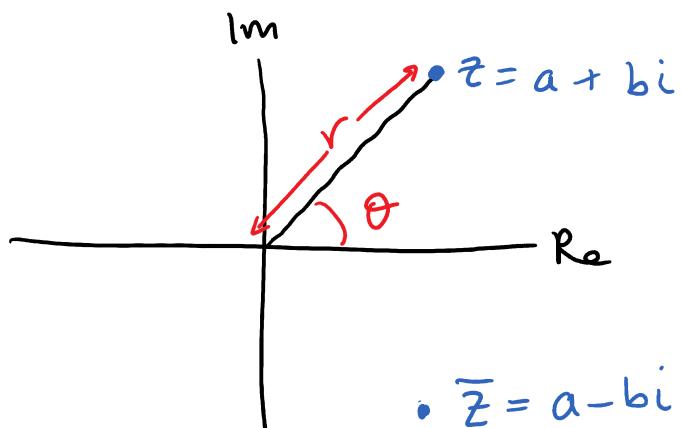


Last time: Review of complex numbers! ①



Modulus:

$$r = \sqrt{a^2 + b^2} = |z| \\ = \sqrt{z\bar{z}}$$

Argument:

$$\theta = \arctan\left(\frac{b}{a}\right)$$

$$z = r(\cos(\theta) + i\sin(\theta)) = re^{i\theta}$$

Review of vector spaces

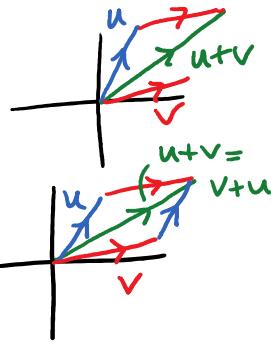
- collections of objects that interact with one another

the same way vectors do (in the following sense):

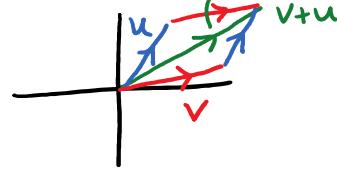
- V - objects
 - $+$ -
 - $k \cdot$ - for each scalar k
- These are specified/
named/defined.
- this*

V is a vector space (with addition $+$ and scalar multiplication $k \cdot$ for each k) if the following axioms are all true:

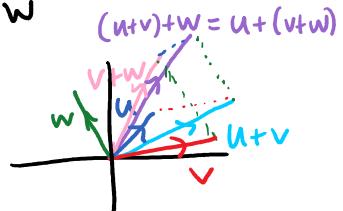
1. If u, v in V , then $u+v$ is in V



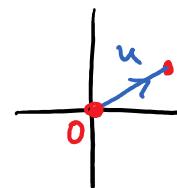
2. If u, v in V , then $u+v = v+u$



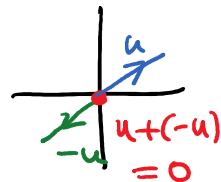
3. If u, v, w in V , then $u+(v+w) = (u+v)+w$



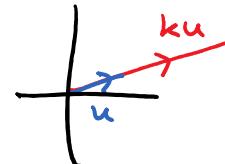
4. There is an object in V , called 0 , with the property that $0+u=u$ (for any u in V)



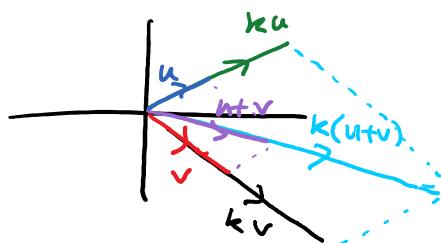
5. If u is in V , then there is some object in V , called $-u$, with the property that $u+(-u)=0 \leftarrow$ special object from 4.



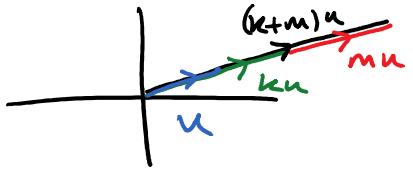
6. If k is a scalar and u is in V then ku is in V .



7. If k is a scalar and u, v in V then $k(u+v) = ku + kv$



8. If k, m are scalars and u in V ,
then $(k+m)u = ku + mu$



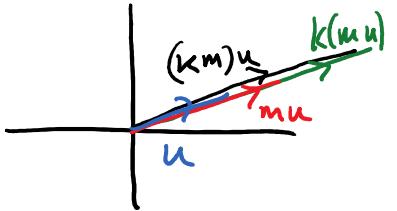
9. If k, m are scalars and u in V

then $(km)u = k(mu)$

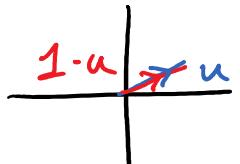
(and notice this is $m(ku)$)

$$= (mk)u = (km)u$$

scalar multiplication



10. If u is in V , then $\underset{\text{scalar}}{1} \cdot u = u$



We said this in class: the scalars can be reals or can be complex numbers. We fix a choice of scalars: \mathbb{R} or \mathbb{C} . Then our vector space is respectively a real v.s. or a complex v.s.

A note about the pictures: special case
where $V = \mathbb{R}^2$ and scalars are in \mathbb{R}

Examples

1. \mathbb{R}^n and \mathbb{C}^n are vector spaces.

→ What about the scalars?

$(V =) \mathbb{R}^n$ is a real^{scalars} vector space but NOT a complex vector space e.g. $i(5, 6, 1) = (5i, 6i, i)$
 \downarrow scalars Axiom 6 fails for \mathbb{R}^3 .

~~For~~ \mathbb{C}^n is a complex vector space

AND a real vector space

(any complex vector space is also a real vector space)

↳ if the axioms hold for all complex# scalars, they automatically hold for all real # scalars, since reals are also complex numbers! From now on just say "complex v.s." (not both).

2. $M_{m \times n}(\mathbb{R})$ — $m \times n$ matrices with real entries
— real v.s.

$M_{m \times n}(\mathbb{C})$ — " " " complex entries
— complex v.s.

3. Zero v.s. $\{0\}$; + defined by $0 + 0 = 0$

$$k0 \quad " \quad " \quad k0 = 0 \uparrow$$

is a complex vector space.

We have to define them both to equal 0 as this is the only choice possible.

4. Set of all polynomials of degree at most d
- $$a_0 + a_1 x + \dots + a_d x^d$$
- is a real v.s. if a_i real
complex v.s. if a_i complex
- (irrelevant where x lives
- we don't evaluate the polynomials)
5. The set of all $\overset{\text{complex}}{\text{real}}$ -valued functions defined on $\overset{\text{C}}{\mathbb{R}}$
is a $\overset{\text{real}}{\text{real}}$ v.s. where $f+g$ is the function
defined by $(f+g)(x) = f(x) + g(x)$ for all x
and kf is the function defined by $(kf)(x) = kf(x)$
for all k real, for all x
- i.e. this is two definitions in one : "real" everywhere $\xrightarrow{\text{complex}}$ real vector space
or "complex" everywhere $\xrightarrow{\text{real}}$ complex vector space.
6. The set of infinite sequences $\{a_n\}_{n \in \mathbb{N}}$
of real (respectively complex) numbers is a
real ("") v.s. when we
define $\{a_n\} + \{b_n\} = \{a_n + b_n\} = a_0 + b_0, a_1 + b_1, \dots$
and $k \{a_n\} = \{ka_n\} = k a_0, k a_1, \dots$

Check out Example 8 , p. 188 in textbook.

Non-examples

highest exponent of the terms
with non-zero
coefficients.

1. Set of polynomials of degree 3

$$2 - 5x^2 + 6x^3$$

$$1 + 3x + 2x^2 - 6x^3$$

Sum: $3 + 3x - 3x^2$ NOT of degree 3 so
Axiom 1 fails

Not a real vector space.

2. The set \mathbb{R}^2 with + as usual but

"scalar multiplication" $k(u_1, u_2) = (ku_1, 0)$

(Why is this NOT a v.s.? Axiom 10...)

Subspaces W , a subset of vector space V , is
a subspace of V if $W \subseteq V$ and W is a v.s.
with the same + and scalar multiplication as in V .

Theorem $W \subseteq V$, V a v.s., is a subspace if

- ① W is not empty.
- ② If u, v are in W , then $u+v$ is also in W .
(W is "closed under addition")
- ③ If k scalar, u in W , then ku is in W .
(W is "closed under scalar multiplication")

Examples 1. Any plane through the origin in \mathbb{R}^3
(real subspace)

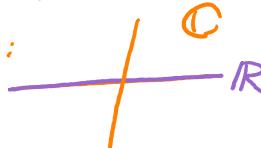
2. $\{0\}$ is a subspace of any vector space
 V is a subspace of itself for any vector space V

3. If W_1, \dots, W_n are subspaces of V , then so is
 $W_1 \cap \dots \cap W_n$, their intersection.

4. If A is a $m \times n$ matrix, then $\{x \in \mathbb{C}^n \mid Ax = 0\}$
is a subspace of \mathbb{C}^n the kernel of A

5. The set of all polynomials of degree at most d
with complex coefficients is a subspace of the
v.s. of complex valued functions.

6. (Example & Not-an-Example) I was asked during class:
Is \mathbb{R}^n a subspace of \mathbb{C}^n ? Two answers:

(a) As a complex vector space : YES e.g. we think
of \mathbb{R} as a line through the origin sitting inside \mathbb{C} : 

(b) As a real vector space : NO ; $\textcircled{3}$ from the
Theorem fails for the same reason that \mathbb{R}^n is
not a complex vector space (see #1 Examples of
Vector Spaces above : $i \underbrace{(a,b,c)}_{\in \mathbb{R}^3} = \underbrace{(ai, bi, ci)}_{\text{NOT in } \mathbb{R}^3}$).

Linear independence & spanning

When we have a set of vectors $S = \{v_1, \dots, v_r\}$

We can make new vectors: linear combinations

$$k_1 v_1 + k_2 v_2 + \dots + k_r v_r \quad k_i \text{ all scalars}$$

Collection of all linear combinations like this from S is the Span of S $\text{span}(S)$

If the only way to get 0 is by taking all k_i to be 0 , we say S is linearly independent

If there is some solution to the equation

$$k_1 v_1 + \dots + k_r v_r = 0 \quad \text{other than } k_i = 0 \quad \text{for all } i=1, \dots, r$$

then we say S is linearly dependent.

Bases & Dimension \vee a vector space

S is a set of vectors

S is a basis for V if ① S is linearly independent

$$\textcircled{2} \quad \text{span}(S) = V \quad ("S \text{ spans } V")$$

If V has a finite basis S , then it is called finite dimensional & all bases of V have the same size as S , called the dimension of V .

If V does not have a finite basis, then it is called infinite dimensional.

All definitions (span, lin. ind., basis, dim.) do not depend on whether scalars are real or complex.

1. The set $\{(1,0), (0,1)\}$ is a basis for \mathbb{C}^2 as a complex vector space.

i.e. it is lin. independent and we can obtain every $(z_1, z_2) \in \mathbb{C}^2$ as a linear combination of $(1,0)$ and $(0,1)$ because $(z_1, z_2) = z_1 \cdot (1,0) + z_2 \cdot (0,1)$.

So \mathbb{C}^2 has dimension 2 as a complex vector space.

But $\{(1,0), (0,1)\}$ is NOT a basis for \mathbb{C}^2 as a real vector space. If we can only use real #'s as scalars we cannot e.g. reach $(1,0)$ as a linear combination of $(1,0), (0,1)$.

We need e.g. $\{(1,0), (i,0), (0,1), (0,i)\}$.
(as a basis for \mathbb{C}^2 as a real v.s. - where only real scalars are allowed)

So as a real vector space, \mathbb{C}^2 is 4-dimensional.
(Just like complex plane \mathbb{C} is 2-dim. as a real vector space.)

We write complex #'s as $a+bi$, a linear combination of 1 and i with real scalars!

$$2. \left\{ \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix} \right\}$$

is the standard basis for $M_2(\mathbb{R})$ as a real vector space and $M_2(\mathbb{C})$ as a complex V.S.

Remember: Theorem (4.5.3 in textbook) (+/-)

S non-empty set of vectors in V.S. V

+ 1. If S is lin. independent and v in V lies outside $\text{span}(S)$, then $\text{span}(S) \cup \{v\}$ is lin. independent.

- 2. If v in S , $v = k_1 v_1 + \dots + k_r v_r$ with k_i scalar
then $\text{span}(S) = \text{span}(S \setminus \{v\})$ and v_i in S
 \uparrow without v .

Finally coordinates: if $S = \{v_1, \dots, v_r\}$ is a basis for a u.s. V ,

then every v in V can be written as $k_1 v_1 + \dots + k_r v_r$ for some unique choice of scalars k_1, \dots, k_r call these the coordinates of v relative to the basis S .

Dot products

This is all supposed to be very hesitant—
you really shouldn't be thinking of
multiplying vectors!

In (only) one sense we do have a way (sort of) of multiplying vectors: dot product in \mathbb{R}^n

If $u = (u_1, \dots, u_n)$ are vectors in \mathbb{R}^n , their dot product is

$$u \cdot v = \{u_1 v_1 + \dots + u_n v_n\}$$

We also have a definition of a dot product in \mathbb{C}^n . If $u = (u_1, \dots, u_n)$ are vectors in \mathbb{C}^n ,
 $v = (v_1, \dots, v_n)$

the dot product is

$$u \cdot v = \{u_1 \bar{v}_1 + \dots + u_n \bar{v}_n\}. \quad \text{T.B.C.!}$$