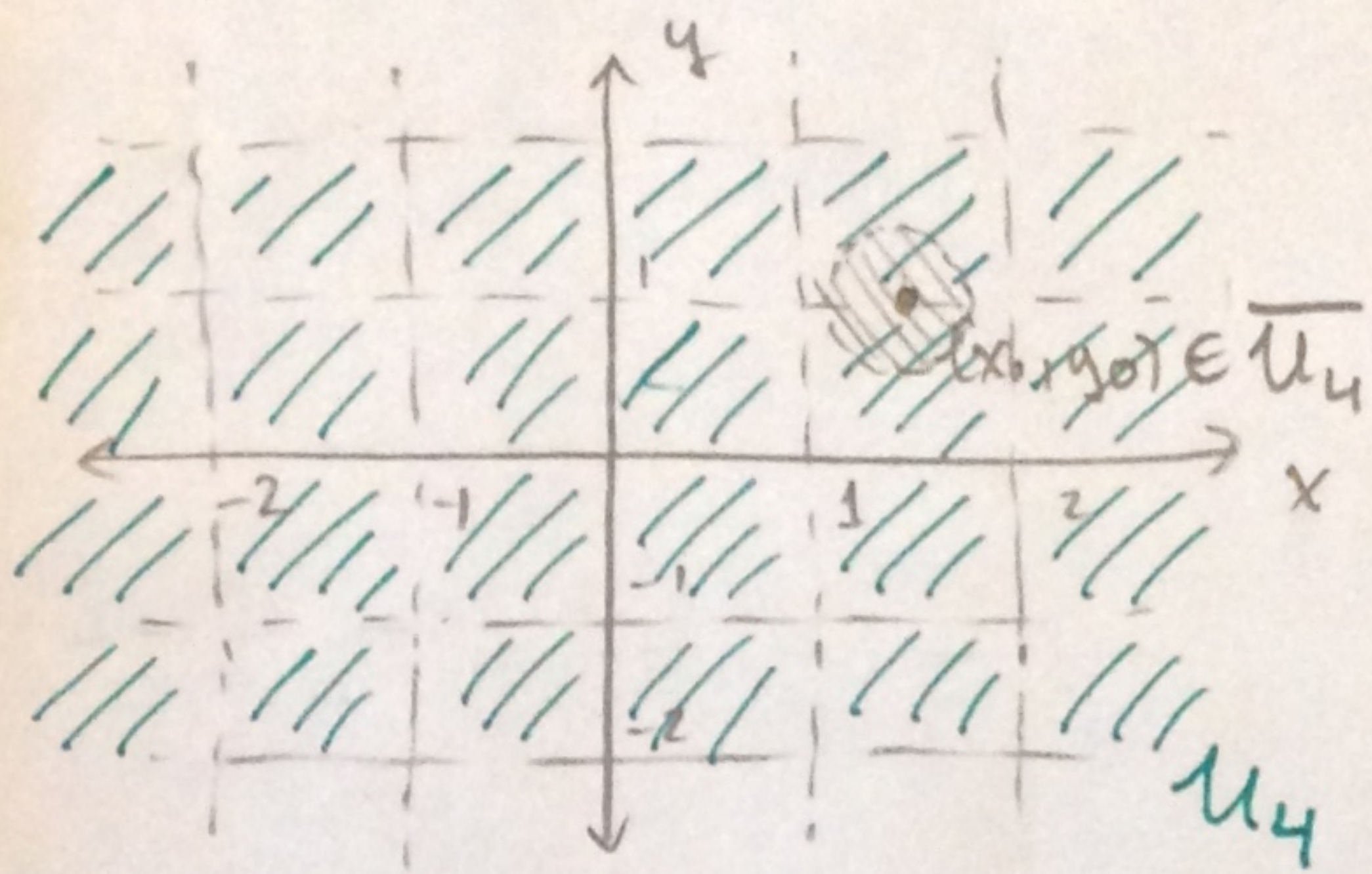
→ dense, because for any point in the complement of $U_2 = \{(x,y) \mid x^2 + y^2 = 1\}$, any neighbourhood of such a point intersects U_2 (see diagram)

c. $U_3 = \{(x,y) \mid x \text{ is irrational}\}$

→ not open, because any open ball about a point in the set will intersect the complement $\mathbb{R}^2 \setminus U_3$ (every open ball leaves the set).

→ dense, because for any point in the complement, $\mathbb{R}^2 \setminus U_3 = \{(x,y) \mid x \text{ is rational}\}$, an open ball about that point will contain points with a rational x -coordinate.

d. $U_4 = \{(x,y) \mid x \text{ and } y \text{ are not integers}\}$



→ open, because we can take any point in U_4 & find an open ball about that point fully contained in U_4

→ dense, because for any point in the complement $\overline{U_4} = \{(x,y) \mid x \text{ or } y \text{ is an integer}\}$, any open ball about such a point will always intersect U_4 (see diagram)

e. U_5 is the complement of a set C_1 where C_1 is closed & not dense.

→ open because, by definition, a closed set ^(like C_1) is one where its complement (i.e. U_5 in this case) is open.

→ Could either be dense or not... the fact that the complement C_1 is dense is not enough info.

↳ For instance, the complement of U_1 from part a is not dense, and neither is U_1 .

↳ However, the complement of U_2 from part b is not dense either, but U_2 is.

f. U_6 is the complement of a set C_2 that contains exactly 6 billion and 2 points.

If a subset of \mathbb{R}^2 contains a finite number of points (like C_2), then it must be a set of discrete points, for if it contains even one line (continuum), the set will contain infinitely many points.

Thus the complement of U_6 contains finitely many points, which means U_6 is open since, for any point in U_6 , we can always find an open set about this point that avoids the finitely many points in the complement C_2 small enough so

U_0 is also dense since any point in C_2 , (the complement), is a discrete (isolated) point, so any open ball about this point will have to intersect U_0 .

5. pg 135, ex 1:

a. $A = \begin{pmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ 1 & 0 & 0 \end{pmatrix}$ → From question 2 of this assignment, we know that A has eigenvalues $\lambda_1 = 1, \lambda_2 = -1$ & λ_1 has corresponding eigenvectors $v_1 = \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix}$ & $v_2 = \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}$

For $\lambda_2 = -1$:

want $v_3 = \begin{pmatrix} v_{13} \\ v_{23} \\ v_{33} \end{pmatrix} : \begin{pmatrix} 1 & 0 & 1 & | & 0 \\ 0 & 2 & 0 & | & 0 \\ 1 & 0 & 1 & | & 0 \end{pmatrix} = \begin{pmatrix} 1 & 0 & 1 & | & 0 \\ 0 & 1 & 0 & | & 0 \\ 0 & 0 & 0 & | & 0 \end{pmatrix} \Rightarrow v_{23} = 0$
 $v_{13} = -v_{33}$
 where v_{33} is a free variable.
 Choose $v_{33} = -1 \Rightarrow v_{13} = 1$.

so $v_3 = \begin{pmatrix} 1 \\ 0 \\ -1 \end{pmatrix}$

so the matrix $T = \begin{pmatrix} 1 & 0 & 1 \\ 0 & 1 & 0 \\ 1 & 0 & -1 \end{pmatrix}$ puts the matrix A into the canonical form $J = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & -1 \end{pmatrix}$ by the relation $A = T J T^{-1}$

we can compute that $T^{-1} = \begin{pmatrix} \frac{1}{2} & 0 & \frac{1}{2} \\ 0 & 1 & 0 \\ \frac{1}{2} & 0 & -\frac{1}{2} \end{pmatrix}$

The general solution to $\underline{x}' = A \underline{x}$ is given by $\underline{x}(t) = e^{tA} \underline{x}_0$.

$\underline{x}(t) = e^{tA} \underline{x}_0 = e^{t(TJT^{-1})} \underline{x}_0 = T e^{tJ} T^{-1} \underline{x}_0 = \begin{pmatrix} 1 & 0 & 1 \\ 0 & 1 & 0 \\ 1 & 0 & -1 \end{pmatrix} \begin{pmatrix} e^t & 0 & 0 \\ 0 & e^t & 0 \\ 0 & 0 & e^{-t} \end{pmatrix} \begin{pmatrix} \frac{1}{2} & 0 & \frac{1}{2} \\ 0 & 1 & 0 \\ \frac{1}{2} & 0 & -\frac{1}{2} \end{pmatrix} \begin{pmatrix} x_0 \\ y_0 \\ z_0 \end{pmatrix}$

which you can multiply out...

c. $A = \begin{pmatrix} 0 & 1 & 0 \\ -1 & 0 & 0 \\ 1 & 1 & 1 \end{pmatrix}$ → eigenvalues: $\lambda_1 = 1, \lambda_{2,3} = \pm i$
 → eigenvectors: $v_1 = \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}, v_2 = \begin{pmatrix} i \\ -1 \\ 1 \end{pmatrix}, v_3 = \begin{pmatrix} -i \\ -1 \\ 1 \end{pmatrix}$

→ canonical form:

$J = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & -1 & 0 \end{pmatrix}, e^{tJ} = \begin{pmatrix} e^t & 0 & 0 \\ 0 & 1 & \sin(t) \\ 0 & -\sin(t) & 1 \end{pmatrix}$

$\text{Re}(v_2) = \begin{pmatrix} 0 \\ -1 \\ 1 \end{pmatrix}, \text{Im}(v_2) = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}$

→ transformation matrix:

$T = \begin{pmatrix} 0 & 0 & 1 \\ 0 & -1 & 0 \\ 1 & 1 & 0 \end{pmatrix}, T^{-1} = \begin{pmatrix} 0 & 1 & 1 \\ 0 & -1 & 0 \\ 1 & 0 & 0 \end{pmatrix}$

→ general solution:

$\underline{x}(t) = \begin{pmatrix} 0 & 0 & 1 \\ 0 & -1 & 0 \\ 1 & 1 & 0 \end{pmatrix} \begin{pmatrix} e^t & 0 & 0 \\ 0 & 1 & \sin(t) \\ 0 & -\sin(t) & 1 \end{pmatrix} \begin{pmatrix} 0 & 1 & 1 \\ 0 & -1 & 0 \\ 1 & 0 & 0 \end{pmatrix} \begin{pmatrix} x_0 \\ y_0 \\ z_0 \end{pmatrix}$

$$h. A = \begin{pmatrix} 1 & 0 & 0 & 1 \\ 0 & 1 & 1 & 0 \\ 0 & 0 & 1 & 0 \\ 1 & 0 & 0 & 0 \end{pmatrix} \rightarrow \text{eigenvalues: } \lambda_1 = 1, \lambda_{2,3} = \frac{1 \pm \sqrt{5}}{2}$$

$$\rightarrow \text{eigenvectors: } v_1 = \begin{pmatrix} 0 \\ 1 \\ 0 \\ 0 \end{pmatrix}, v_2 = \begin{pmatrix} 1 \\ 0 \\ 0 \\ -\sqrt{5}/2 \end{pmatrix}, v_3 = \begin{pmatrix} 1 \\ 0 \\ 0 \\ \sqrt{5}/2 \end{pmatrix}$$

$$\rightarrow \text{generalized eigenvector: } u_1 = \begin{pmatrix} 0 \\ 0 \\ 1 \\ 0 \end{pmatrix}$$

\rightarrow canonical form:

$$J = \begin{pmatrix} 1 & 1 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & \frac{1+\sqrt{5}}{2} & 0 \\ 0 & 0 & 0 & \frac{1-\sqrt{5}}{2} \end{pmatrix} \quad e^{tJ} = \begin{pmatrix} e^t & t & 0 & 0 \\ 0 & e^t & 0 & 0 \\ 0 & 0 & e^{\frac{1+\sqrt{5}}{2}t} & 0 \\ 0 & 0 & 0 & e^{\frac{1-\sqrt{5}}{2}t} \end{pmatrix}$$

\rightarrow transformation matrix:

$$T = \begin{pmatrix} 0 & 0 & 1 & 1 \\ 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & -\frac{\sqrt{5}}{2} & \frac{\sqrt{5}}{2} \end{pmatrix}, \quad T^{-1} = \begin{pmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 1 & 0 & 0 & 0 \\ \frac{1}{2} & 0 & 0 & \frac{1}{\sqrt{5}} \end{pmatrix}$$

\rightarrow general solution:

$$X(t) = \begin{pmatrix} 0 & 0 & 1 & 1 \\ 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & -\frac{\sqrt{5}}{2} & \frac{\sqrt{5}}{2} \end{pmatrix} \begin{pmatrix} e^t & t & 0 & 0 \\ 0 & e^t & 0 & 0 \\ 0 & 0 & e^{\frac{1+\sqrt{5}}{2}t} & 0 \\ 0 & 0 & 0 & e^{\frac{1-\sqrt{5}}{2}t} \end{pmatrix} \begin{pmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 1 & 0 & 0 & 0 \\ \frac{1}{2} & 0 & 0 & \frac{1}{\sqrt{5}} \end{pmatrix} \begin{pmatrix} x_0 \\ y_0 \\ z_0 \\ u_0 \end{pmatrix}$$

7. pg 137, ex 12

a. $A = \begin{pmatrix} 5 & -6 \\ 3 & -4 \end{pmatrix} \rightarrow$ eigenvalues: $\lambda_1 = -1, \lambda_2 = 2$
 \rightarrow eigenvectors: $V_1 = \begin{pmatrix} 1 \\ 1 \end{pmatrix}, V_2 = \begin{pmatrix} 2 \\ 1 \end{pmatrix}$

\rightarrow canonical form: $J = \begin{pmatrix} -1 & 0 \\ 0 & 2 \end{pmatrix}$

\rightarrow transformation matrix: $T = \begin{pmatrix} 1 & 2 \\ 1 & 1 \end{pmatrix}, T^{-1} = \begin{pmatrix} -1 & 2 \\ 0 & -1 \end{pmatrix}$

\rightarrow matrix exponential:

$$e^A = e^{TJT^{-1}} = Te^JT^{-1} = \begin{pmatrix} 1 & 2 \\ 1 & 1 \end{pmatrix} \begin{pmatrix} e^{-1} & 0 \\ 0 & e^2 \end{pmatrix} \begin{pmatrix} -1 & 2 \\ 0 & -1 \end{pmatrix}$$

which you can multiply out...

f. $A = \begin{pmatrix} 2 & 0 & 0 \\ 0 & 3 & 0 \\ 0 & 1 & 3 \end{pmatrix} = \underbrace{\begin{pmatrix} 2 & 0 & 0 \\ 0 & 3 & 0 \\ 0 & 0 & 3 \end{pmatrix}}_D + \underbrace{\begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 1 & 0 \end{pmatrix}}_N$

Note that $DN = ND$, so

$$e^A = e^{D+N} = e^D e^N$$

Moreover, $N^2 = 0$, so $e^A = e^D e^N = \begin{pmatrix} e^2 & 0 & 0 \\ 0 & e^3 & 0 \\ 0 & 0 & e^3 \end{pmatrix} \cdot \sum_{k=0}^1 \frac{N^k}{k!}$

$$= \begin{pmatrix} e^2 & 0 & 0 \\ 0 & e^3 & 0 \\ 0 & 0 & e^3 \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 1 & 1 \end{pmatrix} = \begin{pmatrix} e^2 & 0 & 0 \\ 0 & e^3 & 0 \\ 0 & e^3 & e^3 \end{pmatrix}$$

i. $A = \begin{pmatrix} 1+i & 0 \\ 2 & 1+i \end{pmatrix} = \underbrace{\begin{pmatrix} 1 & 0 \\ 2 & 1 \end{pmatrix}}_R + i \underbrace{\begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}}_I$

Note that $RI = IR$, so

$$e^A = e^{R+iI} = e^R \cdot e^{iI}$$

First consider $R = \begin{pmatrix} 1 & 0 \\ 2 & 1 \end{pmatrix} = \underbrace{\begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}}_I + \underbrace{\begin{pmatrix} 0 & 0 \\ 2 & 0 \end{pmatrix}}_N$ } Again, $IN = NI$
 & so $e^R = e^I e^N$

Now, $N^2 = 0$, so $e^N = \sum_{k=0}^1 \frac{N^k}{k!} = I + N = \begin{pmatrix} 1 & 0 \\ 2 & 1 \end{pmatrix}$

& so $e^R = e^I e^N = \begin{pmatrix} e & 0 \\ 0 & e \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 2 & 1 \end{pmatrix} = \begin{pmatrix} e & 0 \\ 2e & e \end{pmatrix}$

Also, $e^{iI} = \begin{pmatrix} e^i & 0 \\ 0 & e^i \end{pmatrix}$, so $e^A = e^R e^{iI} = \begin{pmatrix} e & 0 \\ 2e & e \end{pmatrix} \begin{pmatrix} e^i & 0 \\ 0 & e^i \end{pmatrix} = \begin{pmatrix} e^{1+i} & 0 \\ 2e^{1+i} & e^{1+i} \end{pmatrix}$

8. pg. 138, ex 14:

Suppose $AB = BA$.

a. Want to show that $e^A e^B = e^B e^A$ since matrix addition is commutative.
 start with $e^A e^B = \underbrace{e^{A+B}}_{\text{since } AB=BA} = \underbrace{e^{B+A}}_{\text{again, since } AB=BA} = e^B e^A \rightarrow \text{done!}$

b. Want to show that $e^A B = B e^A$
 start with $e^A B = \left(\sum_{k=0}^{\infty} \frac{A^k}{k!} \right) B = \sum_{k=0}^{\infty} \frac{A^k B}{k!} = \sum_{k=0}^{\infty} \frac{\overbrace{(A \cdot A \cdots A)}^{k\text{-times}} B}{k!} = \sum_{k=0}^{\infty} \frac{B \overbrace{(A \cdot A \cdots A)}^{k\text{-times}}}{k!}$
 since B does not depend on k , so we can bring it into the series
 since $AB = BA$, we can pass B to the left k -times

$\rightarrow = \sum_{k=0}^{\infty} \frac{B A^k}{k!} = B \sum_{k=0}^{\infty} \frac{A^k}{k!} = B e^A \rightarrow \text{done!}$