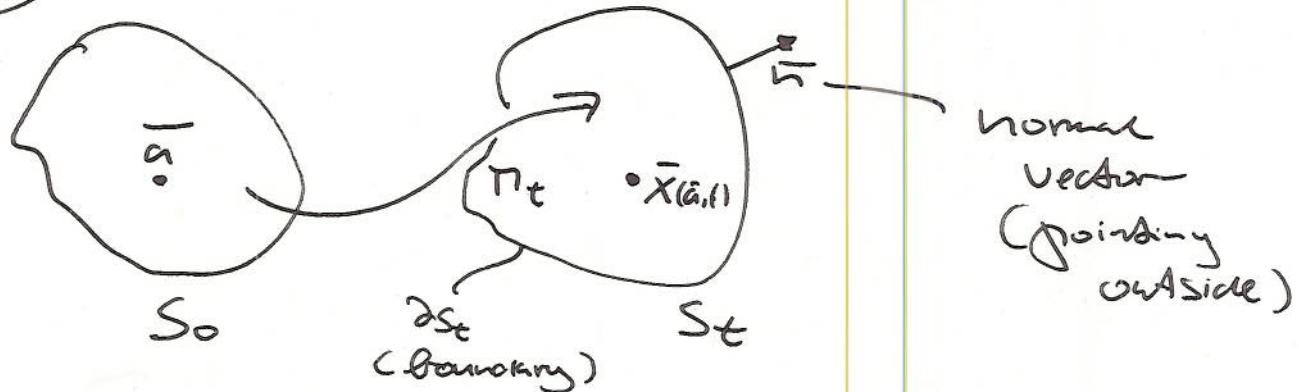


$$\int_A \bar{u} \cdot \bar{n} ds = \int_A \nabla^{\perp} \psi \cdot \bar{n} ds = \int_A \frac{\partial \psi}{\partial \bar{s}} ds =$$

$$= \int_A^B ds \psi = \psi_2 - \psi_1$$

* Reynolds Transport (Convection) Theorem



Let φ be a scalar function defined on the fluid region $\varphi: S_t \times [0, T] \rightarrow \mathbb{R}$

φ may represent some fluid property (e.g. density)

We are interested in the rate of change of

$$\int_{S_t} \varphi(x, t) d\omega(x)$$

with time

$d\omega(x)$ is the integration measure associated with the fluid domain S_t . Note that

$$d\omega(x) = dx_1 \cdots dx_N = \text{Det}(\mathbf{J}) da_1 \cdots da_N = \text{Det}(\mathbf{J}) d\omega_0$$

Suppose also that the flow map M_t is "driven" by the velocity field \bar{u} .

The difficulty in differentiating $\int_{S_t} \varphi d\omega(x)$ is that the domain S_t varies with time.

Theorem

$$\frac{d}{dt} \int_{S_t} g(\bar{x}, t) d\omega(\bar{x}) = \frac{d}{dt} \int_{S_0} g(\bar{x}(\bar{a}, t), t) \text{Det}(\mathbf{J}) d\omega_0$$
$$= \int_{S_0} \left[\frac{d g(\bar{x}(\bar{a}, t), t)}{dt} \text{Det}(\mathbf{J}) + g(\bar{x}(\bar{a}, t), t) \frac{d}{dt} \text{Det}(\mathbf{J}) \right] d\omega_0$$
$$= \int_{S_0} \left[\frac{d g(\bar{x}(\bar{a}, t), t)}{dt} + g \nabla \cdot \bar{u} \right] \text{Det}(\mathbf{J}) d\omega_0 = \begin{array}{|l} \text{transforming back to} \\ \text{the fluid region} \end{array}$$
$$= \int_{S_t} \left[\frac{df}{dt} + g \nabla \cdot \bar{u} \right] d\omega(\bar{x}) = \begin{array}{|l} \text{expanding using} \\ \text{② order product rule} \end{array}$$
$$= \int_{S_t} \left[\frac{\partial f}{\partial t} + u \cdot \nabla f + g \nabla \cdot \bar{u} \right] d\omega(\bar{x}) = \int_{S_t} \left[\frac{\partial f}{\partial t} + \nabla \cdot (\bar{u}f) \right] d\omega(\bar{x})$$
$$= \left| \begin{array}{l} \text{a. divergence} \\ \text{theorem} \end{array} \right| = \int_{S_t} \frac{\partial f}{\partial t} d\omega(\bar{x}) + \int_{\partial S_t} g (\bar{u} \cdot \bar{n}) d\sigma(\bar{x})$$

We have thus proven the following

Theorem

$$\frac{d}{dt} \int_{S_t} g(\bar{x}, t) d\omega(\bar{x}) = \underbrace{\int_{S_t} \frac{\partial f}{\partial t} d\omega(\bar{x})}_{\text{Change within the region } S_t} + \underbrace{\int_{\partial S_t} g (\bar{u} \cdot \bar{n}) d\sigma(\bar{x})}_{\text{Flux across the moving boundary}}$$

③
⑪

(Combining and using the divergence theorem

$$\int_{S_t} \left[\frac{\partial g}{\partial t} + \nabla \cdot (g \bar{u}) - q \right] d\sigma(\bar{x}) = 0$$

Since:

- g, \bar{u} and q are assumed sufficiently smooth and
- the region S_t is an arbitrary subset of \mathbb{R}^n

Conservation of mass is expressed as

$$\frac{\partial g}{\partial t} + \nabla \cdot (g \bar{u}) = q \quad \text{in } S_t$$

(4) OR

$$\frac{dg}{dt} + g(\nabla \cdot \bar{u}) = q \quad \text{in } S_t$$

Known as the equation of continuity

Thus, the density g may change as a result of

- Production / annihilation of mass (q)
- Compression of the fluid ($\nabla \cdot \bar{u}$)

Remark

If the fluid is incompressible ($\nabla \cdot \bar{u} = 0$),
~~then~~ and there are no sinks or sources of mass,
then $q = 0$

$$\frac{dg}{dt} = \frac{\partial g}{\partial t} + (\bar{u} \cdot \nabla) g = 0 \quad \text{in } S_t$$

$$(\nabla \cdot \bar{u} \neq 0) \quad \cancel{\Rightarrow} \quad g = \text{const.} \quad (\text{density } i)$$

Conserved only along particle trajectories, and particles may initially possess different density)

However,

$$g = \text{const} \quad \Rightarrow \quad \nabla \cdot \bar{u} = 0$$

* Lagrangian form

Suppose δ is a volume of size small enough, so that the mass gV in that volume is materially invariant

$$\frac{d}{dt}(gV) = 0$$

$$\frac{dS}{dt} V + g \frac{dV}{dt} = 0 \quad \Rightarrow \quad \frac{dS}{dt} + \frac{g}{V} \frac{dV}{dt} = 0 \quad \left. \right\} \Rightarrow$$

(4)

$$\nabla \cdot \bar{u} = \frac{1}{V} \frac{dV}{dt}$$

$$V = \text{Det}(\gamma) V_0 \quad \left. \right\} \Rightarrow \quad \nabla \cdot \bar{u} = \frac{1}{\text{Det}(\gamma)} \frac{d \text{Det}(\gamma)}{dt}$$

(for some initial volume V_0)

Therefore

$$\frac{dS}{dt} + g \nabla \cdot \bar{u} = \frac{dS}{dt} + \frac{g}{\text{Det}(\gamma)} \frac{d(\text{Det}(\gamma))}{dt}$$

$$= \frac{1}{\text{Det}(\gamma)} \frac{d}{dt} [g \text{Det}(\gamma)] = q$$

(14)

Remark

The Lagrangian form of the continuity equation is nonlinear in the flow properties ($\text{Det}(\mathbf{f})$)

Remark

Sometimes we are interested in the density per unit mass, rather than per unit volume, of a given conserved quantity. Then, in order to conjugate the amount of the quantity in the volume S_t we ~~will~~ need to multiply by \bar{g} , i.e.,

$$\int_{S_t} \bar{g} g d\omega(\bar{x})$$

Then (assuming $q=0$)

$$\begin{aligned} \frac{\partial}{\partial t} \int_{S_t} \bar{g} f d\omega(\bar{x}) &= \int_{S_t} \left[\frac{\partial(\bar{g} f)}{\partial t} + \nabla \cdot (\bar{g} \bar{u}) \right] d\omega \\ &= \int_{S_t} \underbrace{\left[f \frac{\partial \bar{g}}{\partial t} + \bar{g} \frac{\partial f}{\partial t} + f \cancel{\nabla} \cdot (\bar{g} \bar{u}) + \bar{g} \bar{u} \cdot \nabla f \right]}_{=0 \text{ (continuity)}} d\omega \end{aligned}$$

$$= \int_{S_t} \bar{g} \left(\frac{\partial f}{\partial t} + \bar{u} \cdot \nabla f \right) d\omega = \int_{S_t} \bar{g} \frac{df}{dt} d\omega$$

(Quite different formula than before)

(c) Conservation of Momentum

Momentum density (per unit volume): $\bar{g}\bar{u}$

Newton's second law of motion: The change of momentum of a mass of fluid is equal to the sum of forces acting on it

Assume: $\bar{q} \equiv 0$, \bar{F} - density (per unit volume)
of forces

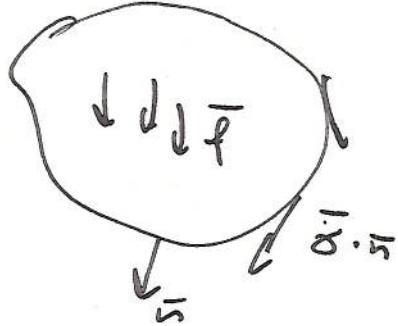
$$\frac{d}{dt} \left\{ \int_{S_t} \bar{g}\bar{u} d\omega \right\} = \int_{S_t} \bar{F} d\omega \quad \Rightarrow$$

$$\frac{d}{dt} \int_{S_t} \bar{g}\bar{u} d\omega = \int_{S_t} \bar{g} \frac{du}{dt} d\omega$$

(From previous remark with $\bar{g} = \bar{u}$)

$$\Rightarrow \int_{S_t} \bar{g} \frac{du}{dt} d\omega = \int_{S_t} \bar{F} d\omega \quad (*)$$

What about the forces \bar{F} ? This is what distinguishes different fluid models. We need a "constitutive relation" which relates the forces (slices of momentum) to other state variables and fluid properties



$$\int \bar{F} d\omega = \int_{S_t} \cancel{\bar{\sigma} \cdot \bar{n}} d\omega$$

$$\int_{S_t} \bar{f} d\omega + \int_{\partial S_t} \bar{\sigma} \cdot \bar{n} d\omega$$

body forces
 surface forces

$\bar{\sigma}$ - Stress tensor

Body Forces - e.g., gravity

$$\bar{f} = g \bar{g}$$

Surface Forces - pressure, frictional (viscous) forces

We are first focus on ideal fluids in which there are no frictional forces and the only surface forces are due to pressure, $\bar{\sigma} \cdot \bar{n} = -p \bar{n}$

Thus $\bar{\sigma} = -p \bar{I}$, or $\sigma_{ij} = -p \delta_{ij}$

identity matrix

and

$$\begin{aligned}
 \int_{S_t} \bar{F} d\omega &= \int_{S_t} g \bar{g} d\omega + \int_{\partial S_t} \bar{\sigma} \cdot \bar{n} d\omega \\
 &= \int_{S_t} g \bar{g} d\omega + \int_{S_t} \nabla \cdot \bar{\sigma} d\omega \\
 &= \int_{S_t} g \bar{g} + \int_{S_t} \nabla p d\omega
 \end{aligned}$$

Finally, from \oint and dropping integrals

$$\int_{S_t} g \frac{du}{dt} du = \int_{S_t} g \bar{g} du - \int_{S_t} \nabla p du$$

(5) $\frac{d\bar{u}}{dt} + \nabla p = g \bar{g}$ in S_t

which together with the continuity equation

$$\frac{dg}{dt} + g \nabla \cdot \bar{u} = 0$$

forms Euler's equations of fluid motion.

(N+1) equations vs. (N+2) state variables
 u_1, \dots, u_N, g, p

One equation is missing...

* compressible case - we need ~~one~~ an additional "equation of state" (a constitutive relation) $g = g(p, \dots)$ relating density to pressure and other parameters

* incompressible case $g = \text{const} \Rightarrow \nabla \cdot \bar{u} = 0$
~~g~~ is no longer an unknown
(WLOS $g=1$)

$$\left\{ \begin{array}{l} \frac{d\bar{u}}{dt} + \nabla p = \bar{g} \\ \nabla \cdot \bar{u} = 0 \end{array} \right.$$

Remark

Due to the constitutive relationship $\bar{\sigma} = -p\bar{J}$,
pressure is isotropic, i.e., acts in the same way
in all directions.

In incompressible fluids pressure σ is defined
up to a constant (this is not true in the
compressible case).