

1ZC3 ENGINEERING MATH II-B (Linear Algebra I)

(ws¹⁹)
(c03) Lecture 9

Last Time

Big Theorem about Invertibility

The following statements are equivalent for any $n \times n$ A:

- (1) A is invertible.
 - (2) The only solution to the system $A\bar{x} = \bar{0}$ is $\bar{x} = \bar{0}$.
 - (3) The RREF of A is I_n .
 - (4) A is a product of elementary matrices.
 - (5) For all \bar{b} , the system $A\bar{x} = \bar{b}$ is consistent.
 - (6) For all \bar{b} , the system $A\bar{x} = \bar{b}$ has exactly 1 solution.
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Fact Let $A, B \in n \times n$. If $AB = I$, then
A, B are invertible (with $A^{-1} = B$, $B^{-1} = A$
and $BA = I$).

Why? We'll show B invertible, by showing the only
solution to $B\bar{x} = \bar{0}$ is $\bar{x} = \bar{0}$.

Suppose we have \bar{x} with $B\bar{x} = \bar{0}$.

$$A(B\bar{x}) = A(\bar{0}) = \bar{0}$$

$$I\bar{x} = \bar{0} \Rightarrow \bar{x} = \bar{0}$$

So B is invertible. \leftarrow
Since $AB = I$ & B^{-1} exists $\Rightarrow ABB^{-1} = B^{-1}$.

In a similar way (using (1) & (2) in the Big Theorem) we can show:

Fact If A, B are $n \times n$ and AB is invertible then so are A and B . (Hint: start with B)

Recall To find the inverse of a matrix A we reduced A to its RREF R :

$$[A \mid I] \longrightarrow [R \mid B]$$

If $R = I$, then $B = A^{-1}$.

If $R \neq I$, then A not invertible.

↳ R has row of zeros so R not invertible.

$$= E_k E_{k-1} \dots E_1 A$$

↖ all E_i are invertible

So A not invertible.

Matrix Polynomials

Example Let $A = \begin{bmatrix} 5 & -1 \\ -2 & 3 \end{bmatrix}$

We can for example compute

$$A^2 = \begin{bmatrix} 27 & -8 \\ -16 & 11 \end{bmatrix} \quad \text{or} \quad 8A = \begin{bmatrix} 40 & -8 \\ -16 & 24 \end{bmatrix}$$

& so if $p(x) = x^2 - 8x + 13$ then
it makes sense to talk about $p(A) = A^2 - 8A + 13I$
(for any constant c replace with cI).]

$$\begin{aligned} p(A) &= \begin{bmatrix} 27 & -8 \\ -16 & 11 \end{bmatrix} - \begin{bmatrix} 40 & -8 \\ -16 & 24 \end{bmatrix} + \begin{bmatrix} 13 & 0 \\ 0 & 13 \end{bmatrix} \\ &= \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix} \end{aligned}$$

We say A is a root of $p(x)$.

$$A = \begin{bmatrix} 5 & -1 \\ -2 & 3 \end{bmatrix} \quad \& \quad p(x) = x^2 - 8x + 13$$

Notice $\text{tr}(A) = 8$ $\det(A) = 5(3) - (-1)(-2)$
 $= 13$

Fun Fact : If $A = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$, then A is

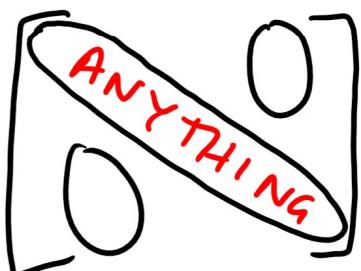
a root of $x^2 - \text{tr}(A)x + \det(A)$
 $x^2 - (a+d)x + (ad - bc)$

Question for later : How does this relate to inverses?

1.7 Special Kinds of Square Matrices :

Diagonal, Triangular, Symmetric

Diagonal $A = [a_{ij}]$ is diagonal if $a_{ij} = 0$ for $i \neq j$



e.g. $\begin{bmatrix} 5 & 0 & 0 \\ 0 & -2 & 0 \\ 0 & 0 & 1 \end{bmatrix} = I_3$

$$\begin{bmatrix} 3 & 0 \\ 0 & 0 \end{bmatrix}$$

If A, B are diagonal $n \times n$, then $A + B$ and $k \overset{\text{scalar}}{\uparrow} A$ are also diagonal.

If A diagonal $n \times n$ & B is any $n \times n$ matrix

then $AB = \begin{bmatrix} a_{11} & 0 & \dots & 0 \\ 0 & a_{22} & & \vdots \\ \vdots & & \ddots & 0 \\ 0 & 0 & \dots & a_{nn} \end{bmatrix} \begin{bmatrix} b_{11} & b_{12} & \dots & b_{1n} \\ \vdots & \vdots & \ddots & \vdots \\ b_{n1} & b_{n2} & \dots & b_{nn} \end{bmatrix}$

$$= \begin{bmatrix} a_{11}b_{11} & a_{11}b_{12} & \dots & a_{11}b_{1n} \\ a_{nn}b_{n1} & a_{nn}b_{n2} & \dots & a_{nn}b_{nn} \end{bmatrix}$$

(Scale rows of B by corresponding entry of A .)

Likewise BA has columns of B scaled by corresponding entry of A .

e.g.

$$\begin{bmatrix} 3 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 2 & 5 \\ -6 & 1 \end{bmatrix} = \begin{bmatrix} 6 & 15 \\ -6 & 1 \end{bmatrix}$$

$\times 3$

$$\begin{bmatrix} 2 & 5 \\ -6 & 1 \end{bmatrix} \begin{bmatrix} 3 & 0 \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} 6 & 0 \\ -18 & 1 \end{bmatrix}$$

$\times 1$

In particular if A and B are both diagonal

$$AB = \begin{bmatrix} a_{11}b_{11} & & & 0 \\ & a_{22}b_{22} & & \dots & 0 \\ 0 & & \ddots & & a_{nn}b_{nn} \end{bmatrix} \quad \leftarrow \text{in particular, it's diagonal}$$

Also $A^k = \begin{bmatrix} a_{11}^k & & & 0 \\ & a_{22}^k & & \dots & 0 \\ 0 & & \ddots & & a_{nn}^k \end{bmatrix}$ if A diagonal.

If A diagonal AND invertible, then

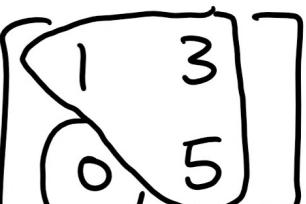
$$A^{-1} = \begin{bmatrix} \frac{1}{a_{11}} & & & 0 \\ 0 & \frac{1}{a_{22}} & & \dots & 0 \\ & & \ddots & & \frac{1}{a_{nn}} \end{bmatrix}$$

If A is diagonal, A is invertible exactly when all $a_{ii} \neq 0$.

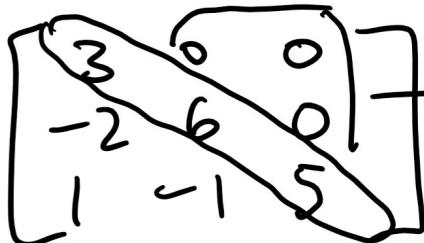
e.g. $\begin{bmatrix} 2 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & -1 \end{bmatrix}$ ✓ is invertible

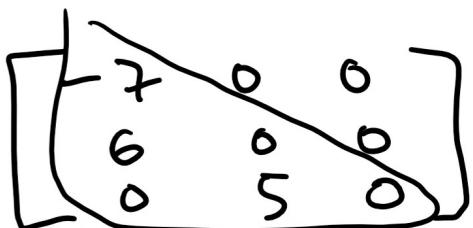
$\begin{bmatrix} 2 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix}$ ✗ not invertible

Triangular \rightarrow Upper Triangular $a_{ij}=0$ if $i>j$
 \rightarrow Lower Triangular $a_{ij}=0$ if $i<j$

e.g.  \Rightarrow U.T.

below diagonal all 0

 above diagonal all 0 \Rightarrow L.T.

 L.T.

$\begin{bmatrix} 1 & 0 \\ 0 & 3 \end{bmatrix} \rightarrow$ U.T. L.T. Diagonal