

Lecture 21

- Null Spaces, Column Spaces, and Linear Transformations (4.2)
- Linearly independent sets and bases (4.3)

Last time: The null space of a $m \times n$ matrix A :

$$\text{Nul}(A) = \{ \vec{x} \in \mathbb{R}^n \mid A\vec{x} = \vec{0} \} \subseteq \mathbb{R}^n \text{ (subspace)}$$

- Today:
- column space of A
 - linearly independent sets

Column Space

Recall: If $\vec{v}_1, \dots, \vec{v}_p$ any p vectors in \mathbb{R}^n ,

$\text{span}\{\vec{v}_1, \dots, \vec{v}_p\}$ is a subspace of \mathbb{R}^n

Defⁿ The column space of an $m \times n$ matrix A , denoted

$\text{Col}(A)$, is $\text{span}\{\vec{a}_1, \dots, \vec{a}_n\}$ where $A = [\vec{a}_1 \dots \vec{a}_n]$

Ex $A = \begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \end{bmatrix} \Rightarrow \text{Col}(A) = \text{span} \left\{ \begin{bmatrix} 1 \\ 4 \end{bmatrix}, \begin{bmatrix} 2 \\ 5 \end{bmatrix}, \begin{bmatrix} 3 \\ 6 \end{bmatrix} \right\}$

$$= \left\{ c_1 \begin{bmatrix} 1 \\ 4 \end{bmatrix} + c_2 \begin{bmatrix} 2 \\ 5 \end{bmatrix} + c_3 \begin{bmatrix} 3 \\ 6 \end{bmatrix} \mid c_1, c_2, c_3 \in \mathbb{R} \right\}$$

Thm $\text{Col}(A)$ is a subspace of \mathbb{R}^m

Note $\text{Col}(A) = \left\{ \vec{b} \mid x_1 \vec{a}_1 + x_2 \vec{a}_2 + \dots + x_n \vec{a}_n = \vec{b} \text{ for some } \right.$
 $\left. x_i \in \mathbb{R} \right\}$

$$= \left\{ \vec{b} \mid A \vec{x} = \vec{b} \text{ for some } \vec{x} \in \mathbb{R}^n \right\}$$

$$= \left\{ A \vec{x} \mid \vec{x} \in \mathbb{R}^n \right\}$$

In general, $\text{Col}(A) \subseteq \mathbb{R}^m$

Thm Let A be an $m \times n$ matrix

$$\text{Col}(A) = \mathbb{R}^m \Leftrightarrow A\vec{x} = \vec{b} \text{ has a sol}^n \text{ for all } \vec{b} \in \mathbb{R}^m$$

$$\Leftrightarrow A \text{ has a pivot in every row}$$

Comparing $\text{Col}(A)$ and $\text{Nul}(A)$

$\text{Col}(A)$ and $\text{Nul}(A)$ are different subspaces,
If A is $m \times n$

$$\cdot \text{Col}(A) \subseteq \mathbb{R}^m \quad \text{and} \quad \text{Nul}(A) \subseteq \mathbb{R}^n$$

(A) $\text{Nul}(A)$ defined implicitly \Rightarrow given a condition a vector must satisfy, i.e. $A\vec{x} = \vec{0}$.

$$\text{Col}(A) \text{ defined explicitly} \Rightarrow \text{Col}(A) = \text{span}\{\vec{a}_1, \dots, \vec{a}_n\}$$

(B) Typical $\vec{v} \in \text{Nul}(A)$ satisfies $A\vec{v} = \vec{0}$
Typical $\vec{v} \in \text{Col}(A)$ has property that the SLE $A\vec{x} = \vec{v}$ is consistent

(C) Given \vec{v} , "easy" to check if $\vec{v} \in \text{Nul}(A) \Rightarrow$ check $A\vec{v} = \vec{0}$.

"hard" to check if $\vec{v} \in \text{Col}(A) \Rightarrow$ need to solve $A\vec{x} = \vec{v}$

① $\text{Nul}(A) \supseteq \{\vec{0}\}$ and $\text{Nul}(A) = \{\vec{0}\} \Leftrightarrow$
 $A\vec{x} = \vec{0}$ has only trivial solⁿ

$\text{Col}(A) \subseteq \mathbb{R}^m$ and $\text{Col}(A) = \mathbb{R}^m \Leftrightarrow$
columns of A span \mathbb{R}^m

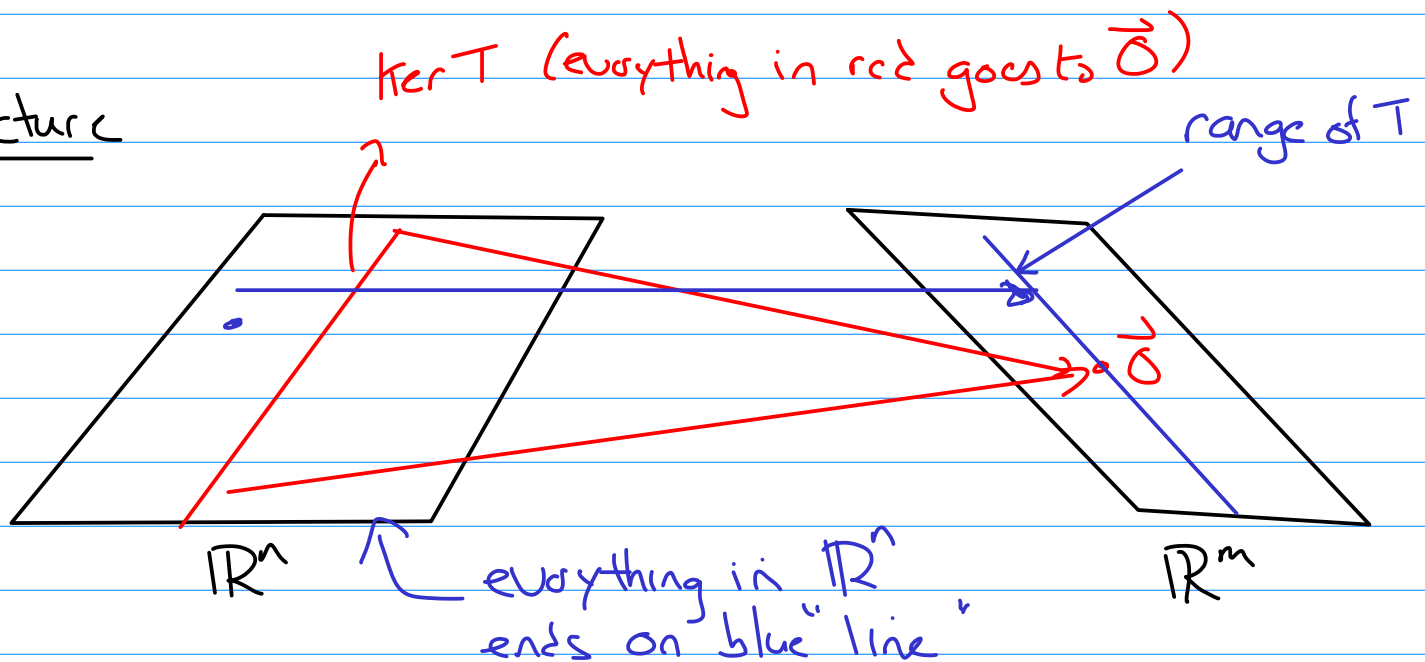
$\text{Nul}(A), \text{Col}(A)$ and linear transformations

Defⁿ Given a linear transformation $T: \mathbb{R}^n \rightarrow \mathbb{R}^m$

$\text{kernel of } T = \ker T = \{\vec{x} \in \mathbb{R}^n \mid T(\vec{x}) = \vec{0}\} \subseteq \mathbb{R}^n$

$\text{range of } T = \text{range } T = \{T(\vec{x}) \mid \vec{x} \in \mathbb{R}^n\} \subseteq \mathbb{R}^m$

Picture



Thm Let $T: \mathbb{R}^n \rightarrow \mathbb{R}^m$ be a linear transformation with standard matrix A , i.e. $T(\vec{x}) = A\vec{x}$.

Then (1) $\ker T = \{ \vec{x} \mid \vec{0} = T(\vec{x}) = A\vec{x} \} = \text{Nul}(A)$

(2) $\text{range } T = \{ T(\vec{x}) = A\vec{x} \mid \vec{x} \in \mathbb{R}^n \} = \text{Col}(A)$

Thm Let $T: \mathbb{R}^n \rightarrow \mathbb{R}^m$ be a linear transformation w/ standard matrix A .

(1) T is one-to-one $\Leftrightarrow A\vec{x} = \vec{0}$ has only trivial sol.
 $\Leftrightarrow \text{Nul}(A) = \{ \vec{0} \}$

(2) T is onto $\Leftrightarrow \text{range } T = \text{Col}(A) = \mathbb{R}^m$
 \Leftrightarrow columns of A span \mathbb{R}^m

Linearly independent sets

In lecture 7 (go review!) we introduced linear independence in \mathbb{R}^n . Extend to any vector space.

Defⁿ An indexed set of vectors $\{\vec{v}_1, \dots, \vec{v}_p\}$ in V is linearly independent if the vector equation

$$c_1 \vec{v}_1 + c_2 \vec{v}_2 + \dots + c_p \vec{v}_p = \vec{0}$$

has only the trivial solⁿ $c_1 = c_2 = \dots = c_p = 0$

If there is a nontrivial solⁿ, say there is a linear dependence relation among $\vec{v}_1, \dots, \vec{v}_p$.

Ex (1) Same defⁿ as in \mathbb{R}^n

So standard basis vectors $\vec{e}_1, \dots, \vec{e}_n$ linearly independent

$$\vec{0} = c_1 \vec{e}_1 + \dots + c_n \vec{e}_n = \begin{bmatrix} c_1 \\ \vdots \\ c_n \end{bmatrix} \Leftrightarrow c_i = 0$$

Ex (2) Let $\mathbb{P}_2 = \{a_0 + a_1t + a_2t^2 \mid a_i \in \mathbb{R}\}$

Show $p_1(t) = -3 + 4t^2$ $p_2(t) = 5 - t + t^2$ $p_3(t) = 1 + t + 3t^2$

linearly independent.

Need to show the only solⁿ to

$$c_1 p_1(t) + c_2 p_2(t) + c_3 p_3(t) = 0 \Leftrightarrow c_1 = c_2 = c_3 = 0$$

$$c_1(-3 + 4t^2) + c_2(5 - t + t^2) + c_3(1 + t + 3t^2)$$

$$= (-3c_1 + 5c_2 + c_3) + (-c_2 + c_3)t + (4c_1 + c_2 + 3c_3)t^2$$

$$= 0 + 0t + 0t^2$$

SLE $\begin{bmatrix} -3 & 5 & 1 \\ 0 & -1 & 1 \\ 4 & 1 & 3 \end{bmatrix} \begin{bmatrix} c_1 \\ c_2 \\ c_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$ Fact $\begin{vmatrix} -3 & 5 & 1 \\ 0 & -1 & 1 \\ 4 & 1 & 3 \end{vmatrix} = 9 + 20 + 0$
 $= -(-4) - (-3)$
 $= 36$
 $\neq 0$

determinant of coefficient matrix $\neq 0$

\Rightarrow coefficient matrix is invertible

\Rightarrow SLE has only trivial solⁿ $c_1 = c_2 = c_3 = 0$

\Rightarrow our vectors $p_1(t), p_2(t), p_3(t)$ linearly independent.

Key ideas . $\text{Col}(A)$

- linear transformations & $\text{Nul}(A)/\text{Col}(A)$
- linear independence in any vector space