

GRAM-SCHMIDT ORTHONORMALISATION

An algorithm for 'orthonormalising' a set of vectors.
that are in $\mathbb{R}^n$

Takes a finite, linearly independent set $S = \{v_1, \dots, v_k\}$

Generates a finite, orthogonal set $S' = \{u_1, \dots, u_n\}$

NOTE: We must have $k \leq n$ or else not enough DOF.

How it works:

Define a projection operator $\text{proj}_{\underline{u}}(\underline{v}) = \frac{\langle \underline{u}, \underline{v} \rangle}{\langle \underline{u}, \underline{u} \rangle} \underline{u}$.

where $\langle \underline{u}, \underline{v} \rangle$ is usually
just the dot product.

Then $\hat{u}_1 = v_1$

$$\hat{u}_2 = v_2 - \text{proj}_{\hat{u}_1}(v_2)$$

$$\hat{u}_3 = v_3 - \text{proj}_{\hat{u}_1}(v_3) - \text{proj}_{\hat{u}_2}(v_3)$$

$$\vdots$$
$$\hat{u}_k = v_k - \sum_{j=1}^{k-1} \text{proj}_{\hat{u}_j}(v_k)$$

Then $u_i = \frac{\hat{u}_i}{\|\hat{u}_i\|}$.

Ob

EX. $\underline{v}_1 = \begin{pmatrix} 2 \\ 3 \end{pmatrix}$ $\underline{v}_2 = \begin{pmatrix} -1 \\ 0 \end{pmatrix}$

$\underline{w}_1 = \begin{pmatrix} 2 \\ 3 \end{pmatrix}$ ~~XXXXXXXXXX~~

$\underline{w}_2 = \begin{pmatrix} -1 \\ 0 \end{pmatrix} - \frac{\begin{pmatrix} -1 \\ 0 \end{pmatrix} \cdot \begin{pmatrix} 2 \\ 3 \end{pmatrix}}{\begin{pmatrix} 2 \\ 3 \end{pmatrix} \cdot \begin{pmatrix} 2 \\ 3 \end{pmatrix}} \cdot \begin{pmatrix} 2 \\ 3 \end{pmatrix} = \begin{pmatrix} -1 \\ 0 \end{pmatrix} + \frac{2}{13} \cdot \begin{pmatrix} 2 \\ 3 \end{pmatrix}$

$= \begin{pmatrix} -1 \\ 0 \end{pmatrix} + \begin{pmatrix} 4/13 \\ 6/13 \end{pmatrix}$

$= \begin{pmatrix} -9/13 \\ 6/13 \end{pmatrix} = \begin{pmatrix} -9 \\ 6 \end{pmatrix} = \begin{pmatrix} -3 \\ 2 \end{pmatrix}$

$\underline{w}_1 \cdot \underline{w}_2 = \begin{pmatrix} 2 \\ 3 \end{pmatrix} \cdot \begin{pmatrix} -9 \\ 6 \end{pmatrix} = -18 + 18 = 0 \quad \checkmark$

$\underline{w}_1 = \frac{1}{\sqrt{13}} \begin{pmatrix} 2 \\ 3 \end{pmatrix}$ $\underline{w}_2 = \frac{1}{\sqrt{13}} \begin{pmatrix} -3 \\ 2 \end{pmatrix}$

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THE SINGULAR VALUE DECOMPOSITION

Very useful for overdetermined (rectangular/least square) problems.

$$\underline{A} \underline{x} = \underline{b} \quad \underline{A} \in \mathbb{R}^{m \times n} \text{ with } m \geq n.$$

For any such matrix ~~matrix~~ A there exist a

$$\underline{U} \in \mathbb{R}^{m \times m}, \quad \underline{V} \in \mathbb{R}^{n \times n}, \quad \underline{\Sigma} \in \mathbb{R}^{m \times n}$$

$\swarrow$ orthogonal $(\underline{A}^T \underline{A} = \underline{A} \underline{A}^T = \underline{I})$ $\searrow$ diagonal

such that

$$\underline{A} = \underline{U} \underline{\Sigma} \underline{V}^T$$

and $\underline{\Sigma} = \text{diag}(\sigma_1, \sigma_2, \dots, \sigma_n)$ with $\sigma_1 \geq \sigma_2 \geq \dots \geq \sigma_n \geq 0$

NOTE: If $\sigma_r > 0$ is the smallest singular value greater than zero, then the matrix A has rank r .

We call - the columns of U the left singular vectors.

- " " V - " right " "

- the diagonal entries of $\underline{\Sigma}$ are the singular values of A

(2)

How do we find U, Σ and V?

- 1) Compute ~~AA^T~~ Eig vals and vecs of AA^T
- 2) Orthonormalise the Eig. vecs.
- 3) The columns of U are these ~~same~~ vectors ordered by size of Eigs.
- 4) Compute Eig vals and vecs of A^TA
- 5) Orthonormalise the Eig vecs.
- 6) The columns of V are these vectors organised
- 7) Σ is diagonal with entries $\sqrt{\text{Eigs}}$ ordered.

EX $\underline{A} = \begin{pmatrix} 3 & 1 & 1 \\ -1 & 3 & 1 \end{pmatrix} \quad \underline{A}\underline{A}^T = \begin{pmatrix} 11 & 1 \\ 1 & 11 \end{pmatrix}$

Eigs of AA^T: $(11 - \lambda)^2 - 1 = 0 \Rightarrow 11 - \lambda = \pm 1$

$\Rightarrow \boxed{\lambda = 10, 12}$

$\lambda = 10: \begin{pmatrix} 1 & 1 \\ 1 & 1 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \underline{0} \Rightarrow \boxed{x_1 = -x_2}$

$\lambda = 12: \begin{pmatrix} -1 & 1 \\ 1 & -1 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \underline{0} \Rightarrow \boxed{x_1 = x_2}$

Thus: $\lambda = 10$ $\underline{x} = \begin{pmatrix} 1 \\ -1 \end{pmatrix}$ and $\lambda = 12$ $\underline{x} = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$

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$$\underline{\hat{u}} = \begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix}$$

$$\underline{\hat{u}}_1 = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

$$\underline{\hat{u}}_2 = \begin{pmatrix} +1 \\ -1 \end{pmatrix}$$

$$\underline{\hat{w}}_1 = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ 1 \end{pmatrix} \quad \underline{\hat{w}}_2 = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ -1 \end{pmatrix}$$

CHECK $\underline{w}_1 \cdot \underline{w}_2 = 0$.

$$\underline{u} = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix}$$

$$\underline{A}^T \underline{A} = \begin{pmatrix} 10 & 0 & 2 \\ 0 & 10 & 4 \\ 2 & 4 & 2 \end{pmatrix}$$

$$\lambda(\lambda-10)(\lambda-12) = 0$$

$$\Rightarrow \boxed{\lambda = 0, 10, 12}$$

Thus $\lambda=12$ $\underline{x} = \begin{pmatrix} 1 \\ 2 \\ 1 \end{pmatrix}$, $\lambda=10$ $\underline{x} = \begin{pmatrix} 2 \\ -1 \\ 0 \end{pmatrix}$

$\lambda=0$ $\underline{x} = \begin{pmatrix} 1 \\ 2 \\ -5 \end{pmatrix}$

$$\underline{\hat{v}} = \begin{pmatrix} 1 & 2 & 1 \\ 2 & -1 & 2 \\ 1 & 0 & -5 \end{pmatrix}$$

$$\underline{\hat{v}}_1 = \begin{pmatrix} 1 \\ 2 \\ 1 \end{pmatrix}$$

$$\underline{\hat{v}}_2 = \begin{pmatrix} 2 \\ -1 \\ 0 \end{pmatrix}$$

$$\underline{\hat{v}}_3 = \begin{pmatrix} 1 \\ 2 \\ -5 \end{pmatrix}$$

$$\underline{V} = \begin{pmatrix} \frac{1}{\sqrt{6}} & \frac{2}{\sqrt{6}} & \frac{1}{\sqrt{6}} \\ \frac{2}{\sqrt{5}} & -\frac{1}{\sqrt{5}} & 0 \\ \frac{1}{\sqrt{30}} & \frac{2}{\sqrt{30}} & -\frac{5}{\sqrt{30}} \end{pmatrix}$$

$$\underline{\underline{S}} = \begin{pmatrix} \sqrt{12} & 0 & 0 \\ 0 & \sqrt{10} & 0 \end{pmatrix}$$

CHECK: $\underline{\underline{A}} = \underline{\underline{U}} \underline{\underline{S}} \underline{\underline{V}}^T$ ✓

Why is this useful?

1) It allows us to easily compute the pseudo-inverse

If $\underline{\underline{A}} = \underline{\underline{U}} \underline{\underline{\Sigma}} \underline{\underline{V}}^T$ Then $\underline{\underline{A}}^+ \leftarrow$ the pseudo-inverse of $\underline{\underline{A}}$

$$\underline{\underline{A}}^+ = \underline{\underline{V}} \underline{\underline{\Sigma}}^+ \underline{\underline{U}}^T$$

and $\underline{\underline{\Sigma}}^+$ is computed by each non-zero diagonal entry of $\underline{\underline{\Sigma}}$ with its reciprocal and then transposing.

2) least square minimization.

This can be use for finding a 'best fit' to data

$$\min_x \| \underline{\underline{A}} \underline{\underline{x}} - \underline{\underline{b}} \|$$

A soln is given by $\underline{\underline{A}}^+ \underline{\underline{b}} = \underline{\underline{x}}$

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3) Approximating the condition number.

$$\text{cond}(A) = \|A\| \|A^+\|. \quad (= \|A\| \|A^{-1}\|).$$

$$\text{cond}(A) \approx \frac{\sigma_1}{\sigma_r}$$