

## lecture 17.

We are moving on to chapter 8.

### General Linear Transformations.

- Recall that for an  $m \times n$  matrix  $A$ , we have a map  
$$T_A: \mathbb{R}^n \rightarrow \mathbb{R}^m$$

defined by  $T_A(\vec{v}) = A\vec{v}$ . which has the following linearity properties:

$$T_A(\vec{u} + \vec{v}) = T_A(\vec{u}) + T_A(\vec{v}), \quad T_A(k\vec{v}) = k T_A(\vec{v})$$

- In fact, for any map  $T: \mathbb{R}^n \rightarrow \mathbb{R}^m$  satisfying these linear properties, there is an  $m \times n$  matrix such that  $T = T_A$ . (How to do this?).
- From here we can define more general linear transformations.

Definition: Let  $V, W$  be  $V$  spaces. A map  $T: V \rightarrow W$  is called a linear map iff it satisfies the following two properties for all  $\vec{u}, \vec{v} \in V$  and all scalars  $k$ :

1) (Homogeneity)  $T(k\vec{u}) = k T(\vec{u})$ .

$$2) \text{ (Additivity) } T(\vec{u} + \vec{v}) = T(\vec{u}) + T(\vec{v}).$$

If  $W = V$ , then  $T: V \rightarrow V$  is called a linear operator on  $V$ .

• Note that, combining these two properties

$$T(c_1 \vec{v}_1 + \dots + c_n \vec{v}_n) = c_1 T(\vec{v}_1) + \dots + c_n T(\vec{v}_n).$$

Theorem: Let  $T$  be a linear transformation.

$$\text{Then } 1) T(\vec{0}) = \vec{0}.$$

$$2) T(\vec{v} - \vec{u}) = T(\vec{v}) - T(\vec{u}).$$

Pf: Easy.  $\square$

Examples:

i) matrix transforms.

ii) The zero map:  $T(\vec{v}) = \vec{0} \quad \forall \vec{v}$ .

iii) The map  $T: P_n \rightarrow P_{n+1}$  defined by

$$T(p(x)) = x p(x).$$

is linear.

iv) Let  $\vec{v} \in \mathbb{R}^n$ . Define a map  $\mathbb{R}^n \rightarrow \mathbb{R}$

$$\text{by } \langle \cdot, \vec{v} \rangle: \mathbb{R}^n \rightarrow \mathbb{R} \\ : \vec{u} \mapsto \langle \vec{u}, \vec{v} \rangle.$$

(maps from  $\mathbb{R}^n \rightarrow \mathbb{R}$  are called linear functionals).

Theorem: Let  $T: V \rightarrow W$ . Let  $S = \{\vec{v}_1, \dots, \vec{v}_n\}$  be a basis of  $V$ . Then for any  $\vec{v} \in V$ , we can express the image as

$$T(\vec{v}) = c_1 T(\vec{v}_1) + \dots + c_n T(\vec{v}_n)$$

for some constants  $c_1, \dots, c_n$ .

In other words,  $T$  is determined by how it acts on a basis!

Proof: use linearity and properties of basis.  $\square$

Ex: Let  $V = C^1(-\infty, \infty)$  the space of continuously differentiable functions. Then

$$\begin{aligned} D: V &\rightarrow C^0(-\infty, \infty) \\ &: f(x) \mapsto \frac{d}{dx} f(x). \end{aligned}$$

is a linear map.

Definition: Let  $T: V \rightarrow W$  be a linear map.

The kernel of  $T$  is

$$\ker(T) = \{\vec{v} \in V : T(\vec{v}) = \vec{0}\}.$$

The range of  $T$  is the set

$$R(T) = \{\vec{w} \in W \mid (\exists \vec{v} \in V) T(\vec{v}) = \vec{w}\}.$$

Ex: What is  $\ker(D)$ ,  $D: C'[-2, 2] \rightarrow C[-2, 2]$   
( $D(f) = 0$ ,  $f$  is differentiable, so  $f = c$  a constant).

Theorem Let  $T: V \rightarrow W$  be a linear map.

- 1)  $\ker(T)$  is a subspace of  $V$ .
- 2)  $R(T)$  is a subspace of  $W$ .

Pf: 1).  $\ker(T) \subseteq V$ , so we need only to check that it's closed under addition and scalar multiplication.

↳ Let  $\vec{u}, \vec{v} \in \ker(T)$ . Then

$$\begin{aligned} T(\vec{u} + \vec{v}) &= T(\vec{u}) + T(\vec{v}) \\ &= \vec{0} + \vec{0} = \vec{0}. \end{aligned}$$

so  $\vec{u} + \vec{v} \in \ker(T)$ .

↳ Let  $\vec{v} \in \ker(T)$ ,  $k$  a scalar. Then

$$T(k\vec{v}) = kT(\vec{v}) = k\vec{0} = \vec{0}.$$

so  $k\vec{v} \in \ker(T)$ .

Hence  $\ker(T)$  is a subspace.

2)  $R(T) \subseteq W$ , so we only need to check that  $R(T)$  is closed under addition and scalar multiplication.

↳ Let  $\vec{w}_1, \vec{w}_2 \in R(T)$ .

↳ By definition, there are  $\vec{v}_1, \vec{v}_2 \in V$  such that  $T(\vec{v}_1) = \vec{w}_1$  and  $T(\vec{v}_2) = \vec{w}_2$ .

↳ then  
$$\vec{w}_1 + \vec{w}_2 = T(\vec{v}_1) + T(\vec{v}_2) \text{ by linearity}$$
$$= T(\vec{v}_1 + \vec{v}_2) \in R(T).$$

↳ Let  $\vec{w} \in R(T)$ ,  $k \in \text{scalars}$ .

↳ Since  $\vec{w} \in R(T)$  there is  $\vec{v} \in V$  such that  $T(\vec{v}) = \vec{w}$ .

↳ then  
$$k\vec{w} = kT(\vec{v}) \text{ by linearity}$$
$$= T(k\vec{v}) \in R(T).$$

So  $R(T) \subseteq W$  is a subspace.

□

Definition: Let  $T: V \rightarrow W$ . If  $\ker(T)$  is finite dimensional, then the nullity of  $T$  is defined to be  
$$\text{nullity}(T) = \dim(\ker(T)).$$

If  $R(T)$  is finite dimensional, then the rank of  $T$  is defined to be  
$$\text{rank}(T) = \dim(R(T)).$$

Important Theorem: (Rank-Nullity).

Let  $T: V \rightarrow W$  be a linear map with  $\dim(V) < \infty$  ( $W$  may have arbitrary dimension).

Then  $\dim(V) = \text{rank}(T) + \text{nullity}(T)$ .

Pf: Next time!