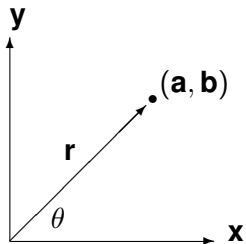


The complex plane



- $r = \sqrt{a^2 + b^2}$; this is called the modulus of the complex number $z = a + bi$ and written $|z|$.
- We saw that $z \cdot \bar{z} = |z|^2$.
- θ is an argument for $a + bi$ and is only determined up to multiples of 2π .
- $a = r \cos(\theta)$ and $b = r \sin(\theta)$ so $z = r(\cos(\theta) + i \sin(\theta))$.

A beautiful formula and a caveat going forward

- Exponentiation can be defined on complex numbers as follows:

$$e^{i\theta} = \cos(\theta) + i \sin(\theta)$$

- Consider then that if $\theta = \pi$ then

$$e^{i\pi} + 1 = 0$$

Linear algebra over the complex numbers

Everything we have done in the course to date - linear systems, matrices, determinants, eigenvalues, diagonalization - all goes through **unchanged** if we are using complex numbers instead of real numbers. Going forward it will be considered fair to have complex entries in matrices and to consider complex roots of polynomials.

Definition

- \mathbb{R}^n or real n -space is the collection of all n -tuples $v = (v_1, v_2, \dots, v_n)$ where $v_1, \dots, v_n \in \mathbb{R}$. We refer to elements of \mathbb{R}^n as vectors.

- We define addition between vectors in \mathbb{R}^n as follows:

$$(u_1, \dots, u_n) + (v_1, \dots, v_n) = (u_1 + v_1, \dots, u_n + v_n)$$

- Scalar multiples of vectors in \mathbb{R}^n is defined, for $r \in \mathbb{R}$ by

$$r(v_1, \dots, v_n) = (rv_1, \dots, rv_n)$$

- The vector $0 = (0, \dots, 0)$ is called the zero vector.
- Lots of interesting properties involving $+$, scalar multiplication and the zero vector contained in Theorem 3.1.1.
- If k_1, \dots, k_m are numbers and v_1, \dots, v_m are vectors then $k_1 v_1 + \dots + k_m v_m$ is a vector and is called a linear combination of v_1, \dots, v_m .
- The norm of a vector $v = (v_1, \dots, v_n)$, written $\|v\|$, is $\sqrt{v_1^2 + \dots + v_n^2}$ and there is a corresponding notion of distance $d(u, v) = \|u - v\|$.

Theorem (3.2.1)

For $v \in \mathbb{R}^n$,

- $\|v\| \geq 0$
- $\|v\| = 0$ iff $v = 0$
- $\|kv\| = |k|\|v\|$

Definition

For two vectors $u = (u_1, \dots, u_n)$ and $v = (v_1, \dots, v_n)$ in \mathbb{R}^n we define the dot product

$$(u_1, \dots, u_n) \cdot (v_1, \dots, v_n) = u_1 v_1 + \dots + u_n v_n$$

and the angle θ between non-zero vectors u and v by

$$\cos(\theta) = \frac{u \cdot v}{\|u\| \|v\|}$$

The geometry of \mathbb{R}^n , cont'd

- Theorems 3.2.2 and 3.2.3 have many valuable parts; I draw your attention to the part which says: for a vector v , $v \cdot v \geq 0$ and $v \cdot v = 0$ iff $v = 0$.
- Theorem 3.2.4, the Cauchy-Schwartz inequality says that for all vectors $u, v \in \mathbb{R}^n$, $|u \cdot v| \leq \|u\| \|v\|$.
- This allows us to prove the triangle inequality: for all vectors $u, v \in \mathbb{R}^n$, $\|u + v\| \leq \|u\| + \|v\|$.
- Theorems 3.2.6 and 3.2.7 express in n -space two geometric results: for all vectors $u, v \in \mathbb{R}^n$,

$$\|u + v\|^2 + \|u - v\|^2 = 2(\|u\|^2 + \|v\|^2) \text{ and}$$

$$u \cdot v = \frac{1}{4} \|u + v\|^2 - \frac{1}{4} \|u - v\|^2$$