Lecture 6	Solution sets of linear equations
	(Section 1.5)

Today's lecture * homogeneous systems of linear equations
              * describe all sol's to a SLE as a span
                of vectors

Homogeneous linear systems

Zero vector

Def^n A s.l.e. is homogeneous if it has the form $A\vec{x} = \vec{0}$

A homogeneous s.l.e. always has at least one sol^n:

namely, $\vec{x} = \begin{bmatrix} 0 \\ 0 \\ \vdots \\ 0 \end{bmatrix}$ ← normally, called trivial sol^n

Ex homog s.l.e

$$x_1 + 3x_2 - 2x_3 = 0$$
$$-2x_1 - 5x_2 + 4x_3 = 0$$
$$-x_1 + 2x_2 + 2x_3 = 0$$

$$\iff \begin{bmatrix} 1 & 3 & -2 \\ -2 & -5 & 4 \\ -1 & 2 & 2 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

Fundamental Q for homog s.l.e.:

does a homog s.l.e have only the trivial sol⁰ (one sol⁰)
or an infinite # of sol⁰s?

Thm $A\vec{x} = \vec{0}$ has a non-trivial sol^n if and only if the system has at least one free variable

Ex (Con't)

$$\begin{bmatrix} 1 & 3 & -2 & : & 0 \\ -2 & -5 & 4 & : & 0 \\ -1 & 2 & 2 & : & 0 \end{bmatrix} \sim \begin{bmatrix} 1 & 3 & -2 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 5 & 0 & 0 \end{bmatrix} \sim \begin{bmatrix} 1 & 3 & -2 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

pivots x_3 is free variable

The homog S.l.e. has a nontrivial sol^n:
x_1, x_2 basic variables
x_3 free variable

Describe basic variables in terms of free variables:

$$x_1 + 3x_2 - 2x_3 = 0 \implies x_1 - 2x_3 = 0 \implies x_1 = 2x_3$$
$$x_2 = 0 \qquad\qquad x_2 = 0 \qquad\qquad x_2 = 0$$

So $\begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}$ is a sol^n to $A\vec{x} = \vec{0}$ if and only if

$$\vec{x} = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 2x_3 \\ 0 \\ x_3 \end{bmatrix} = x_3 \begin{bmatrix} 2 \\ 0 \\ 1 \end{bmatrix} \quad \leftarrow x_3 \in \mathbb{R}$$

Every sol^n of $A\vec{x} = \vec{0}$ "lives in"

$$\text{span}\left\{ \begin{bmatrix} 2 \\ 0 \\ 1 \end{bmatrix} \right\} = . \quad \left\{ c \begin{bmatrix} 2 \\ 0 \\ 1 \end{bmatrix} \mid c \in \mathbb{R} \right\}$$

Nonhomogeneous SLE

Def^n A s.l.e. is non-homogeneous if $A\vec{x} = \vec{b}$ with $\vec{b} \neq \vec{0}$

Ex Find all sol^{n}s to $A\vec{x} = \vec{b}$ when

$$A = \begin{bmatrix} 1 & 3 & -2 \\ -2 & -5 & 4 \\ -1 & 2 & 2 \end{bmatrix} \quad \text{and} \quad \vec{b} = \begin{bmatrix} 1 \\ 2 \\ 19 \end{bmatrix}$$

Sol^n

r.r.e.f

$$\begin{bmatrix} 1 & 3 & -2 & : & 1 \\ -2 & -5 & 4 & : & 2 \\ -1 & 2 & 2 & : & 19 \end{bmatrix} \sim \begin{bmatrix} 1 & 3 & -2 & : & 1 \\ 0 & 1 & 0 & : & 4 \\ 0 & 0 & 0 & : & 0 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & -2 & -11 \\ 0 & 1 & 0 & 4 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

x_1, x_2 are basic and x_3 is free
          variables   variable

Describe basic var. in terms of free var.

$$x_1 = -11 + 2x_3$$
$$x_2 = 4$$
$$x_3 = x_3$$

As a vector, sol^n to $A\vec{x}=\vec{b}$ has form

$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} -11 + 2x_3 \\ 4 \\ x_3 \end{bmatrix} = \begin{bmatrix} 2x_3 \\ 0 \\ x_3 \end{bmatrix} + \begin{bmatrix} -11 \\ 4 \\ 0 \end{bmatrix} = x_3 \begin{bmatrix} 2 \\ 0 \\ 1 \end{bmatrix} + \begin{bmatrix} -11 \\ 4 \\ 0 \end{bmatrix}$$

$$x_3 \in \mathbb{R}$$

Let $\vec{p} = \begin{bmatrix} -11 \\ 4 \\ 0 \end{bmatrix}$ and $\vec{v} = \begin{bmatrix} 2 \\ 0 \\ 1 \end{bmatrix}$. Sol^n has form

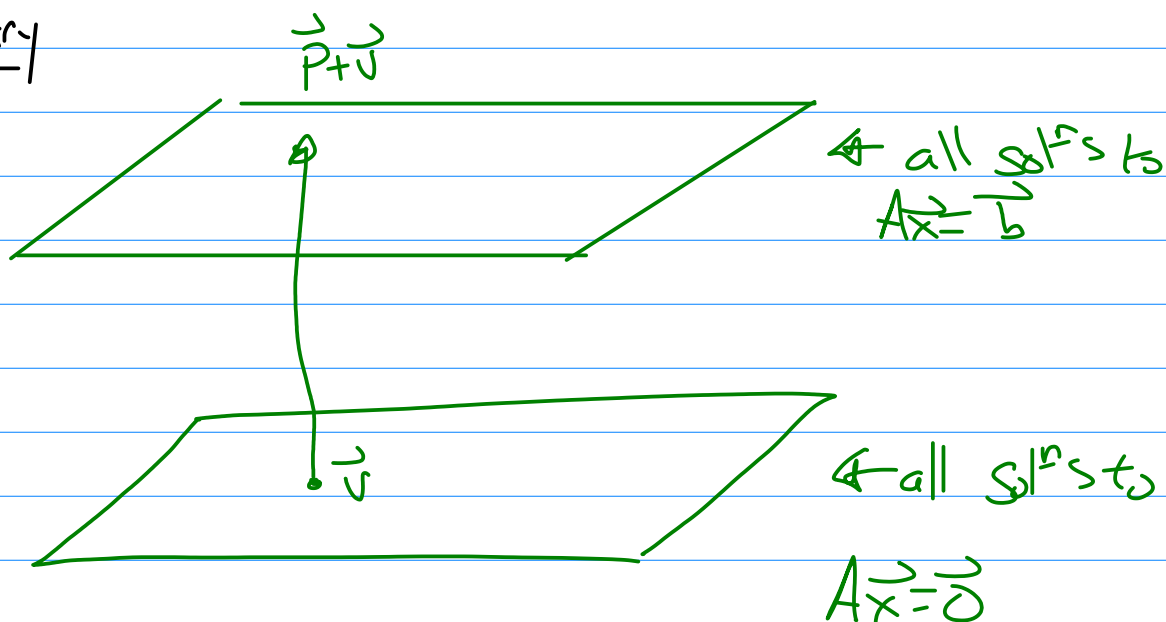$$\vec{x} = \vec{p} + c\vec{v} \text{ with } c \in \mathbb{R}$$

parametric form

Note $c\vec{v}$ is a sol^n to homog s.l.e. $A\vec{x}=\vec{0}$!!

$\boxed{Q}$ How are the solution sets of $A\vec{x} = \vec{0}$ and $A\vec{x} = \vec{b}$ related?

Thm Let $\vec{p}$ be any sol^n to $A\vec{x} = \vec{b}$. Then

$$B = \{\vec{w} \mid A\vec{w} = \vec{b}\} = \{\vec{p} + \vec{v} \mid \vec{v} \text{ any sol}^n \text{ to } A\vec{x} = \vec{0}\} = C$$

all sol^{n}s to $A\vec{x} = \vec{b}$

Geometry

← all sol^{n}s to $A\vec{x} = \vec{b}$

← all sol^{n}s to $A\vec{x} = \vec{0}$

Solution sets are "translations"

Consequence: to find all sol's to $A\vec{x}=\vec{b}$, find one sol^n
to $A\vec{x}=\vec{b}$ and add it to all sol's of $A\vec{x}=\vec{0}$.

Why? Want to show $B=C$

Need to show $B\subseteq C$ and $C\subseteq B$
 $\in$ B is a subset of C

Let $\vec{p}+\vec{v}\in C$. Then

$A(\vec{p}+\vec{v})=A\vec{p}+A\vec{v}=A\vec{p}+\vec{0}=\vec{b}$.
  So $\vec{p}+\vec{v}\in B$ So $C\subseteq B$

Let $\vec{w}\in B$. This means $A\vec{w}=\vec{b}$
So
   $A(\vec{w}+\vec{p}-\vec{p})=\vec{b}$.
Thus
     $A\vec{p}+A(\vec{w}-\vec{p})=\vec{b}$
So
     $\vec{b}+A(\vec{w}-\vec{p})=\vec{b} \implies A(\vec{w}-\vec{p})=\vec{0}$.

Thus $\vec{w}=\vec{p}+\underbrace{(\vec{w}-\vec{p})}$
                  a sol^n to $A\vec{x}=\vec{0}$.

So $B\subseteq C$.   So $B=C$.

Writing sol⁰'s in parametric form

① Row reduce augmented matrix to <u>reduced</u> <u>row</u> echelon form.

② Express each basic variable in terms of free variables

③ Express typical sol⁰ $\vec{x}$ as a vector whose entries depend upon free variables (if any)

④ Decompose $\vec{x}$ into linear combinations of vectors with numeric entries using free variables as parameters.

<u>Problem</u> Write sol⁰ to $A\vec{x}=\vec{b}$ in parametric form

$$A= \begin{bmatrix} 1 & -1 & -1 & 2 \\ 2 & -2 & -1 & 3 \\ -1 & 1 & -1 & 0 \end{bmatrix} \qquad \vec{b}= \begin{bmatrix} 1 \\ 3 \\ -3 \end{bmatrix}$$

<u>Step 1</u>
$$\begin{bmatrix} 1 & -1 & -1 & 2 & : & 1 \\ 2 & -2 & -1 & 3 & : & 3 \\ -1 & 1 & -1 & 0 & : & -3 \end{bmatrix} \sim \begin{bmatrix} ① & -1 & 0 & 1 & : & 2 \\ 0 & 0 & ① & -1 & : & 1 \\ 0 & 0 & 0 & 0 & : & 0 \end{bmatrix}$$

<u>Step 2</u>   basic variables $= x_1, x_3$
  free variables $= x_2, x_4$

$$x_3 - x_4 = 1 \implies x_3 = 1 + x_4$$
$$x_1 - x_2 + x_4 = 2 \implies x_1 = 2 + x_2 - x_4$$

Step 3 Typical solⁿ

$$\vec{x} = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} = \begin{bmatrix} 2 + x_2 - x_4 \\ x_2 \\ 1 + x_4 \\ x_4 \end{bmatrix}$$

Step 4

$$\vec{x} = \begin{bmatrix} 2 \\ 0 \\ 1 \\ 0 \end{bmatrix} + x_2 \begin{bmatrix} 1 \\ 1 \\ 0 \\ 0 \end{bmatrix} + x_4 \begin{bmatrix} -1 \\ 0 \\ 1 \\ 1 \end{bmatrix} \qquad x_2, x_4 \in \mathbb{R}$$

parametric form

Key ideas: * homogeneous vs. non-homogeneous
* parametric solⁿ sets