| Lecture 34 | 5.5 Complex Eigenvalues/vectors |

Today: Geometry of 2x2 matrices with complex eigenvalues

| Complex eigenvalues and eigenvectors |

Def^n If A is an $n \times n$ complex matrix, a complex scalar λ is a complex eigenvalue if there is a nonzero vector $\vec{v} \in \mathbb{C}^n$ such that
$$A\vec{v} = \lambda \vec{v}.$$
Call $\vec{v}$ the complex eigenvector

$\leftarrow$ ha!

Recall over $\mathbb{R}^n$, eigenvectors correspond to "stretching"

Ex Let $A = \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix}$, and consider the

linear transformation $T: \mathbb{R}^2 \to \mathbb{R}^2$ given by $T(\vec{x}) = A\vec{x}$.

Show geometrically that A has no real eigenvalues

For any point $\begin{bmatrix} a \\ b \end{bmatrix} \in \mathbb{R}^2$, $\begin{bmatrix} a \\ b \end{bmatrix} \mapsto \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} a \\ b \end{bmatrix} = \begin{bmatrix} -b \\ a \end{bmatrix}$

Picture:

a linear transformation
of a rotation
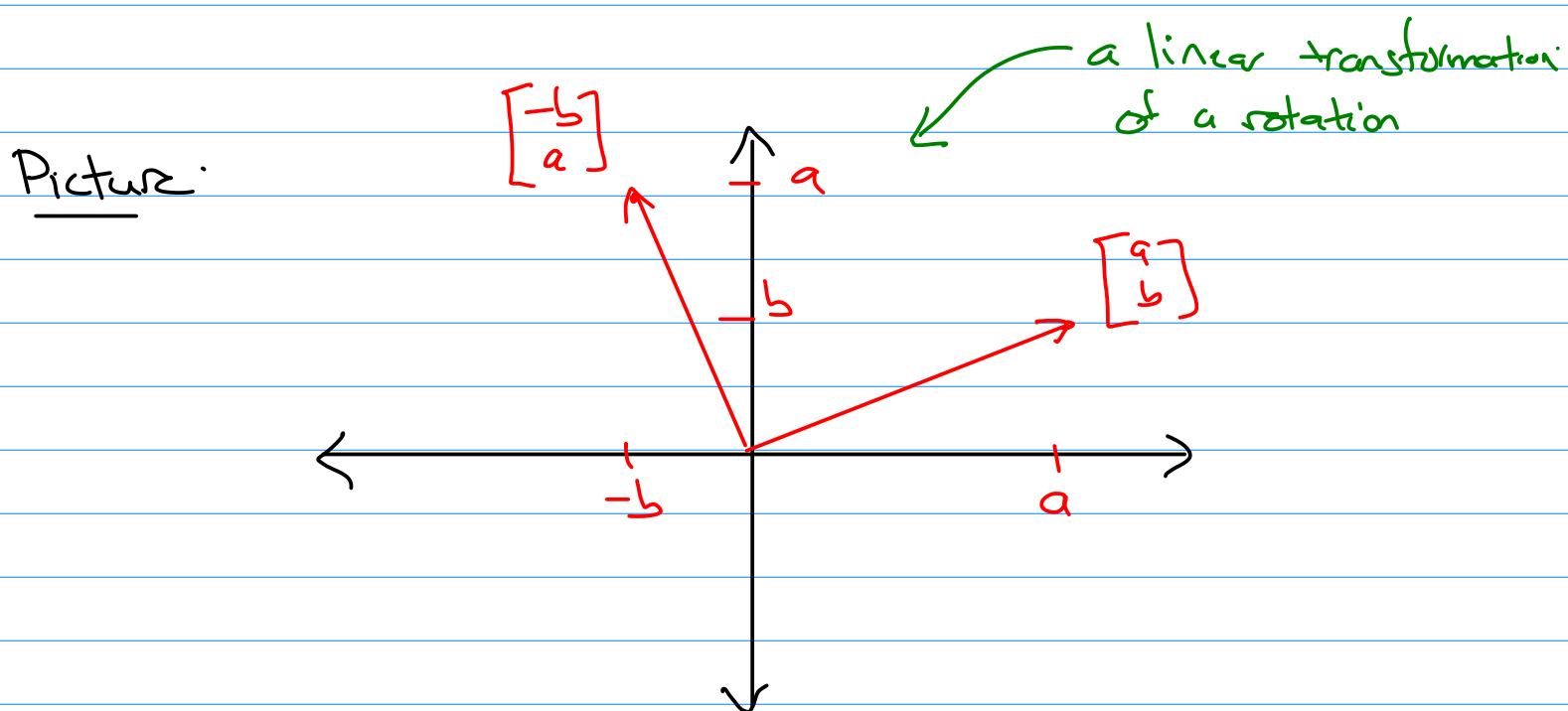
The matrix A has **no** real eigenvalues, since
every point is sent to a new direction

Indeed $\det(A - \lambda I_2) = \begin{vmatrix} -\lambda & -1 \\ 1 & -\lambda \end{vmatrix} = \lambda^2 + 1 = 0$

$$\iff \lambda = \pm i$$

BIG IDEA If $T: \mathbb{R}^2 \to \mathbb{R}^2$ is a linear transformation given by $T(\vec{x}) = A\vec{x}$ and A has complex eigenvalues, then T corresponds to a rotation.

Computing eigenvectors

conjugate of $z = a + bi \implies \bar{z} = a - bi$

Useful fact: Let A be an $n \times n$ real matrix. If λ is an eigenvalue of A with eigenvector $\vec{x}$, then $\bar{\lambda}$ is an eigenvalue of A with eigenvector $\bar{\vec{x}}$.

Proof Given $A\vec{x} = \lambda \vec{x}$. So

$$\overline{A\vec{x}} = \overline{A}\,\overline{\vec{x}} = \overline{\lambda}\,\overline{\vec{x}} = \overline{\lambda \vec{x}}$$

Since A is real, $\overline{A} = A$. So $A\overline{\vec{x}} = \overline{\lambda}\,\overline{\vec{x}}$, i.e $\overline{\lambda}$ is an eigenvalue with eigenvector $\overline{\vec{x}}$. $\boxed{}$

Problem Find eigenvectors of $A = \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix}$

Recall, eigenvalues $\lambda = i, -i$

$\boxed{\lambda = i}$

$A - i\lambda = \begin{bmatrix} -i & -1 \\ 1 & -i \end{bmatrix} \sim \begin{bmatrix} 1 & -i \\ 0 & 0 \end{bmatrix}$ So x_2 free

$x_1 - x_2 i = 0 \iff x_1 = i x_2$

eigenvalue is $\vec{v} = \begin{bmatrix} i x_2 \\ x_2 \end{bmatrix} = x_2 \begin{bmatrix} i \\ 1 \end{bmatrix} \implies$ an eigenvector of $\lambda = i$ is $\vec{v} = \begin{bmatrix} i \\ 1 \end{bmatrix}$

$\boxed{\lambda = -i}$ by thm $\overline{\vec{v}} = \overline{\begin{bmatrix} i \\ 1 \end{bmatrix}} = \begin{bmatrix} -i \\ 1 \end{bmatrix}$ is the

eigenvector of $\lambda = -i$

Ex $A = \begin{bmatrix} 1 & -2 \\ 1 & 3 \end{bmatrix}$ eigenvalue $\lambda = 2 + i$ with eigen vector $\vec{x} = \begin{bmatrix} 2 \\ -1-i \end{bmatrix}$

$\implies \overline{\lambda} = 2 - i$ is an eigenvalue with eigenvector $\begin{bmatrix} 2 \\ -1+i \end{bmatrix}$

Special case of 2x2 matrices

Thm If $C = \begin{bmatrix} a & -b \\ b & a \end{bmatrix}$ with a, b real,

then eigenvalues are $a \pm bi$

Polar form

If $\lambda = a + bi = |\lambda|(\cos\theta + i\sin\theta)$, then

$$C = \begin{bmatrix} |\lambda| & 0 \\ 0 & |\lambda| \end{bmatrix} \begin{bmatrix} \cos\theta & -\sin\theta \\ \sin\theta & \cos\theta \end{bmatrix}$$

Stretching

rotating by θ

Proof (first part only)

$$\det(C - \lambda I_2) = \begin{vmatrix} a-\lambda & -b \\ b & a-\lambda \end{vmatrix} = (a-\lambda)^2 + b^2 = 0$$

So $(a-\lambda)^2 = -b^2 \Rightarrow a-\lambda = \pm bi \Rightarrow a \pm ib = \lambda$

Ex $A = \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix}$ has form $\begin{bmatrix} a & -b \\ b & a \end{bmatrix}$ with $a = 0$, $b = 1$

Eigenvalues are $\lambda = 0 \pm 1i = \pm i$ ← as before

$\lambda = 0 + i \Rightarrow \lambda = |\lambda|\left(\cos\left(\frac{\pi}{2}\right) + i\sin\left(\frac{\pi}{2}\right)\right)$
$\qquad\qquad\qquad = 1\left(\cos\left(\frac{\pi}{2}\right) + i\sin\left(\frac{\pi}{2}\right)\right)$

So $A = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} \cos\left(\frac{\pi}{2}\right) & -\sin\left(\frac{\pi}{2}\right) \\ \sin\left(\frac{\pi}{2}\right) & \cos\left(\frac{\pi}{2}\right) \end{bmatrix}$

"stretch" by $\times 1$ $\qquad$ rotate by $\frac{\pi}{2} = 90°$

General case of 2×2 matrices

If A is a real 2×2 matrix with complex eigenvalues, has a nice decomposition.

Thm Let A be a real 2×2 matrix with complex eigenvalue $\lambda = a - bi$ and associated eigenvector $\vec{v} \in \mathbb{C}^2$. Then

$A = PCP^{-1}$ where $P = [\text{re}(\vec{v})\ \ \text{im}(\vec{v})]$
and $C = \begin{bmatrix} a & -b \\ b & a \end{bmatrix}$

a factorization of A

Ex $\quad A = \begin{bmatrix} 1 & -2 \\ 1 & 3 \end{bmatrix}$ $\qquad$ $\overset{\overset{a-bi}{\shortmid\shortmid}}{\lambda} = 2-i$ and $\vec{v} = \begin{bmatrix} 2 \\ -1+i \end{bmatrix}$

$P = [\operatorname{re}(\vec{v}) \ \operatorname{im}(\vec{v})] = \begin{bmatrix} 2 & 0 \\ -1 & 1 \end{bmatrix}$

So $\quad A = \begin{bmatrix} 2 & 0 \\ -1 & 1 \end{bmatrix} \begin{bmatrix} 2 & -1 \\ 1 & 2 \end{bmatrix} \begin{bmatrix} 2 & 0 \\ -1 & 1 \end{bmatrix}^{-1}$

Diagram

$$\vec{x} \xmapsto{\hspace{3cm}} A\vec{x}$$

P^{-1} $\downarrow$ $\qquad\qquad\qquad\uparrow$ $P\begin{bmatrix} 2 & -1 \\ 1 & 2 \end{bmatrix} P^{-1}\vec{x}$

change coordinates back

$$P^{-1}\vec{x} \xrightarrow{\begin{bmatrix} 2 & -1 \\ 1 & 2 \end{bmatrix}} \begin{bmatrix} 2 & -1 \\ 1 & 2 \end{bmatrix} P^{-1}\vec{x}$$

change of coordinates of $\mathbb{R}^2$ using P as our basis
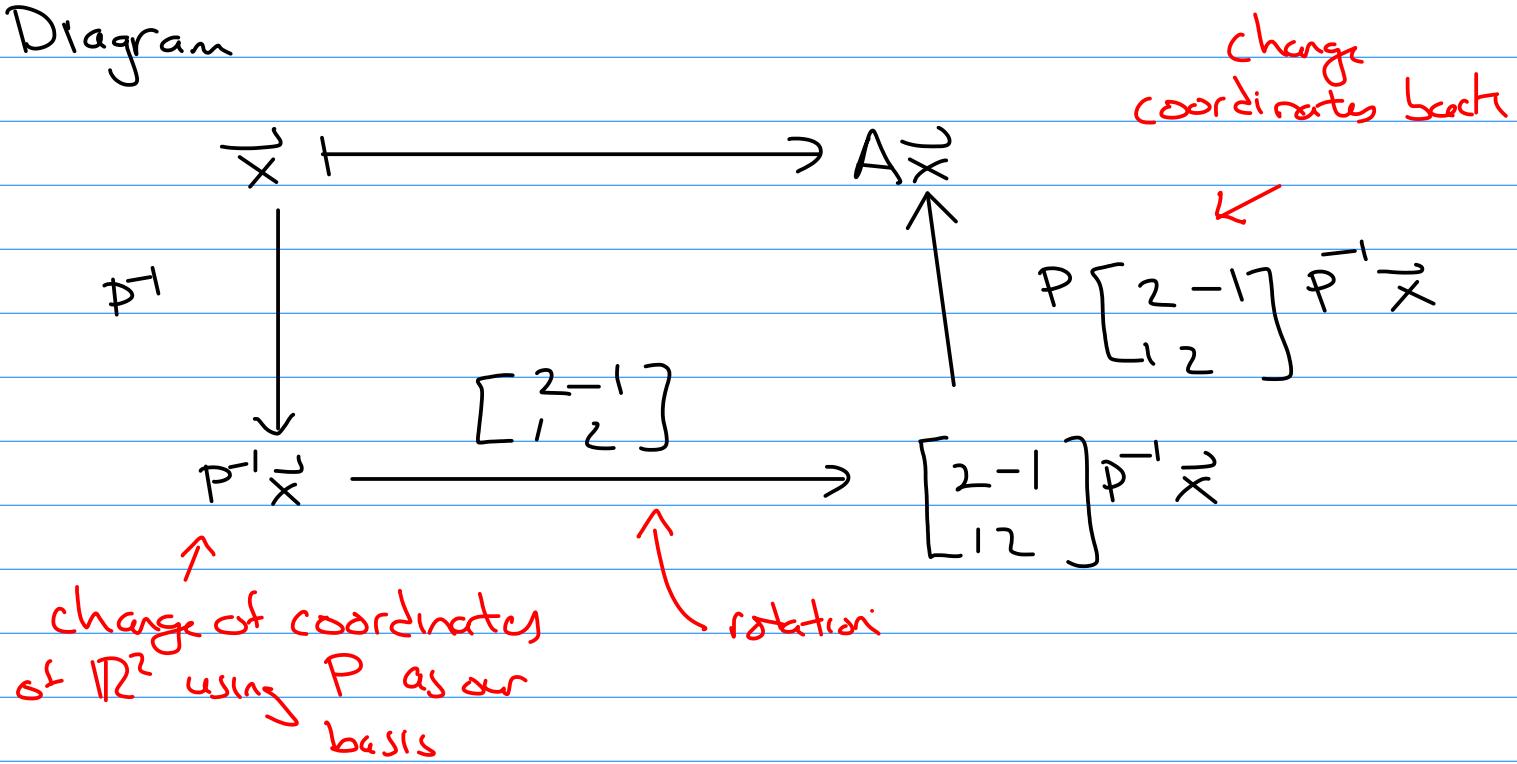
rotation

Key idea: 2×2 $\overset{\text{real}}{\wedge}$ matrices with complex eigenvalues $\implies$ rotations.