

19.1 Eigenvalues and Eigenfunctions

A Sturm-Liouville system consists of the information

$$(*) \quad \begin{aligned} & \frac{d}{dx} \left[r(x) \frac{dy}{dx} \right] + [\lambda p(x) - q(x)] y = 0 \quad a < x < b \\ & -l_1 y'(a) + h_1 y(a) = 0 \\ & l_2 y'(b) + h_2 y(b) = 0. \end{aligned}$$

- The last two equations are linear homogeneous boundary conditions
- $h_1, h_2, l_1, l_2 \in \mathbb{R}$ and independent of the parameter λ .
- The negative signs are simply a matter of convenience.

Think of the system as a family of differential equations dependent on the parameter λ . That is, for each λ , you get some differential equation which may or may not have solutions.

- $y \equiv 0$ is always a solution
- For certain λ , the system has non-trivial solutions. These λ are called eigenvalues, and there are always ∞ many (denoted by λ_n for $n=1, 2, 3, \dots$)
- A solution of the system corresponding to λ_n is denoted by $y_n(x)$ and is called an eigenfunction
- When $\lambda=0$ is an eigenvalue, we write $\lambda_0=0$ with eigenfunction $y_0(x)$.

Theorem: All eigenvalues of Sturm-Liouville system (*) are real, and eigenfunctions corresponding to distinct eigenvalues are orthogonal with respect to the weight function $p(x)$,

$$\int_a^b p(x) y_n(x) y_m(x) dx = 0$$

This is similar to the language from linear algebra.
There, we are given an $n \times n$ matrix A and asked when a vector v satisfies

$$Av = \lambda v \quad (\text{or when does a linear transformation}$$

$$\Rightarrow Av - \lambda v = 0 \quad (\text{map a vector to a scalar multiple of itself}).$$

$$\Rightarrow (A - \lambda I_n)v = 0$$

$$\Rightarrow v \in \text{Ker}(A - \lambda I_n)$$

λ is called an eigenvalue and v an eigenvector.

- The ^{eigen}vectors corresponding to a fixed λ define an eigen space V_λ .

- Eigenvectors from distinct λ_i are linearly independent

- The linear transformation in general can be $\frac{d}{dx}$ applied to the vector space $C^1([a, b])$.

Vectors are functions, and we could have

$$\frac{d}{dx} e^{\lambda x} = \lambda e^{\lambda x}$$

so $e^{\lambda x}$ is an eigenvector (or an eigenfunction)

corresponding to λ .

Review of solutions to homogeneous linear ODEs with constant coefficients.

- Since the differential equation is linear, we can write

$$\phi(D)y = F(x)$$

$$\text{where } \phi(D) = (a_n D^{(n)} + \dots + a_1 D^{(1)} + a_0)$$

We call $\phi(m)$ the auxiliary equation.

Theorem: (i) If $\phi(m)=0$ has a real root m of multiplicity k , then a solution to the differential equation $\phi(D)y=0$ is

$$(C_1 + C_2 x + \dots + C_k x^{k-1}) e^{mx}$$

(ii) If $\phi(m)=0$ has a pair of complex conjugate roots $a \pm bi$ each of multiplicity k , then a solution is

$$e^{ax} [(C_1 + C_2 x + \dots + C_k x^{k-1}) \cos bx + (D_1 + D_2 x + \dots + D_k x^{k-1}) \sin bx]$$

To find a general solution, superpose all solutions from (i) and (ii)

For example, if $\phi(m) = (m-1)^2(m^2+1)$, then a general solution to the associated ODE is

$$y(x) = (C_1 + C_2 x) e^x + C_3 \cos x + C_4 \sin x$$

$$\text{where } m=1 \text{ or } m=\overset{a}{\cancel{\pm}} i = \overset{b}{\cancel{0}} \pm 1i$$

19.2 Special Sturm-Liouville Systems

For computations needed in chapter 21, we restrict to the special case of $r(x)=1$, $p(x)=1$ and $q(x)=0$.

The differential equation we will be considering is

$$y'' + \lambda y = 0 \quad 0 < x < L$$

with 4 cases of boundary conditions. In each case, we need to consider subcases of $\lambda < 0$, $\lambda = 0$, $\lambda > 0$.

Cases: (1) $y(0) = y(L) = 0$, (2) $y'(0) = y'(L) = 0$,
 (3) $y(0) = y'(L) = 0$, (4) $y'(0) = y(L) = 0$.

$\lambda < 0$: We can write $\lambda = -\alpha^2$ where $\alpha > 0$

$y'' - \alpha^2 y = 0$ has $m^2 - \alpha^2 = 0$ as its auxiliary equation

There are two roots, $m = \pm \alpha$, so the general solution is

$$y(x) = C_1 e^{\alpha x} + C_2 e^{-\alpha x}$$

The boundary conditions in each case require

$$(1) \underbrace{C_1 + C_2 = 0}_{C_1 = -C_2}, \underbrace{C_1 e^{\alpha L} + C_2 e^{-\alpha L} = 0}_{C_2(e^{-\alpha L} - e^{\alpha L}) = 0} \Rightarrow C_1 = C_2 = 0.$$

So there are no nontrivial solutions in this case, so λ cannot be an eigenvalue when $\lambda < 0$.

$$(2) \underbrace{\alpha C_1 - \alpha C_2 = 0}_{\Rightarrow C_1 = C_2}, \underbrace{C_1 \alpha e^{\alpha L} - C_2 \alpha e^{-\alpha L} = 0}_{C_1 \alpha (e^{\alpha L} - e^{-\alpha L}) = 0} \Rightarrow C_1 = C_2 = 0$$

Similarly for (3) and (4) $\therefore \lambda < 0$ cannot be an eigenvalue.

$\lambda = 0$: The auxiliary equation for $y'' = 0$ is $m^2 = 0$, so there is a double root.

Then $y(x) = (C_1 + C_2 x)e^{0x} = C_1 + C_2 x$ ← we could have just used the Fundamental Theorem of Calculus to find this.

The boundary conditions imply:

$$(1) C_1 + 0 = 0, C_1 + C_2 L = 0 \Rightarrow C_2 = 0 = C_1$$

$$(2) C_2 = 0, C_2 = y'(L) = 0 \Rightarrow C_2 = 0$$

C_1 is free, so $y(x) = C_1$ is a nontrivial solution for $C_1 \neq 0$, and $\lambda = 0$ is an eigenvalue.

$$(3) C_1 = 0, C_2 = y'(L) = 0 \Rightarrow C_1 = C_2 = 0$$

$$(4) C_1 + C_2 L = 0, C_2 = 0 \Rightarrow C_1 = C_2 = 0.$$

$\lambda > 0$: The auxiliary equation for $y'' + \lambda^2 y = 0$

has $m^2 + \lambda^2 = 0$ where $\lambda = \alpha^2$, $\alpha > 0$.

This has two complex roots, $\pm \alpha i$, and a general solution is:

$$y(x) = e^{\alpha x} [C_1 \cos \alpha x + C_2 \sin \alpha x]$$

The boundary conditions imply

$$(1) 0 = y(0) = C_1, 0 = y(L) = C_1 \cos \alpha L + C_2 \sin \alpha L$$

$$\Rightarrow C_2 \sin \alpha L = 0.$$

If $C_2 = 0$, then we wouldn't have a nontrivial solution.

Instead, observe that $\sin \alpha L = 0$ if

$$\alpha L = n\pi \text{ for } n \in \mathbb{Z}$$

$$\Rightarrow \alpha = \frac{n\pi}{L} \Rightarrow \lambda = \alpha^2 = \frac{n^2\pi^2}{L^2}$$

Then $\lambda_n = \frac{n^2\pi^2}{L^2}$ for $n > 0$ are eigenvalues

corresponding to eigenfunctions $Y_n(x) = C_2 \sin\left(\frac{n\pi x}{L}\right)$

- We call $[\lambda_n, Y_n(x)]$ an eigenpair, and it is clear that $[\lambda_n, cY_n(x)]$ is also an eigenpair for $c \neq 0$ (The equations in the system are homogeneous.)
- It is customary to omit the constant C_2 from $Y_n(x)$ since it is understood that $Y_n(x) = \sin\left(\frac{n\pi x}{L}\right)$ is not unique, and any nonzero scalar multiple is also a solution.

$$(2) y'(x) = -\alpha C_1 \sin \alpha x + \alpha C_2 \cos \alpha x$$

Then $0 = y'(0) = \alpha C_2 \Rightarrow C_2 = 0$ since $\alpha > 0$
 $0 = y'(L) = -\alpha C_1 \sin \alpha L + \alpha C_2 \cos \alpha L$
 $\Rightarrow \alpha C_1 \sin \alpha L$

To get nontrivial solutions, we need $\alpha L = n\pi \quad n \in \mathbb{Z}$

Then $\lambda_n = \alpha^2 = \frac{n^2\pi^2}{L^2} \quad n > 0, \quad Y_n(x) = \cos\left(\frac{n\pi x}{L}\right)$

are eigenpairs for this system

$$(3) 0 = y(0) = C_1$$
$$0 = y'(L) = -\alpha C_1 \sin(\alpha L) + \alpha C_2 \cos(\alpha L)$$

$$\Rightarrow \alpha C_2 \cos \alpha L = 0$$

For there to be nontrivial solutions, we need

$$\alpha L = \pi / \frac{2}{2} - n\pi = \frac{\pi(1-2n)}{2} \quad n \in \mathbb{Z}$$

use - so that index can start at $n = 1$,

$$\Rightarrow \alpha = \frac{\pi(1-2n)}{2L}$$

$$\Rightarrow \lambda = \alpha^2 = \frac{(2n-1)^2 \pi^2}{4L^2}$$

$$\text{Then } \lambda_n = \frac{(2n-1)^2 \pi^2}{4L^2}, \quad n \geq 1, \quad y_n(x) = \sin\left(\frac{(2n-1)\pi x}{2L}\right)$$

are eigenpairs for each n for this system.

$$(4) \quad 0 = y'(0) = \alpha c_2 \Rightarrow c_2 = 0$$

$$0 = y(L) = C_1 \cos \alpha L + C_2 \sin \alpha L$$

$$\Rightarrow \cos \alpha L = 0$$

$$\Rightarrow \alpha L = \frac{\pi}{2} - n\pi \quad n \in \mathbb{Z}$$

$$\text{Then } \lambda_n = \frac{(2n-1)^2 \pi^2}{4L^2}, \quad n \geq 1, \quad y_n(x) = \cos\left(\frac{(2n-1)\pi x}{2L}\right)$$

In summary:

Boundary Conditions

Eigenvalues

Eigenfunctions

$$y(0) = y(L) = 0 \quad \frac{n^2 \pi^2}{L^2}, \quad n \geq 1 \quad y_n(x) = \sin \frac{n\pi x}{L}$$

$$y'(0) = y'(L) = 0 \quad \frac{n^2 \pi^2}{L^2}, \quad n \geq 0 \quad y_n(x) = \cos \frac{n\pi x}{L}$$

$$y(0) = y'(L) = 0 \quad \frac{(2n-1)^2 \pi^2}{4L^2}, \quad n \geq 1 \quad y_n(x) = \sin \frac{(2n-1)\pi x}{2L}$$

$$y''(0) = y(L) = 0 \quad \frac{(2n-1)^2 \pi^2}{4L^2}, \quad n \geq 1 \quad y_n(x) = \cos \frac{(2n-1)\pi x}{2L}$$

* This includes the $\lambda_0 = 0$ eigenvalue case where

$$y_0(x) = 1$$

- Since each $y_n(x)$ is a function coming from a Fourier series, by 18.2, we can expand any piecewise smooth function on $0 < x < L$ in terms of eigenfunctions of a Sturm-Liouville system.

- Is this true of any Sturm-Liouville

Theorem: • $p, q, r, r' , (pr)'' \in C^0([a, b])$ with $p, r > 0$ on $[a, b]$
• $l_1, l_2, h_1, h_2 \in \mathbb{R}$ independent of λ .

Then (1) The Sturm-Liouville system has many eigenvalues
 $\lambda_1 < \lambda_2 < \dots$, all real, with only finitely
many which are negative, and $\lim_{n \rightarrow \infty} \lambda_n = \infty$.

(2) If f is piecewise smooth on $[a, b]$, then on (a, b)

$$\frac{f(x+) + f(x-)}{2} = \sum_{n=1}^{\infty} c_n y_n(x)$$

where $c_n = \frac{1}{F_n} \int_a^b p(x) f(x) y_n(x) dx$

and $F_n = \int_a^b p(x) [f(x)]^2 dx$.

• In other words, we can expand any such f with a basis of functions for Sturm-Liouville systems, called eigenfunction expansions.

• We can also write $c_n = \frac{\langle f, y_n \rangle}{\|f\|^2} = \frac{\int_a^b p(x) f(x) y_n(x) dx}{\int_a^b p(x) [y_n(x)]^2 dx}$

Example: Expand $f(x) = 2x - 1$, $0 \leq x \leq 4$ in terms of eigenfunctions of the Sturm-Liouville system

$$y'' + \lambda y = 0, \quad 0 < x < 4 \\ y'(0) = 0 = y(4)$$

$L=4$, and by the table $y_n(x) = \frac{\cos((2n-1)\pi x)}{8} \quad n \geq 1$

$$c_n = \frac{2}{4} \int_0^4 (2x-1) y_n(x) dx$$

$$= \frac{1}{2} \left\{ \left[\frac{(2x-1) \sin\left(\frac{(2n-1)\pi x}{8}\right)}{(2n-1)\pi} \cdot 8 \right] \Big|_0^4 - \int_0^4 2 \sin\left(\frac{(2n-1)\pi x}{8}\right) \frac{8}{(2n-1)\pi} dx \right\}$$

$$= \frac{4}{(2n-1)\pi} \left[7 \sin\left(\frac{(2n-1)\pi}{2}\right) \right] - \frac{8}{(2n-1)\pi} \left(-\cos\left(\frac{(2n-1)\pi x}{8}\right) \frac{8}{(2n-1)\pi} \right) \Big|_0^4$$

$$= \frac{4}{\pi^2 (2n-1)^2} \left[7(-1)^{n+1} (2n-1)\pi - 16 \right]$$

$$\Rightarrow 2x-1 = \frac{4}{\pi^2} \sum_{n=1}^{\infty} \left[\frac{7(2n-1)\pi(-1)^{n+1} - 16}{(2n-1)^2} \right] \cos\left(\frac{(2n-1)\pi x}{8}\right)$$

on $0 < x < 4$

$$\text{Position } 0^\circ \text{ at } x = 0 \\ \text{Position } 60^\circ \text{ at } x = 2$$