On the Boltzmann equation: global solutions in one spatial dimension

Walter Craig

Department of Mathematics & Statistics



Colloque de mathématiques de Montréal Centre de Recherches Mathématiques November 11, 2005

Walter Craig

Global solutions of the Boltzmann equation

McMaster University

Collaborators

Andrei Biryuk McMaster University



Vlad Panferov McMaster University



Walter Craig Global solutions of the Boltzmann equation

Summary

The Boltzmann equation for $f(x, v, t) \ge 0$ with $x \in \mathbb{R}^1/\mathbb{Z}^1$, $v \in \mathbb{R}^3$ The macroscopic density

$$\rho(x,t) = \int_{v \in \mathbb{R}^3} f(x,v,t) \, dv$$

The entropy relative to a Maxwellian $M(v) = m \left(\frac{a}{\pi}\right)^{3/2} e^{-a|v-u|^2}$ is

$$H(f|M) = \int_{x \in \mathbb{T}^1} \int_{v \in \mathbb{R}^3} \left(f \log(\frac{f}{M}) - f + M \right) \, dv dx$$

Main result: There exists a constant C_0 such that if $\rho_0(x) \in L_x^{\infty}$ and

for some M_0 , $H(f_0|M_0) \le C_0$ then global strong solutions exist.

The Boltzmann equation

Global existence results

Uniqueness

Properties of propagation

Main ideas of the proof

Walter Craig Global solutions of the Boltzmann equation

The Boltzmann equation

Global existence results

Uniqueness

Properties of propagation

Main ideas of the proof

Walter Craig Global solutions of the Boltzmann equation McMaster University

The Boltzmann equation

Global existence results

Uniqueness

Properties of propagation

Main ideas of the proof

Walter Craig Global solutions of the Boltzmann equation

The Boltzmann equation

Global existence results

Uniqueness

Properties of propagation

Main ideas of the proof

Walter Craig

Global solutions of the Boltzmann equation

McMaster University

The Boltzmann equation

Global existence results

Uniqueness

Properties of propagation

Main ideas of the proof

Boltzmann equation

The classical Boltzmann equation

$$\partial_t f + v \cdot \partial_x f = Q(f, f) , \qquad f(x, v, 0) = f_0(x, v) \qquad (1)$$

Phase space coordinates $(x, v) \in \mathbb{R}^3_x \times \mathbb{R}^3_v$. Phase space distribution function f(x, v, t).

• In case Q = 0 the solution is

$$f(x, v, t) = f_0(x - tv, v) = \Phi_t(f_0)(x, v)$$

Free streaming flow of the equation (1) linearized about f = 0

•
$$Q(f,f)$$
 is the collision operator

Boltzmann equation

The classical Boltzmann equation

$$\partial_t f + v \cdot \partial_x f = Q(f, f) , \qquad f(x, v, 0) = f_0(x, v) \qquad (1)$$

Phase space coordinates $(x, v) \in \mathbb{R}^3_x \times \mathbb{R}^3_v$. Phase space distribution function f(x, v, t).

• In case Q = 0 the solution is

$$f(x, v, t) = f_0(x - tv, v) = \Phi_t(f_0)(x, v)$$

Free streaming flow of the equation (1) linearized about f = 0

•
$$Q(f,f)$$
 is the collision operator

Boltzmann equation

The classical Boltzmann equation

$$\partial_t f + v \cdot \partial_x f = Q(f, f), \qquad f(x, v, 0) = f_0(x, v) \tag{1}$$

Phase space coordinates $(x, v) \in \mathbb{R}^3_x \times \mathbb{R}^3_v$. Phase space distribution function f(x, v, t).

• In case Q = 0 the solution is

$$f(x, v, t) = f_0(x - tv, v) = \Phi_t(f_0)(x, v)$$

Free streaming flow of the equation (1) linearized about f = 0

•
$$Q(f,f)$$
 is the collision operator

portrait of Ludwig Boltzmann (1844 - 1906)

29/09/05

http://www.sil.si.edu/digitalcollectio...-identity/thumbnails/TNSIL14-B5-06.jpg

#1



Walter Craig Global solutions of the Boltzmann equation McMaster University

portrait of J. C. Maxwell (1831 - 1879)

03 / 1 0/ 05



http://www.egr.msu.edu/~bohnsac3/nano/figures/Max#v1e

Walter Craig

McMaster University

Collision operator

The collision operator of Maxwell and Boltzmann

$$Q(f,f)(x,v) = \int_{\mathbb{R}^{3}_{v_{*}}} \int_{\mathbb{S}^{2}_{\sigma}} (f(x,v')f(x,v'_{*}) - f(x,v)f(x,v_{*})) \\ \times K \, dS_{\sigma} dv_{*} \\ = Q^{+}(f,f)(x,v) - Q^{-}(f,f)(x,v)$$
(2)

▶ Velocities before v', v'_* and after v, v_* a binary collision satisfy

 $v + v_* = v' + v'_*$ and $(v' - v'_*)/|v - v_*| = \sigma \in \mathbb{S}^2$

• The collision kernel $K = K(|v - v_*|, \frac{(v - v_*)}{|v - v_*|} \cdot \sigma)$

Global solutions of the Boltzmann equation

Collision operator

The collision operator of Maxwell and Boltzmann

$$Q(f,f)(x,v) = \int_{\mathbb{R}^{3}_{v_{*}}} \int_{\mathbb{S}^{2}_{\sigma}} (f(x,v')f(x,v'_{*}) - f(x,v)f(x,v_{*})) \\ \times K \, dS_{\sigma} dv_{*} \\ = Q^{+}(f,f)(x,v) - Q^{-}(f,f)(x,v)$$
(2)

▶ Velocities before v', v'_* and after v, v_* a binary collision satisfy

 $v + v_* = v' + v'_*$ and $(v' - v'_*)/|v - v_*| = \sigma \in \mathbb{S}^2$

• The collision kernel $K = K(|v - v_*|, \frac{(v - v_*)}{|v - v_*|} \cdot \sigma)$

Global solutions of the Boltzmann equation

Collision operator

The collision operator of Maxwell and Boltzmann

$$Q(f,f)(x,v) = \int_{\mathbb{R}^{3}_{v_{*}}} \int_{\mathbb{S}^{2}_{\sigma}} (f(x,v')f(x,v'_{*}) - f(x,v)f(x,v_{*})) \\ \times K \, dS_{\sigma} dv_{*} \\ = Q^{+}(f,f)(x,v) - Q^{-}(f,f)(x,v)$$
(2)

▶ Velocities before v', v'_* and after v, v_* a binary collision satisfy

$$v + v_* = v' + v'_*$$
 and $(v' - v'_*)/|v - v_*| = \sigma \in \mathbb{S}^2$

• The collision kernel $K = K(|v - v_*|, \frac{(v - v_*)}{|v - v_*|} \cdot \sigma)$

Global solutions of the Boltzmann equation

Macroscopic quantities

macroscopic mass density

$$\rho(x,t) = \int_{v \in \mathbb{R}^3} f(x,v,t) \, dv$$

macroscopic momentum density

$$\rho u(x,t) = \int_{v \in \mathbb{R}^3} v f(x,v,t) \, dv$$

macroscopic energy density

$$\rho e(x,t) = \int_{v \in \mathbb{R}^3} |v|^2 f(x,v,t) \, dv$$

McMaster University

Macroscopic conservation laws

• Conservation of mass:

$$\partial_t \rho(x,t) + \nabla_x \cdot F_\rho(x,t) = 0$$

with density flux $F_{\rho} = \int_{v \in \mathbb{R}^3} v f(x, v, t) dv$

Conservation of momentum:

$$\partial_t \rho u(x,t) + \nabla_x \cdot F_{\rho u}(x,t) = 0$$

with momentum flux $F_{\rho u} = \int_{v \in \mathbb{R}^3} v \otimes v f(x, v, t) dv$

Conservation of energy:

$$\partial_t \rho e(x,t) + \nabla_x \cdot F_{\rho e}(x,t) = 0$$

with energy flux $F_{\rho e} = \int_{v \in \mathbb{R}^3} |v|^2 v f(x, v, t) dv$

NB The closure problem

Walter Craig

One dimensional geometry

We take $x \in \mathbb{R}^1$ and $v \in \mathbb{R}^3$, which is known as the slab geometry. It is the setting of a narrow shock tube, or a situation with spanwise constant macroscopic quantities.

Furthermore, we ask for periodic spatial boundary conditions; that is $x \in \mathbb{R}^1$ and $v \in \mathbb{R}^3$.

NB: Periodic boundary conditions, or perturbations of a state of thermodynamic equilibrium (a constant Maxwellian background) are more difficult problems than setting $f \in L^1(\mathbb{R}^3_x \times \mathbb{R}^3_v)$ in the background of a vacuum.

Conserved quantities

Total Mass

$$M(f) = \int_{\mathbb{T}^1} \rho(x,t) \, dx = \int_{\mathbb{T}^1} \int_{v \in \mathbb{R}^3} f(x,v,t) \, dv dx$$

Total Momentum

$$I(f) = \int_{\mathbb{T}^1} \rho u(x,t) \, dx = \int_{\mathbb{T}^1} \int_{v \in \mathbb{R}^3} v f(x,v,t) \, dv dx$$

Total Energy

$$E(f) = \int_{\mathbb{T}^1} \rho e(x,t) \, dx = \int_{\mathbb{T}^1} \int_{v \in \mathbb{R}^3} |v|^2 f(x,v,t) \, dv dx$$

These quantities are constants of motion for the Boltzmann equation.

Walter Craig

Relative entropy

Define the relative entropy of a phase space distribution function f(x, v) with respect to a constant Maxwellian distribution by

$$H(f|M) = \int_{\mathbb{T}^1} \int_{v \in \mathbb{R}^3} \left(f \log(\frac{f}{M}) - f + M \right) dv dx$$

Proposition (1)

Positivity properties of the relative entropy

- $1. \qquad H(f|M) \ge 0$
- 2. Let $m := \int_{v \in \mathbb{R}^3} M \, dv$. The Csiszár–Kullback–Pinsker inequality is equivalent to

$$\int_{\mathbb{T}^1} \int_{v \in \mathbb{R}^3} |f(x, v) - M(v)| \, dv dx \le \sqrt{4mH(f|M)} + H(f|M)$$

Relative entropy

Define the relative entropy of a phase space distribution function f(x, v) with respect to a constant Maxwellian distribution by

$$H(f|M) = \int_{\mathbb{T}^1} \int_{v \in \mathbb{R}^3} \left(f \log(\frac{f}{M}) - f + M \right) dv dx$$

Proposition (1)

Positivity properties of the relative entropy

- $1. \qquad H(f|M) \ge 0$
- 2. Let $m := \int_{v \in \mathbb{R}^3} M \, dv$. The Csiszár–Kullback–Pinsker inequality is equivalent to

$$\int_{\mathbb{T}^1} \int_{v \in \mathbb{R}^3} \left| f(x,v) - M(v) \right| dv dx \le \sqrt{4mH(f|M)} + H(f|M)$$

The *H*-theorem

Proposition (2)

The relative entropy H(f|M) decreases along the flow of the Boltzmann equation

 $\partial_t H(f|M) \leq 0$

Remarks: The following are equivalent:

1. $f \in L\log(L)$ and $\int_x \int_v (1+|v|^2)|f| \, dv \, dx < +\infty$ 2. $f \in L\log\left(\frac{|f|}{M}\right)$ for some Maxwellian M(v)

The |||f||| norm

Definition (3)

For functions f(x, v) on phase space define the norm

$$||f||| := \sup_{\substack{x \in \mathbb{T}^1 \\ p \in \mathbb{R}^+}} \int_{\mathbb{R}^3_{\nu}} |f|(x - p\nu, \nu) \, d\nu$$
(3)

Denote by *X* the space of functions for which this is finite. The function space $X \subseteq L_x^{\infty}(L_v^1)$.

NB: The streaming flow $\Phi_t(f)(x, v) = f(x - tv, v)$ is not continuous on $L_x^{\infty}(L_v^1)$ but it is so on *X*

The |||f||| norm

Definition (3)

For functions f(x, v) on phase space define the norm

$$||f||| := \sup_{\substack{x \in \mathbb{T}^1 \\ p \in \mathbb{R}^+}} \int_{\mathbb{R}^3_{\nu}} |f|(x - p\nu, \nu) \, d\nu$$
(3)

Denote by *X* the space of functions for which this is finite.

The function space $X \subseteq L_x^{\infty}(L_v^1)$.

NB: The streaming flow $\Phi_t(f)(x, v) = f(x - tv, v)$ is not continuous on $L_x^{\infty}(L_v^1)$ but it is so on *X*

First global result

Theorem (4)

Assume that the collision kernel K satisfies hypothesis (H1). Then there is a constant K_0 such that if initial data f_0 for the Boltzmann equation (1) satisfies

$$|||f_0||| < +\infty$$
 and $H(f_0|M_0) \le \frac{1}{4\pi K_0}$ (4)

for some Maxwellian M_0 , then the solution $f(\cdot, t) \in X$ for all $t \in \mathbb{R}^+$.

More specifically the theorem asserts that there is an estimate on the L_x^{∞} norm of the density $\rho(x, t)$. When strict inequality holds in (4)

 $\exists \beta$ such that $\|\rho(x,t)\|_{L^{\infty}_{x}} \leq \|f(x,v,t)\| \leq C_0 \exp(\sqrt{t/\beta})$

First global result

Theorem (4)

Assume that the collision kernel K satisfies hypothesis (H1). Then there is a constant K_0 such that if initial data f_0 for the Boltzmann equation (1) satisfies

$$|||f_0||| < +\infty$$
 and $H(f_0|M_0) \le \frac{1}{4\pi K_0}$ (4)

for some Maxwellian M_0 , then the solution $f(\cdot, t) \in X$ for all $t \in \mathbb{R}^+$.

More specifically the theorem asserts that there is an estimate on the L_x^{∞} norm of the density $\rho(x, t)$. When strict inequality holds in (4)

$$\exists \beta \quad \text{such that} \quad \|\rho(x,t)\|_{L^{\infty}_{x}} \leq \|f(x,v,t)\| \leq C_{0} \exp(\sqrt{t/\beta})$$

Hypotheses on the collision kernel

The result depends upon a newly described smoothing property of the collision kernel *K*.

$$K(r,\xi) = K\left(|v-v_*|, \frac{(v-v_*)\cdot\sigma}{|v-v_*|}\right)$$

Hypothesis (H1)

Large relative velocity interactions are *soft*, while small relative velocity interactions are *hard*:

(H1)
$$0 \leq K(r,\xi) \leq \frac{K_0 w}{1 + w \log^{1+\varepsilon}(w+1)}$$

NB This hypothesis is related to one appearing in Cercignani's work.

Compare with Boltzmann's collision kernel

Power law potential interactions between molecules for 1 are in the form

$$V(|q_1 - q_2|) = rac{\gamma}{|q_1 - q_2|^p}$$

In this case, the classical Boltzmann collision kernel has the form

$$K(r,\xi) = b(\xi)|v-v_*|^{\beta}$$

where $-\infty < \beta = \beta(p) \le 1$. For hard spheres $\beta = 1$, For the Maxwell molecule case p = 5 it turns out that $\beta = 0$.

NB: For all but the hard spheres case, $b(\xi)$ diverges nonintegrably as $\xi \rightarrow \pm 1$. Grad cutoffs appear here, where they truncate grazing collisions.

Walter Craig

McMaster University

A stronger hypothesis on the collision kernel gives a better result

Hypothesis (H2)

Small relative velocity interactions are absent.

(H2) (i)
$$K(r,\xi) = 0$$
 for $r < R_1$
(ii) $K(r,\xi) \ge \beta(\xi) \sup_{\xi \in (-1,1)} (K(r,\xi))$ for $R_1 < r$,
where $\beta(\xi)$ is positive on a set of positive measure.

Theorem (5)

Assume that hypotheses (H1) and (H2) hold, and that

$$\|f_0\| < +\infty \quad \text{and} \quad M(f_0) + E(f_0) < +\infty \tag{5}$$

then for all $t \in \mathbb{R}^+$ solutions to (1) exist and have L_x^{∞} macroscopic density $\rho(x, t)$. NB These solutions could have infinite entropy

Walter Craig

A stronger hypothesis on the collision kernel gives a better result

Hypothesis (H2)

Small relative velocity interactions are absent.

(H2) (i)
$$K(r,\xi) = 0$$
 for $r < R_1$
(ii) $K(r,\xi) \ge \beta(\xi) \sup_{\xi \in (-1,1)} (K(r,\xi))$ for $R_1 < r$,
where $\beta(\xi)$ is positive on a set of positive measure.

Theorem (5)

Assume that hypotheses (H1) and (H2) hold, and that

$$|||f_0||| < +\infty \quad \text{and} \quad M(f_0) + E(f_0) < +\infty \tag{5}$$

then for all $t \in \mathbb{R}^+$ solutions to (1) exist and have L_x^{∞} macroscopic density $\rho(x, t)$.

NB These solutions could have infinite entropy

Uniqueness in X

Solutions f(x, v, t) of the Boltzmann equation (1) such that

$$\rho(x,t) = \int_{\mathbb{R}^3_{\nu}} f(x,v,t) \, dv \in C([0,T]:L^\infty_x)$$

are known as strong solutions.

- Solutions in the class *X* are unique.
- However the more general property of weak/strong uniqueness holds.

Uniqueness in X

Solutions f(x, v, t) of the Boltzmann equation (1) such that

$$ho(x,t) = \int_{\mathbb{R}^3_v} f(x,v,t) \, dv \in C([0,T]:L^\infty_x)$$

are known as strong solutions.

- Solutions in the class *X* are unique.
- However the more general property of weak/strong uniqueness holds.

Uniqueness in X

Solutions f(x, v, t) of the Boltzmann equation (1) such that

$$\rho(x,t) = \int_{\mathbb{R}^3_{\nu}} f(x,v,t) \, dv \in C([0,T]:L^\infty_x)$$

are known as strong solutions.

- Solutions in the class *X* are unique.
- However the more general property of weak/strong uniqueness holds.

Dissipative solutions

Definition (P.-L. Lions (1994))

A nonnegative $f(x, v, t) \in C([0, T]; L^1(\mathbb{T}^1 \times \mathbb{R}^3))$ is a dissipative solution of the Boltzmann equation (1) if for all

$$g(x,v,t) \in L^{\infty}([0,T]; L^{\infty}_{x}(\mathbb{T}^{1}; L^{1}_{v}(\mathbb{R}^{3})))$$

satisfying

$$\partial_t g + v \cdot \nabla_x g - Q(g,g) = \mathcal{E}(g) ,$$

in the sense of distributions, then f obeys the inequality

$$\partial_t \int |f-g| \, dv + \nabla_x \cdot \int v |f-g| \, dv$$

 $\leq \int Q(g,f-g) \operatorname{sgn}(f-g) \, dv - \int \mathcal{E}(g) \operatorname{sgn}(f-g) \, dv$

Walter Craig

McMaster University

Weak/strong uniqueness

Theorem (6) Given initial data satisfying (4), that is

$$|||f_0||| < +\infty \quad and \quad H(f_0|M_0) \le \frac{1}{4\pi K_0}$$
 (6)

any other dissipative solution starting with the same initial data f_0 must coincide with the strong solution for all $t \in \mathbb{R}^+$

In the case where hypothesis (H2) also holds, for uniqueness we only require

$$\llbracket f_0
rbracket$$
 and $M(f_0) + E(f_0) < +\infty$

Weak/strong uniqueness

Theorem (6) Given initial data satisfying (4), that is

$$|||f_0||| < +\infty \quad and \quad H(f_0|M_0) \le \frac{1}{4\pi K_0}$$
 (6)

any other dissipative solution starting with the same initial data f_0 must coincide with the strong solution for all $t \in \mathbb{R}^+$

In the case where hypothesis (H2) also holds, for uniqueness we only require

$$\|f_0\|$$
 and $M(f_0) + E(f_0) < +\infty$

Moments and derivatives

This question has to do with the evolution of smoothness and moment properties of the phase space distribution function f(x, v, t), once the basic property of being a strong solution is established.

- Moments $M_{\kappa}(f) = \sup_{x \in \mathbb{T}^1} \int_{\mathbb{R}^3_{\nu}} v^{\kappa} f(x, v, t) dv$
- Derivatives in v $Q_{\lambda}(f) = \sup_{x \in \mathbb{T}^1} \int_{\mathbb{R}^3_{\nu}} |\partial_{\nu}^{\lambda} f(x, \nu, t)| d\nu$
- Derivatives in x $P_{\mu}(f) = \sup_{x \in \mathbb{T}^1} \int_{\mathbb{R}^3_v} |\partial_x^{\mu} f(x, v, t)| dv$

Global solutions of the Boltzmann equation

Propagation of moments and derivatives

Theorem (7)

Given initial data $f_0(x, v)$ satisfying (4) (or in the case where hypothesis (H2) also holds, (5)). If in addition for integers k, ℓ, m the data satisfies

$$\sum_{|\kappa|\leq k, |\lambda|\leq \ell, |\mu|\leq m} \sup_{x\in\mathbb{T}^1} \int_{\nu\in\mathbb{R}^3} |\nu^{\kappa}| |\partial_{\nu}^{\lambda}\partial_{x}^{\mu}f_0(x,\nu)| \, d\nu dx < +\infty$$

then for all t > 0

$$\sum_{|\kappa| \leq k, |\lambda| \leq \ell, |\mu| \leq m} \sup_{x \in \mathbb{T}^1} \int_{v \in \mathbb{R}^3} |v^{\kappa}| |\partial_v^{\lambda} \partial_x^{\mu} f(x,v,t)| \, dv dx \leq \varphi_{k\ell m}(t) < +\infty$$

Walter Craig

Propagation of moments and derivatives

Theorem (7)

Given initial data $f_0(x, v)$ satisfying (4) (or in the case where hypothesis (H2) also holds, (5)). If in addition for integers k, ℓ, m the data satisfies

$$\sum_{|\kappa| \leq k, |\lambda| \leq \ell, |\mu| \leq m} \sup_{x \in \mathbb{T}^1} \int_{v \in \mathbb{R}^3} |v^{\kappa}| |\partial_v^{\lambda} \partial_x^{\mu} f_0(x, v)| \, dv dx < +\infty$$

then for all t > 0

$$\sum_{|\kappa| \leq k, |\lambda| \leq \ell, |\mu| \leq m} \sup_{x \in \mathbb{T}^1} \int_{v \in \mathbb{R}^3} |v^{\kappa}| |\partial_v^{\lambda} \partial_x^{\mu} f(x, v, t)| \, dv dx \leq \varphi_{k\ell m}(t) < +\infty$$

The growth rate is bounded by $c_{k\ell m} \exp(\exp(\sqrt{t/\beta}))$.

Walter Craig

Main ideas of the proof

 Using Duhamel's principle and the streaming flow, rewrite the Boltzmann equation as an integral equation

$$f(x, v, t) = f_0(x - tv, v) + \int_0^t Q(x - (t - s)v, v, s) \, ds$$

 Solutions satisfy the maximum principle: f₀(x, v) ≥ 0 implies f(x, v, t) ≥ 0 for t > 0
 Drop the Q⁻ term for the inequality

$$0 \le f(x, v, t) \le f_0(x - tv, v) + \int_0^t Q^+(x - (t - s)v, v, s) \, ds$$

• Integrate in $v \in \mathbb{R}^3$

$$0 \le \rho(x,t) \le \int_{v} f_0(x-tv,v) \, dv + \int_0^t \int_{v} Q^+ (x-(t-s)v,v,s) \, dv ds$$
(7)

Global solutions of the Boltzmann equation

The integrand in (7) involves a spherical integral through the part of the collision operator Q^+

$$\int_{v} Q^{+}(x - (t - s)v, v, s) dv$$

$$= \int_{v} \int_{v_{*}} \int_{\mathbb{S}_{\sigma}^{2}} f(x - (t - s)v, v') f(x - (t - s)v, v'_{*})$$

$$\times K(|v - v_{*}|, \frac{(v - v_{*})}{|v - v_{*}|} \cdot \sigma) dS_{\sigma} dv_{*} dv$$

$$= \int_{v} \int_{v_{*}} \int_{\mathbb{S}_{\sigma}^{2}} f(x - (t - s)v', v) f(x - (t - s)v', v_{*})$$

$$\times K(|v - v_{*}|, \frac{(v - v_{*})}{|v - v_{*}|} \cdot \sigma) dS_{\sigma} dv_{*} dv$$

where
$$v' = \frac{1}{2}((v + v_*) + |v - v_*|\sigma)$$

A smoothing property

In one dimensional geometries, the integral over $\sigma \in \mathbb{S}^2$ converts to a spatial integral over the interval $[v_{min}, v_{max}]$ where

$$v_{min} = \frac{1}{2}((v + v_*) \cdot e_1 - |v - v_*|)$$

$$v_{max} = \frac{1}{2}((v + v_*) \cdot e_1 + |v - v_*|)$$

Changing variables in the integral (assume for simplicity that $K(r, \xi) = 0$ for r > R)

$$\int_{v} Q^{+} (x - (t - s)v, v, s) \, dv \leq \frac{1}{t - s} \int_{-R(t - s)}^{R(t - s)} 4\pi K_0 \rho^2 (x + z, s) \, dz$$

Two estimates of the integrand

• The first estimate of the integrand is simply through $\|\rho\|_{L^{\infty}}$

$$\frac{1}{t-s} \int_{-R(t-s)}^{R(t-s)} 4\pi K_0 \rho^2(x+z,s) \, dz \le 8\pi K_0 R \|\rho\|_{L^{\infty}}^2$$

• The second estimate uses the relative entropy H(f|M)

$$\frac{1}{t-s} \int_{-R(t-s)}^{R(t-s)} 4\pi K_0 \rho^2(x+z,s) \, dz \le \frac{4\pi K_0 H(f|M)}{t-s} \frac{\|\rho\|_{L^{\infty}}}{\log(\|\rho\|_{L^{\infty}})}$$

Each one individually gives rise to an estimate which doesn't forbid blowup in finite time.

The integral inequality

Estimate the integrand by optimizing the two estimates Denote $|||f(x, v, t)||| = \varphi(t)$ and $\alpha = C_0 K_0 H(f_0|M)$

$$\varphi(t) \le \varphi(0) + \int_0^t \min\left\{c_1\varphi^2(s), \left(\frac{\alpha}{t-s} + c_2\right)\frac{\varphi(s)}{\log(\varphi(s))}\right\} ds \quad (8)$$

Theorem (8)

Global solutions of (8) *depend only upon* $\alpha \leq 1$ *.*

The constant c_1 depends upon ε , K_0 and $H(f_0|M)$, while c_2 depends upon the initial data.

The Bony functional

The proof of the second theorem under hypothesis (H2) is based on the Bony functional

$$b(t) = \int \int \int \int f(x,v,t)f(x,v_*,t)$$

$$\times K(|v-v_*|, \sigma \cdot (v-v_*)/|v-v_*|)|v-v_*|^2 dS_{\sigma} dv dv_* dx$$

which has the property that $\int_0^\infty b(t) dt < +\infty$

Using similar ideas in the case where (H2) holds, the integral inequality is

$$\varphi(t) \leq \varphi(0) + \int_0^t \min\left\{c_1\varphi^2(s), \left(\frac{1}{t-s} + 1\right)c_3b(s)\right\} ds \quad (9)$$

global existence

Proposition (9)

Given b(t), the maximal solution $\varphi(t)$ of the integral inequality (9) is a locally bounded function of t.

Furthermore the quantity $|||f(\cdot, t)||| \le \varphi(t)$. This implies global existence of a strong solution f(x, v, t)

However no rate of growth is available from this method, and indeed there may not be any quantitative rate.

Future directions

- Theorem (5) is restricted to one dimensional geometries. It is an open question whether Theorem (4) is so constrained.
- Can we relax the conditions (H1) on the collision kernel, possibly by using energy conservation.
- Does a similar theorem hold for nonelastic collisions (P. Degond). One of the difficult tendencies is for particles to coagulate (this is avoided precisely through hypothesis (H2) in our second category of results).
- Use Boltzmann-like kinetic equations to study homogeneous forms of dispersive nonlinear Hamiltonian partial differential equations