

Lecture 7

Conway - Alexander polynomial is the unique polynomial of oriented links such that

- $\nabla_V(z) = 1$ for $V = \text{unknot}$
- $\nabla_{L_+}(z) - \nabla_{L_-}(z) = -z \nabla_{L_0}(z)$

where



L_+
 L_-
 L_0

Remark: The invariant $\nabla_L(z)$ can be computed in terms of a skein resolution of L .

• The Conway potential $\nabla_L(z)$ is related to the Alexander polynomial by setting $z = t^{1/2} - t^{-1/2}$.
 i.e. $\Delta_K(t) = \nabla_K(z = t^{1/2} - t^{-1/2})$

In that normalization, $\Delta_K(1) = 1$ and $\Delta_K(t^{-1}) = \Delta_K(t)$.

• Recall that $\Delta_K(t)$ does not distinguish a knot K from its mirror image. It also does not distinguish 6_1 from 9_{46} .

Both have
$$\Delta_K(t) = 2 - 5t + 2t^2$$

$$= 2t^{-1} - 5 + 2t$$

The Jones polynomial represents a vast improvement over the Alexander-Conway poly.

The Jones polynomial is defined in terms of the Kauffman bracket.

The bracket $\langle K \rangle$ is defined for knot and link diagrams and satisfies

- $\langle \bigcirc \rangle = 1$
- $\langle L \cup \bigcirc \rangle = (-A^2 - A^{-2}) \langle L \rangle$
- $\langle \text{X} \rangle = A \langle \text{) (} \rangle + \bar{A} \langle \text{ } \rangle$

$\langle L \rangle \in \mathbb{Z}[A, A^{-1}]$ and it is invariant under RM II $\div$ III moves, but not RM I.

Lemma $\langle \text{ } \rangle = -A^3 \langle \text{ } \rangle$ and $\langle \text{ } \rangle = -\bar{A}^3 \langle \text{ } \rangle$

Corollary $\langle \text{ } \rangle = -A^3 \langle \text{ } \rangle = -A^3$

$$\langle \text{ } \rangle = -\bar{A}^3 \langle \text{ } \rangle = -\bar{A}^3$$

Defn The f-polynomial of an oriented link is the quantity

$$f_K(A) = (-A^{-3})^{w(K)} \langle K \rangle$$

where $w(K)$ = total writhe of K .

It is invariant under all 3 Reidemeister moves.

Defn The Jones polynomial is obtained by setting $t^{-1/2} = A^2$ in the f-polynomial.
 i.e. $V_K(t) = f_K(t^{-1/4} = A)$.

Theorem (Jones) There exists a unique polynomial invariant of oriented knots and links satisfying

- (1) $V_U(t) = 1$ for $U = \text{unknot}$
- (2) $t^{-1} V_{L_+}(t) - t V_{L_-}(t) = (t^{1/2} - t^{-1/2}) V_{L_0}(t)$

for



L_+



L_-



L_0

$$V_L(t) \in \mathbb{Z}[t^{1/2}, t^{-1/2}]$$

Proof (2) $\langle \text{X} \rangle = A \langle \text{) (} \rangle + A^{-1} \langle \text{X} \rangle$

$$\langle \text{X} \rangle = A^{-1} \langle \text{) (} \rangle + A \langle \text{X} \rangle$$

$$A \langle \text{X} \rangle - A^{-1} \langle \text{X} \rangle = (A^2 - A^{-2}) \langle \text{) (} \rangle$$

$$\Rightarrow A \langle L_+ \rangle - A^{-1} \langle L_- \rangle = (A^2 - A^{-2}) \langle L_0 \rangle$$

For oriented links, notice that

$$w(L_+) = w(L_0) + 1$$

$$w(L_-) = w(L_0) - 1$$

$$\text{Therefore, } f_{L_+}(A) = (-A^{-3})^{\omega(L_+)} \langle L_+ \rangle =$$

$$= (-A^{-3})^{\omega(L_0)} \cdot (-A^{-3}) \langle L_+ \rangle$$

$$f_{L_-}(A) = (-A^{-3})^{\omega(L_-)} \langle L_- \rangle$$

$$= (-A^{-3})^{\omega(L_0)} (-A^{-3}) \langle L_- \rangle$$

$$A^4 f_{L_+}(A) - A^{-4} f_{L_-}(A)$$

$$= (-A^{-3})^{\omega(L_0)} [-A \langle L_+ \rangle + A^{-1} \langle L_- \rangle]$$

$$= (-A^{-3})^{\omega(L_0)} [(-A^2 + A^{-2}) \langle L_0 \rangle]$$

$$\Rightarrow \bar{t}^{-1} V_{L_+}(t) - t V_{L_-}(t) = (-\bar{t}^{-1/2} + t^{1/2}) V_{L_0}(t)$$

Examples 1. $\langle \bigcirc \bigcirc \rangle = (-A^2 - A^{-2}) \langle \bigcirc \rangle$

$$= -A^2 - A^{-2}$$

$$V_{00}(t) = -\bar{t}^{-1/2} - t^{1/2}$$

2. Hopf links

$$\langle \bigcirc \bigcirc \rangle = A \langle \bigcirc \bigcirc \rangle + A^{-1} \langle \bigcirc \bigcirc \rangle$$

$$= A(-A^3) + A^{-1}(-A^{-3}) \text{ by Cor.}$$

$$= -A^4 - A^{-4}$$

Now consider the two Hopf links

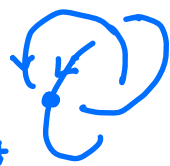
 H_+ positive Hopf link $\omega(H_+) = 2$

 H_- negative Hopf link $w(H_-) = -2$

$$\begin{aligned} V_{H_+}(t) &= [(-A^{-3})^2 \langle H \rangle]_{t^{-1/2}=A} \\ &= A^{-6} (-A^4 - A^{-4}) \Big|_{t^{-1/2}=A} \\ &= -A^{-2} - A^{-10} \Big|_{t^{-1/2}=A} = -t^{1/2} - t^{5/2} \end{aligned}$$

Likewise $V_{H_-}(t) = -t^{-1/2} - t^{-5/2}$

(Notice that H_- is the mirror image of H_+ , and under taking mirror images, the Jones polynomials are related by replacing t by t^{-1} .)

3.  $K=L_+$

$$V_K(t) = -t^4 + t^3 + t$$

for $K = RH$ trefoil.

L_- L_0


unknot


pos. Hopf

$$\begin{aligned} t^{-1} V_{L_+} - t V_{L_-} &= (t^{1/2} - t^{-1/2}) V_{L_0} \\ t^{-1} V_K &= t \cdot 1 + (t^{1/2} - t^{-1/2})(-t^{1/2} - t^{5/2}) \\ &= t + (-t - t^3 + 1 + t^2) \\ &= -t^3 + 1 + t^2 \end{aligned}$$

$$V_K(t) = -t^4 + t^3 + t$$

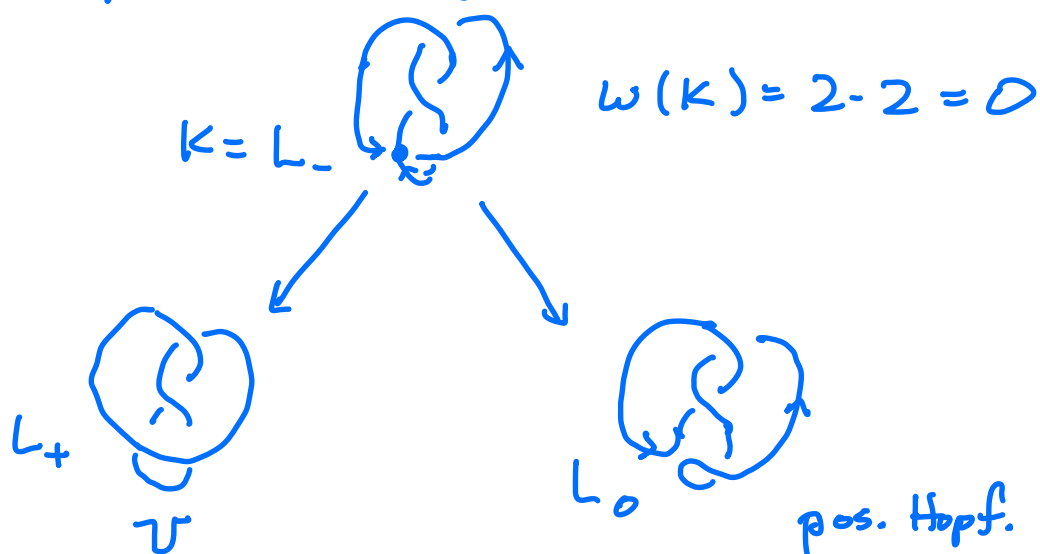
Notice that if K^* is the left hand trefoil, the mirror image of the right hand trefoil, then $V_{K^*}(t) = -t^{-4} + t^{-3} + t^{-1}$

$$V_K(t) \neq V_{K^*}(t)$$

$\Rightarrow$ The RH trefoil is not equivalent to the LH trefoil.



Example The figure 8 knot 4_1



$$t V_{L_-} = t^{-1} V_{L_+} - (t^{1/2} - t^{-1/2}) V_{L_0}$$

$$t V_K = t^{-1} \cdot 1 - (t^{1/2} - t^{-1/2}) (-t^{5/2} - t^{1/2})$$

$$\begin{aligned}
&= t^{-1} - (-t^3 - t + t^2 + 1) \\
&= t^{-1} + t^3 + t - t^2 - 1 \\
tV_K &= t^3 - t^2 + t - 1 + t^{-1} \\
V_K(t) &= t^2 - t + 1 - t^{-1} + t^{-2}
\end{aligned}$$

Notice that $V_K(t^{-1}) = V_K(t)$.
This reflects the fact that the figure 8 knot is equal to its mirror image.
i.e. $K^* = K$ for $K = 4$.

Defn A knot K is said to be amphicheiral if it is equivalent to its mirror image.

Exercise Show that the figure 8 knot is amphicheiral.

Theorem If K is amphicheiral then
 $V_K(t) = V_K(t^{-1})$

The converse is not generally true. For example, 8_{17} is not amphicheiral even though its Jones polynomial is symmetric.

- Remark
1. $V_{K^*}(t) = V_K(t^{-1})$
 2. $V_U(t) = 1$ for $U = \text{unknot}$

OPEN PROBLEM

Does the Jones polynomial detect the unknot?
This has been verified for diagrams up to 25 crossings.

3. Determine necessary and sufficient conditions for a polynomial $f(t) \in \mathbb{Z}[t, t^{-1}]$ to occur as the Jones polynomial for some knot $K \subseteq S^3$.

4. Property $V(K_1 \# K_2) = V(K_1) V(K_2)$