

Monte Carlo Likelihood Approximation

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1 Monte Carlo Likelihood Approximation

Let $f_\theta(x, y)$ be the complete data density for a missing data model, the missing data being x and the observed data being y . Suppose we have observed data y_1, \dots, y_n which are independent and identically distributed (IID) and simulations x_1, \dots, x_m which are IID from a known importance sampling distribution with density h .

The (observed data) log likelihood for this model is

$$l_n(\theta) = \sum_{j=1}^n \log f_\theta(y_j) \quad (1)$$

where

$$f_\theta(y) = \int f_\theta(x, y) dx$$

is the marginal for y .

The Monte Carlo likelihood approximation for (1) is

$$l_{m,n}(\theta) = \sum_{j=1}^n \log f_{m,\theta}(y_j) \quad (2a)$$

where

$$f_{\theta,m}(y) = \frac{1}{m} \sum_{i=1}^m \frac{f_{\theta}(x_i, y)}{h(x_i)}. \quad (2b)$$

The maximizer $\hat{\theta}_{m,n}$ of (2a) is the Monte Carlo (approximation to the) MLE (the MCMLE).

Derivatives of (2a) are, of course,

$$\nabla^k l_{m,n}(\theta) = \sum_{j=1}^n \nabla^k \log f_{m,\theta}(y_j)$$

where ∇ denotes differentiation with respect to θ , and derivatives of (2b) are

$$\nabla f_{\theta,m}(y) = \sum_{i=1}^m \nabla \log f_{\theta}(x_i, y) \cdot v_{\theta}(x_i, y), \quad (3a)$$

where

$$v_{\theta}(x, y) = \frac{\frac{f_{\theta}(x, y)}{h(x)}}{\sum_{i=1}^m \frac{f_{\theta}(x_i, y)}{h(x_i)}}, \quad (3b)$$

and

$$\begin{aligned} \nabla^2 \log f_{\theta,m}(y) &= \sum_{i=1}^m \nabla^2 \log f_{\theta}(x_i, y) \cdot v_{\theta}(x_i, y) \\ &+ \sum_{i=1}^m (\nabla \log f_{\theta}(x_i, y)) (\nabla \log f_{\theta}(x_i, y))^T \cdot v_{\theta}(x_i, y) \\ &- (\nabla \log f_{\theta,m}(y)) (\nabla \log f_{\theta,m}(y))^T. \end{aligned} \quad (3c)$$

These derivative formulas are not obvious but are derived as equations (4.8), (4.9), (4.12), and (4.13) in the first author's thesis.

2 Asymptotic Variance

The asymptotic variance of $\hat{\theta}_{m,n}$, including both the sampling variation in y_1, \dots, y_n and the Monte Carlo variation in x_1, \dots, x_m is

$$J(\theta)^{-1} \left(\frac{V(\theta)}{n} + \frac{W(\theta)}{m} \right) J(\theta)^{-1} \quad (4)$$

where

$$V(\theta) = \text{var}\{\nabla \log f_{\theta}(Y)\} \quad (5a)$$

$$J(\theta) = E\{-\nabla^2 \log f_{\theta}(Y)\} \quad (5b)$$

$$W(\theta) = \text{var} \left\{ E \left[\frac{\nabla f_{\theta}(X | Y)}{h(X)} \mid X \right] \right\} \quad (5c)$$

where X and Y here have the same distribution as x_i and y_j , respectively. This is the content of Theorem 3.3.1 in the first author's thesis.

The first two of these quantities have obvious “plug-in” estimators

$$\hat{V}_{m,n}(\theta) = \frac{1}{n} \sum_{j=1}^n (\nabla \log f_{\theta,m}(y_j)) (\nabla \log f_{\theta,m}(y_j))^T \quad (6a)$$

$$\hat{J}_{m,n}(\theta) = -\frac{1}{n} \sum_{j=1}^n \nabla^2 \log f_{\theta,m}(y_j) \quad (6b)$$

Thus a natural plug-in estimator is

$$\hat{W}_{m,n}(\theta) = \frac{1}{m} \sum_{i=1}^m \hat{S}_{m,n}(\theta, x_i) \hat{S}_{m,n}(\theta, x_i)^T \quad (6c)$$

where

$$\hat{S}_{m,n}(\theta, x) = \frac{1}{n} \sum_{j=1}^n (\nabla \log f_{\theta}(x, y_j) - \nabla \log f_{\theta,m}(y_j)) \cdot \frac{f_{\theta}(x, y_j)}{f_{\theta,m}(y_j)h(x)} \quad (6d)$$

See equations (2.7) and (2.9) in the first author's thesis.

Estimation of W using (6c) and (6d) has the drawback that it either uses $O(mp)$ memory storing all the $\log f_{\theta,m}(y_j)$ and their derivatives, where p is the dimension of the parameter vector θ or it uses $O(mnp)$ time recalculating these quantities. Neither alternative is attractive when m and n are large.

Thus we use an alternative method of estimating W based on the method of batch means, which is usually only used for time series. Let $n = b \cdot l$, where b and l are positive integers, called the *batch number* and *batch length*, respectively. For $k = 1, \dots, b$ calculate

$$\tilde{S}_{m,n,k}(\theta) = \frac{1}{l} \sum_{i=(k-1)l+1}^{kl} \hat{S}_{m,n}(\theta, x_i) \quad (7a)$$

and use

$$\tilde{W}_{m,n}(\theta) = \frac{l}{b} \sum_{k=1}^b \tilde{S}_{m,n,k}(\theta) \tilde{S}_{m,n,k}(\theta)^T. \quad (7b)$$

The factor l in (7b) comes from the fact that the batch means (7a) have $1/l$ times the variance of the individual items (6d).

Using the method of batch means we can estimate W using $O(p)$ memory and only $O(bmp)$ in recalculation. Since the total time is necessarily at least $O(mnp) + O(bp^2)$, this recalculation is negligible so long as b is much smaller than n .

3 Bernoulli Regression with Random Effects

3.1 Normal Random Effects

The `bernor` package up through version 0.2 does only normal random effects.

3.1.1 Complete Data Density

The complete data density that for Bernoulli regression with normal random effects: the response y is conditionally Bernoulli given the fixed effect vector β and the random effect vector b . For this model we change notation, denoting the missing data by b rather x , which we used in the general discussion (to avoid confusion with “big X ” defined presently).

The “other data” for the problem consist of model matrices X and Z , both having row dimension equal to the length of y , X having column dimension equal to the length of β , and Z having column dimension equal to the length of b . Then the “linear predictor” is

$$\eta = X\beta + Z\Sigma b \quad (8)$$

where Σ is a diagonal matrix that specifies the variance components. In R the linear predictor can be specified by

```
eta <- X %*% beta + Z %*% (sigma[i] * b)
```

where `sigma[i]` is the diagonal of Σ , `sigma` being a vector of scale parameters for the random effects and `i` being an index vector that says which scale parameter goes with which random effect (the lengths of `i` and `b` are equal, and each element of `i` is an integer in `seq(along = sigma)`).

Then

```
p <- 1 / (1 + exp(- eta))
```

is the vector of success probabilities. The complete data log density (or complete data log likelihood) is then

$$\log f_{\theta}(y, b) = \sum [y \log(p) + (1 - y) \log(1 - p)] + \sum \log \phi(b)$$

where the first sum runs over elements of y and p (which are the same length), the second sum runs over elements of b , and ϕ is the density of elements of b , which are assumed to be IID mean zero normal. The parameter vector θ combines β and σ .

3.1.2 Gradient

There are two types of elements of the gradient vector (partials with respect to θ 's that are β 's and partials with respect to θ 's that are σ 's). The first are

$$\nabla_{\beta} \log f_{\theta}(y, b) = (y - p)X. \quad (9a)$$

The second are

$$\frac{\partial}{\partial \sigma_k} \log f_{\theta}(y, b) = \sum_{j=1}^{|y|} (y_j - p_j) \sum_{\substack{m=1 \\ i_m=k}}^{|b|} z_{jm} b_m. \quad (9b)$$

For parallelism, we might as well rewrite (9a) to look more like (9b).

$$\frac{\partial}{\partial \beta_k} \log f_\theta(y, b) = \sum_{j=1}^{|y|} (y_j - p_j) x_{jk}. \quad (9c)$$

3.1.3 Hessian

The hessian is fairly simple. First, note that

$$\frac{\partial p_j}{\partial \eta_j} = p_j(1 - p_j).$$

So

$$\frac{\partial^2}{\partial \beta_k \partial \beta_l} \log f_\theta(y, b) = - \sum_{j=1}^{|y|} p_j(1 - p_j) x_{jk} x_{jl} \quad (10a)$$

$$\frac{\partial^2}{\partial \sigma_k \partial \sigma_l} \log f_\theta(y, b) = - \sum_{j=1}^{|y|} p_j(1 - p_j) \sum_{\substack{m=1 \\ i_m=k}}^{|b|} z_{jm} b_m \sum_{\substack{n=1 \\ i_n=l}}^{|b|} z_{jn} b_n \quad (10b)$$

$$\frac{\partial^2}{\partial \beta_k \partial \sigma_l} \log f_\theta(y, b) = - \sum_{j=1}^{|y|} p_j(1 - p_j) x_{jk} \sum_{\substack{n=1 \\ i_n=l}}^{|b|} z_{jn} b_n \quad (10c)$$