

Lecture 7

Linear independence (Section 1.7)
(will return to Sec. 1.6)

Today's lecture: linear independence (key concept in linear alg.)

Defⁿ and Examples

Defⁿ A set of vectors $\{\vec{v}_1, \vec{v}_2, \dots, \vec{v}_p\}$ in \mathbb{R}^n is linearly independent if the vector equation

$$x_1 \vec{v}_1 + x_2 \vec{v}_2 + \dots + x_n \vec{v}_p = \vec{0} \quad (*)$$

has only the trivial solⁿ $x_1 = x_2 = \dots = x_n = 0$
If $(*)$ has a non-trivial solⁿ (some $x_i \neq 0$), then
 $\{\vec{v}_1, \dots, \vec{v}_p\}$ is linearly dependent.

Ex Show $\vec{v}_1 = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$ and $\vec{v}_2 = \begin{bmatrix} 0 \\ 2020 \end{bmatrix}$ are linearly independent

Look at solⁿs to

$$x_1 \begin{bmatrix} 1 \\ 0 \end{bmatrix} + x_2 \begin{bmatrix} 0 \\ 2020 \end{bmatrix} = \begin{bmatrix} x_1 \\ 2020x_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$\Leftrightarrow x_1 = 0 = x_2 \quad \leftarrow \text{only the trivial sol}^n$$

Ex Show $\vec{v}_1 = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$, $\vec{v}_2 = \begin{bmatrix} 1 \\ 2 \end{bmatrix}$, $\vec{v}_3 = \begin{bmatrix} 6 \\ 10 \end{bmatrix}$ are linearly dependent

Note $x_1 \begin{bmatrix} 1 \\ 0 \end{bmatrix} + x_2 \begin{bmatrix} 1 \\ 2 \end{bmatrix} + x_3 \begin{bmatrix} 6 \\ 10 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$

$$\Leftrightarrow \begin{bmatrix} 1 & 1 & 6 \\ 0 & 2 & 10 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 1 & 6 & : & 0 \\ 0 & 2 & 10 & : & 0 \end{bmatrix} \sim \begin{bmatrix} \textcircled{1} & 1 & 6 & & 0 \\ 0 & \textcircled{1} & 5 & & 0 \end{bmatrix} \quad \leftarrow x_3 \text{ is free!} \\ \Rightarrow \text{infinite \# of sol}^n$$

$$\sim \begin{bmatrix} 1 & 0 & 1 & & 0 \\ 0 & 1 & 5 & & 0 \end{bmatrix}$$

$$x_1 = -x_3$$

$$x_2 = -5x_3$$

So all solⁿs have form $\begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = x_3 \begin{bmatrix} -1 \\ -5 \\ 1 \end{bmatrix}$

So, a specific non-trivial solⁿ when $x_3 = 1$ gives $\begin{bmatrix} -1 \\ -5 \\ 1 \end{bmatrix}$

key observations Determining if $\{\vec{v}_1, \dots, \vec{v}_p\}$ in \mathbb{R}^n is linearly independent is equivalent to determining if the homog. s.l.e.

$$[\vec{v}_1 \dots \vec{v}_p] \vec{x} = \vec{0} \text{ has only trivial sol}^n$$

Defⁿ Given a matrix $A = [\vec{a}_1 \dots \vec{a}_n]$, columns of A are linearly independent if $\{\vec{a}_1, \dots, \vec{a}_n\}$ is linearly independent

columns of A are linearly independent

$$\Leftrightarrow [\vec{a}_1 \dots \vec{a}_n : \vec{0}] \text{ has only trivial sol}^n$$

$$\Leftrightarrow A\vec{x} = \vec{0} \text{ has only trivial sol}^n$$

Small sets of vectors and linear independence

Thm Let $S = \{\vec{v}_1, \dots, \vec{v}_p\}$

- ① If $\vec{0} \in S$, then S is linearly dependent.
- ② If $p=1$, and $\vec{v}_1 \neq \vec{0}$, then S linearly independent.
- ③ If $p=2$, $\vec{v}_1, \vec{v}_2 \neq \vec{0}$, and $\vec{v}_2 \neq c \cdot \vec{v}_1$ for any $c \in \mathbb{R}$, then S linearly independent.

Proof ① Suppose $\vec{0} \in S$, and say $\vec{v}_p = \vec{0}$. Then

$$0 \cdot \vec{v}_1 + 0 \cdot \vec{v}_2 + \dots + 0 \cdot \vec{v}_{p-1} + 1 \cdot \vec{v}_p = \vec{0}$$

is a non-trivial solⁿ. So S is linearly dependent.

② If $S = \{\vec{v}_1\}$, then $x_1 \vec{v}_1 = \vec{0}$ and $\vec{v}_1 \neq \vec{0}$, has only the solⁿ $x_1 = 0$ (i.e. trivial solⁿ)

③ (Proof by contradiction)

Suppose there was a non-trivial solⁿ

$$a \vec{v}_1 + b \vec{v}_2 = \vec{0}, \quad a \text{ and } b \text{ not both zero}$$

Assume $a \neq 0$. If $b = 0$, then $a \vec{v}_1 = \vec{0}$. This implies $\vec{v}_1 = \vec{0}$, but not allowed!

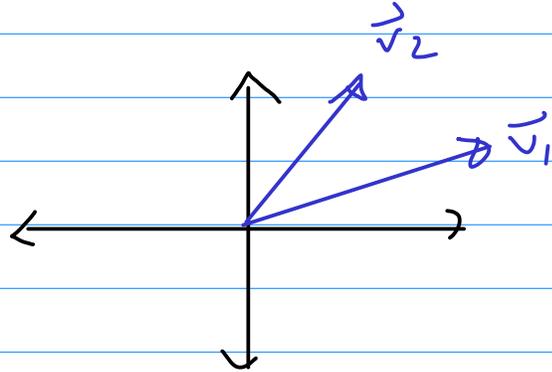
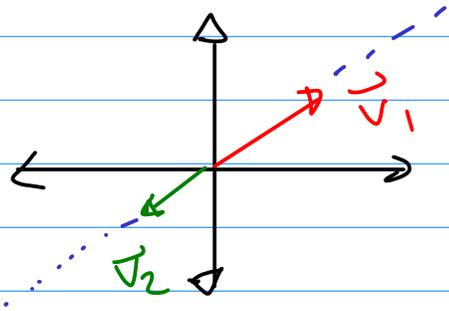
If $b \neq 0$, $a \vec{v}_1 = -b \vec{v}_2 \Rightarrow \vec{v}_1 = \left(\frac{-b}{a}\right) \vec{v}_2$, but not allowed!

So, \vec{v}_1 and \vec{v}_2 must be linearly independent. \square

Geometry

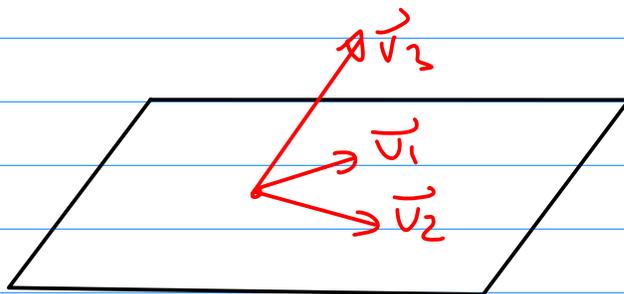
In \mathbb{R}^2 or \mathbb{R}^3 , if \vec{v}_1, \vec{v}_2 linearly dependent \Rightarrow on same line

if \vec{v}_1, \vec{v}_2 linearly independent \Rightarrow point in different directions



In \mathbb{R}^3 , $\vec{v}_1, \vec{v}_2, \vec{v}_3$ linearly dependent \Rightarrow all in same plane or same line

$\vec{v}_1, \vec{v}_2, \vec{v}_3$ linearly independent \Rightarrow no 3-vectors in same plane



Thm (more than 2 vectors) Let $S = \{\vec{v}_1, \dots, \vec{v}_p\}$ in \mathbb{R}^n
with $\vec{v}_1 \neq \vec{0}$.

Then S is linearly dependent if and only if exists
Some $j > 1$ such that $\vec{v}_j \in \text{Span}\{\vec{v}_1, \dots, \vec{v}_{j-1}\}$

Proof Note that statement has form "A if and only if B"

Need to show "if A, then B" and "if B, then A".

We will show

"If $\vec{v}_j \in \text{Span}\{\vec{v}_1, \dots, \vec{v}_{j-1}\}$, then S linearly dependent"

If $\vec{v}_j \in \text{Span}\{\vec{v}_1, \dots, \vec{v}_{j-1}\}$, then

$$\vec{v}_j = c_1 \vec{v}_1 + c_2 \vec{v}_2 + \dots + c_{j-1} \vec{v}_{j-1} \text{ for some } c_1, \dots, c_{j-1} \neq 0$$

But then

$$\vec{0} = c_1 \vec{v}_1 + c_2 \vec{v}_2 + \dots + c_{j-1} \vec{v}_{j-1} + (-1) \vec{v}_j \\ + 0 \vec{v}_{j+1} + \dots + 0 \vec{v}_p.$$

A non-trivial SL^n , so, vectors linearly dependent \square

Thm If $S = \{\vec{v}_1, \vec{v}_2, \dots, \vec{v}_p\}$ is a set of vectors in \mathbb{R}^n with $p > n$, then S is linearly dependent.

Proof Vector equation $x_1\vec{v}_1 + \dots + x_p\vec{v}_p = \vec{0}$ equivalent to SLE

$$\begin{bmatrix} \vec{v}_1 & \dots & \vec{v}_p \end{bmatrix} \begin{bmatrix} x_1 \\ \vdots \\ x_p \end{bmatrix} = \begin{bmatrix} 0 \\ \vdots \\ 0 \end{bmatrix} \iff \begin{cases} \begin{bmatrix} \vec{v}_1 & \dots & \vec{v}_p & \vdots & 0 \\ \vdots & & & \vdots & 0 \\ \vdots & & & \vdots & 0 \end{bmatrix} \end{cases}$$

$\underbrace{\hspace{10em}}_p$

Since $p > n$, cannot have a pivot in each column

\Rightarrow SLE has a free variable

\Rightarrow SLE has an infinite # of sol's

\Rightarrow vectors are linearly dependent

□

Ex $\left\{ \begin{bmatrix} 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 2 \end{bmatrix}, \begin{bmatrix} 6 \\ 10 \end{bmatrix} \right\}$ linear dependent since $p=3 > 2=n$

CAUTION If $S = \{v_1, \dots, v_p\}$ in \mathbb{R}^n is a set of vectors with $p \leq n$, then S may or may not be linearly independent.

Ex $\left\{ \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 2 \\ 2 \\ 2 \end{bmatrix} \right\}$ in \mathbb{R}^3 is not linearly independent
since $1 \cdot \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} - \frac{1}{2} \begin{bmatrix} 2 \\ 2 \\ 2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$

Ex $\left\{ \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} \right\}$ in \mathbb{R}^3 is linearly independent

- Key ideas:
- * defⁿ of linear independence
 - * connection to homog s.l.e.
 - * special cases of \vee linear dependence and linear independence.